UAV-based crop parameter retrieval using radiative transfer models

Erekle Chakhvashvili

Supervisors: Juliane Bendig, Bastian Siegmann, Onno Muller, Uwe Rascher

The aim of the project is to explore the capabilities of a UAV-based crop parameter retrieval using multispectral cameras and radiative transfer models (RTMs). Proximal UAV imagery creates opportunities to map these parameters at a high spatial resolution. Meanwhile, RTMs offer transferable and repeatable solution to the retrieval problem.