

Dynamics of Dispersion Colloids

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Overview

- 1. Introduction & motivation**
- 2. Salient static properties**
- 3. Dynamic light scattering**
- 4. Theoretical description of colloid dynamics**
- 5. Hydrodynamic mobility problem of many spheres**
- 6. Basic properties of Smoluchowski dynamics**
- 7. Short-time dynamics**
- 8. Long-time dynamics**
- 9. Concluding remarks**

1. Introduction & Motivation

- Examples of colloidal dispersions
- Modell dispersions and direct particle forces
- Hydrodynamic interaction (HI)
- Dynamics on colloidal time scales

2. Salient static properties

- Pair distribution function
- Static light scattering and structure factor
- Methods of calculation

3. Dynamic light scattering

- Basic scattering theory
- Dynamic correlation functions

4. Theoretical description of colloid dynamics

- Single-particle dynamics in very dilute dispersions
- Colloidal time and length scales
- Generalized Smoluchowski diffusion equation for dense systems

5. Hydrodynamic mobility problem of many spheres

- General properties of hydrodynamic interaction
- Method of induced forces
- Motion along a liquid-gas interface

6. Basic properties of Smoluchowski dynamics

- Fundamental solution and time correlation functions
- Backward operator and eigenfunction expansion
- Brownian dynamics simulations
- Projection operators and memory equations

7. Short-time dynamics

- Methods of calculation
- Hydrodynamic function
- Sedimentation
- Smoluchowski equation with incident fluid flow
- Collective and gradient diffusion
- Rotational self-diffusion

8. Long-time dynamics

- Generalized hydrodynamics
- Mode coupling approximation of memory functions
- Application: non-exponential decay of dynamic structure factor

9. Concluding remarks

General literature

1. W.B. Russel, D.A. Saville, and W.R. Schowalter, *Colloidal Dispersions* (Cambridge University Press, 1989)
2. J.K.G. Dhont, *An Introduction to Dynamics of Colloids* (Elsevier, Amsterdam, 1996)
3. R. Pecora, *Dynamic Light Scattering*, (Plenum Press, New York, 1985)
4. G. Nägele, *The Physics of Colloid Soft Matter: Lecture Notes 14* (Polish Academy of Sciences Publishing, Warsaw, 2004)
5. G. Nägele, *On The Dynamics and Structure of Charge-Stabilized Colloidal Suspensions* (Physics Reports 272, pp. 215-372, 1996)
6. R.M. Mazo, *Brownian Motion: Fluctuations, Dynamics and Applications* (Clarendon Press, Oxford, 2002)
7. R. Zwanzig, *Non-Equilibrium Statistical Mechanics* (Oxford University Press, 2001)

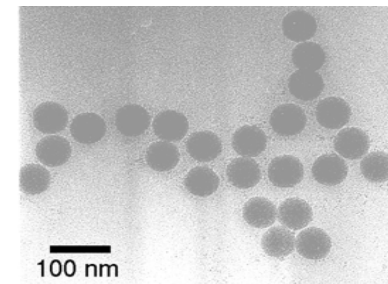
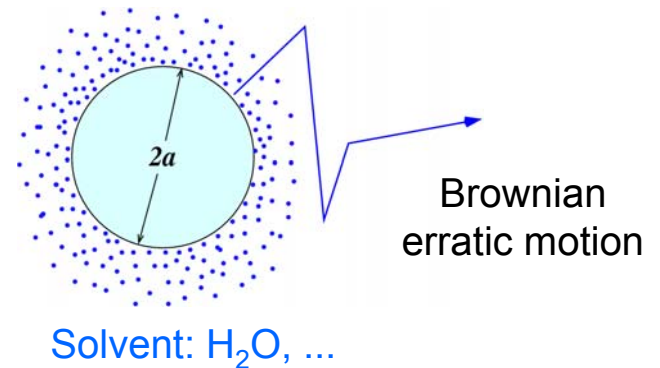
1. Introduction & motivation

- **Examples of colloidal dispersions**
- **Modell dispersions and direct particle forces**
- **Hydrodynamic interaction (HI)**
- **Dynamics on colloidal times scales**

Examples of colloidal dispersions

Definition: $1 \text{ nm} < \varnothing < 10 \text{ }\mu\text{m}$

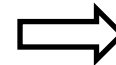
Examples: micellar systems
microemulsions
proteins
viruses
inorganic particles
(goldsol, Silica, ...)



Industrial products: dispersion paints
pharmaceuticals
food stuff
cosmetics
waste water

Theoretical task:

- Particle properties/interactions

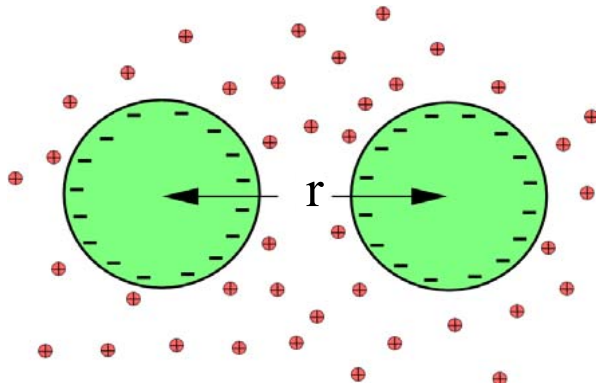


- Transport properties:

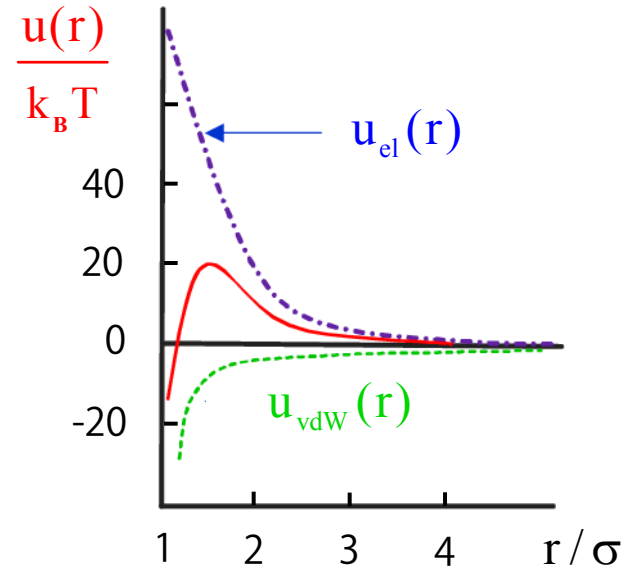
- diffusion coefficients
- viscosities
- conductivities

Model dispersions in 3D

Charge-stabilized dispersions :

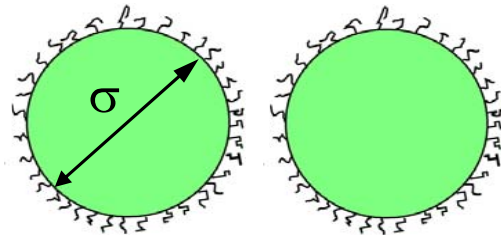


$$u_{\text{el}}(r) \propto Q^2 \exp\{-\kappa r\}/r, \quad r > \sigma$$

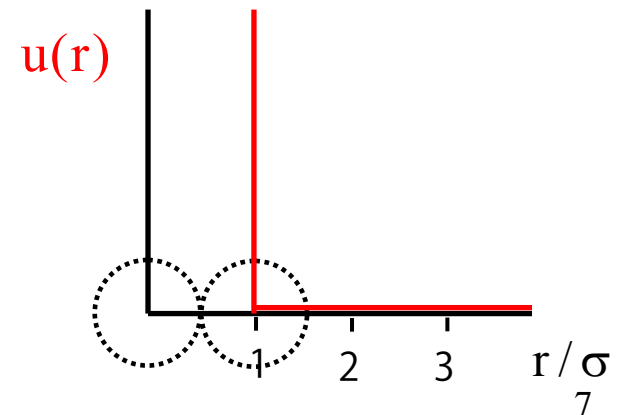


$$u(r) \approx u_{\text{el}}(r) \text{ für } Q/e \gg 1$$

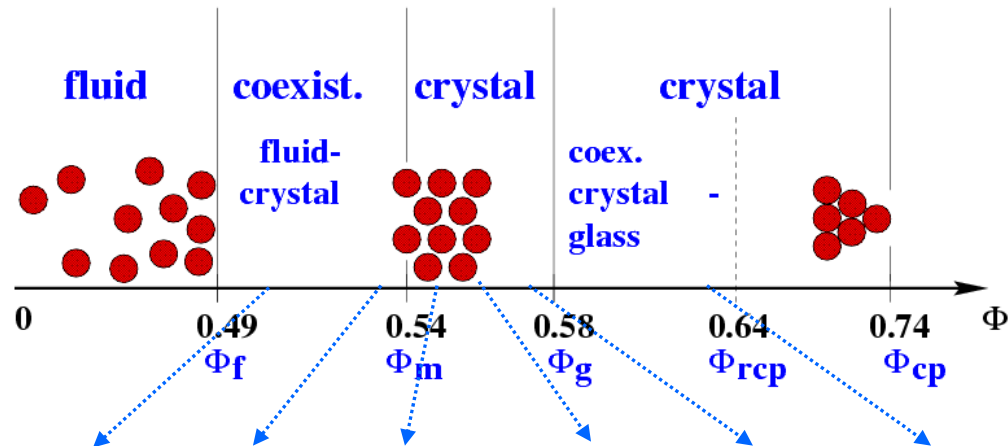
Sterically stabilized dispersions :



- Range and strength of $u(r)$ is tunable



Phase behavior of colloidal hard-sphere dispersion

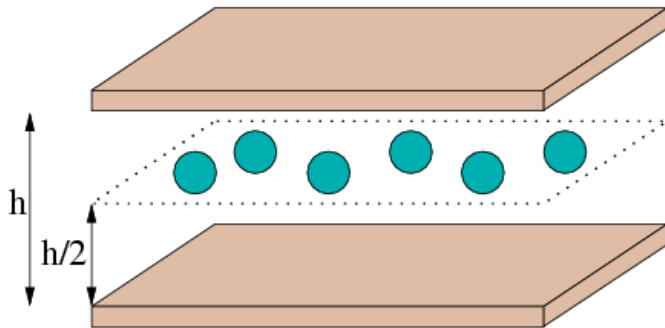


Pusey & van Megen
Nature 320, 1986

- Present lectures restricted on colloidal systems in fluid one-phase region

Quasi-two-dimensional model dispersions

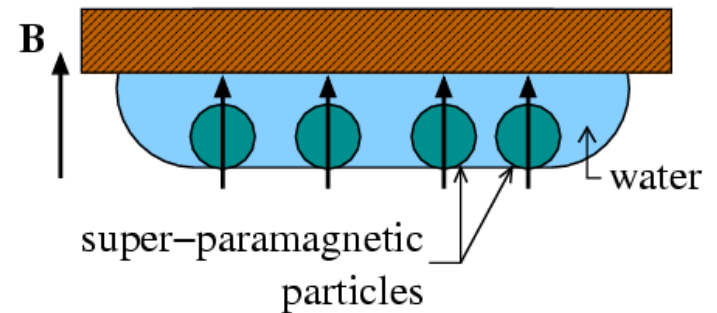
Colloidal spheres between two walls



$$u(r) = \begin{cases} \infty, & r < \sigma \\ Q^2 \frac{e^{-\kappa r}}{\epsilon r}, & r > \sigma \end{cases} \quad \left(\kappa = \frac{\pi}{h\sqrt{2}} \right)$$

- Yukawa-type model potential
(Chang & Hone, EPL 5, '88)

Magnetic spheres at water-air interface

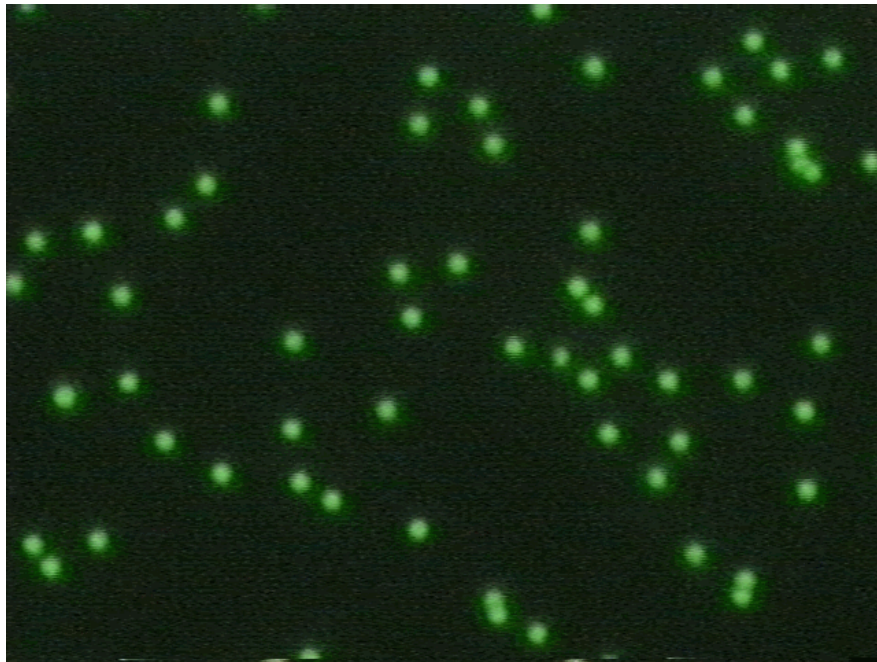


$$u(r) = \frac{\mu_0 \chi_{\text{eff}}^2}{4\pi} \frac{B^2}{r^3}$$

- Well-characterized dipolar potential
(Zahn & Maret, PRL 85, '00)

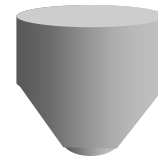
Experimental realization: Brownian forces

Courtesy: J.L. Arauz-Lara, Univ. of San Luis Potosi

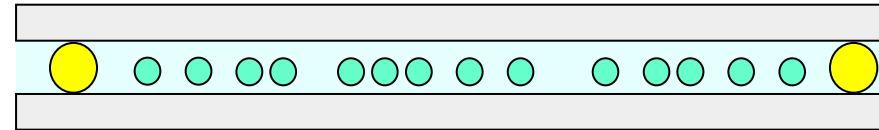


← 100 μm →

Video microscopy



Glass walls



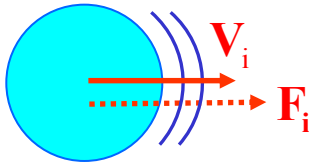
- Polystyrene spheres ($\sigma = 1\mu\text{m}$)
- Spacer spheres ($h > \sigma$)

Colloidal particle dynamics determined by interplay of:

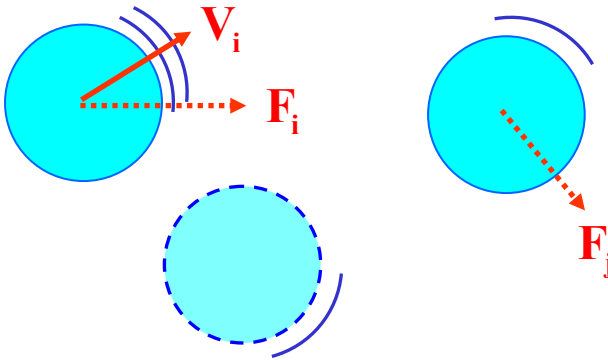
- 1. Direct particle interactions (DI)**
- 2. Brownian erratic forces due to solvent molecules' bombardement**
- 3. Hydrodynamic interactions through solvent (HI)**

Hydrodynamic interaction (HI)

- Long-range dynamic many-body force $\sim r^{-1}$
- Quasi-instantaneous & inertia-free on colloidal time scales
- Small-Reynolds-number creeping solvent flow



$$\mathbf{v}_i = \frac{D_0}{k_B T} \mathbf{F}_i \quad D_0 = \frac{k_B T}{6\pi\eta_0 a}$$

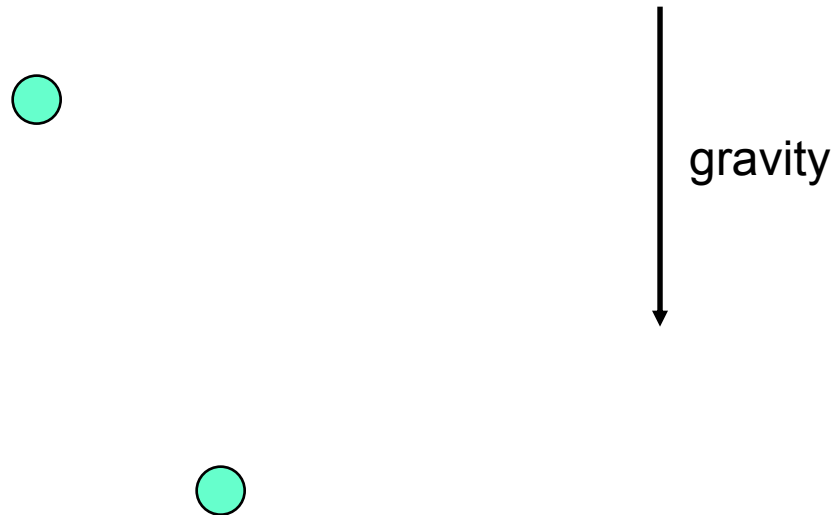


$$\mathbf{v}_i = \frac{1}{k_B T} \sum_{j=1}^N \mathbf{D}_{ij}(\mathbf{r}^N) \cdot \mathbf{F}_j$$

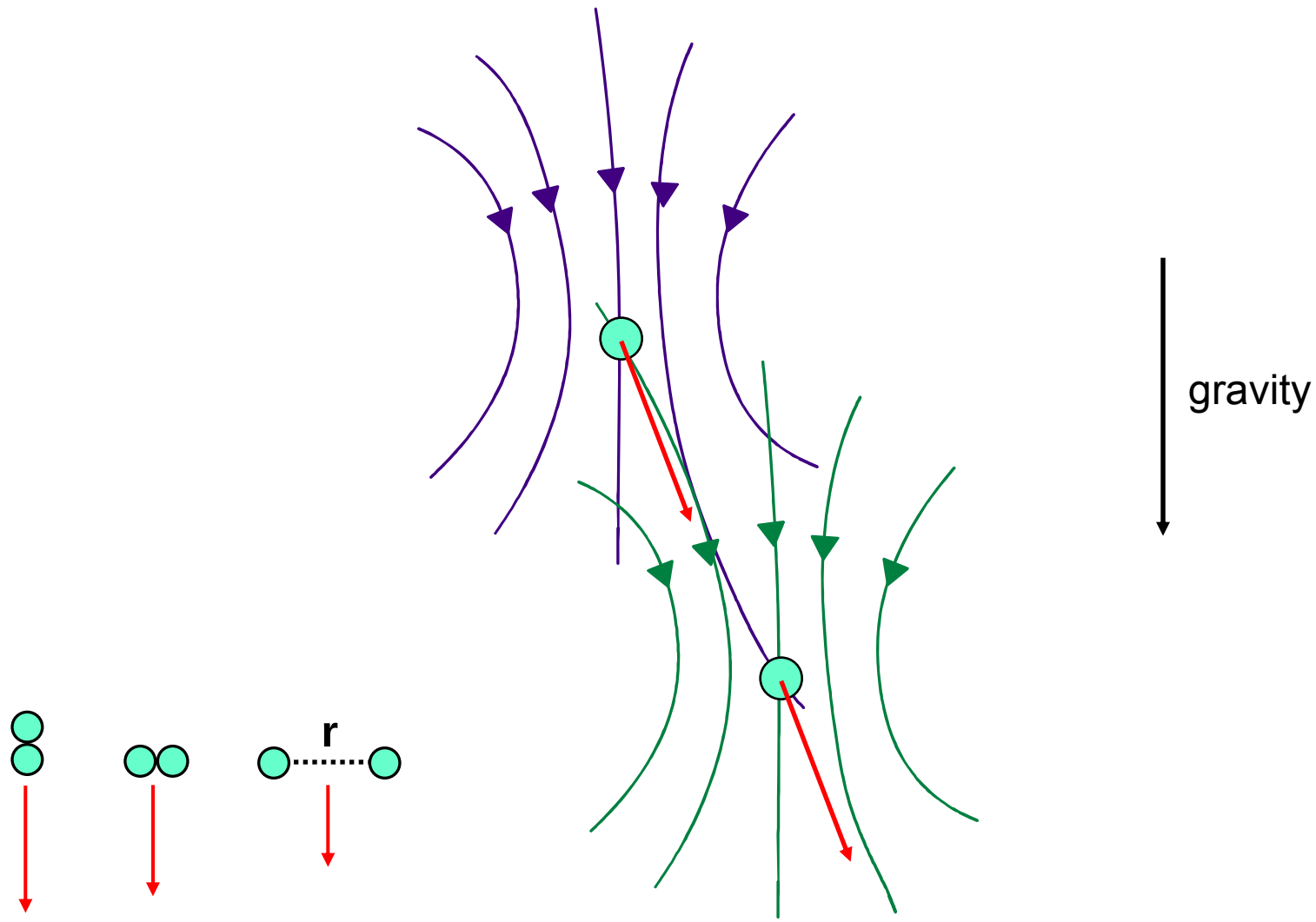
hydrodynamic mobility tensor (non-linear in $\mathbf{r}^N$)

(generalized Stokes' friction law)

HI: Non-Brownian sedimentation of two small spheres

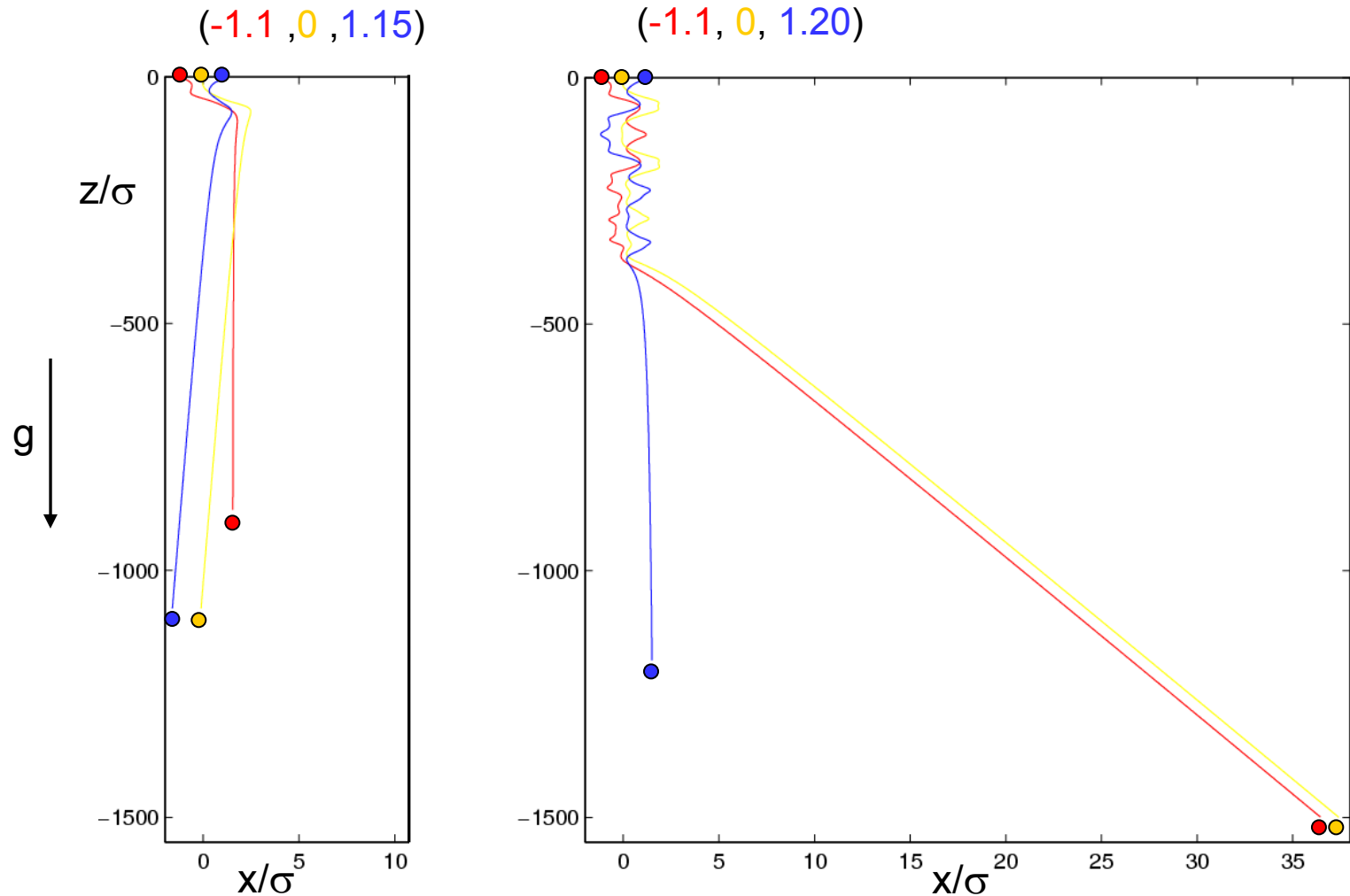


HI: Non-Brownian sedimentation of two small spheres



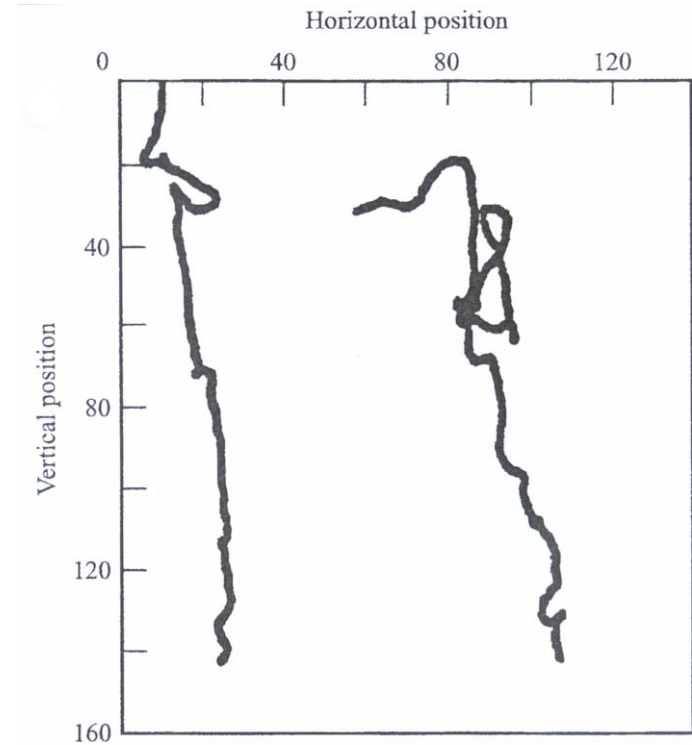
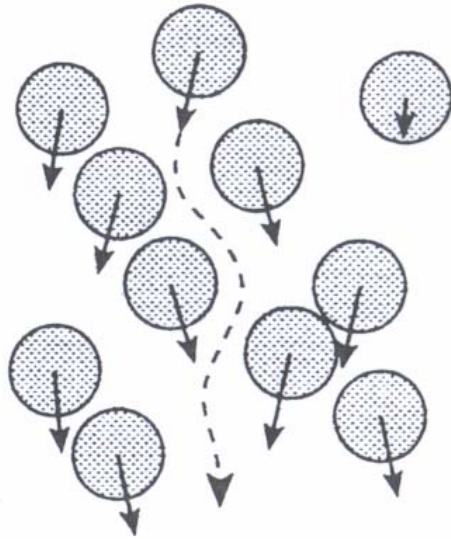
– fixed distance vector $\mathbf{r}$

Asymmetric initial configuration of three spheres at $z = 0$



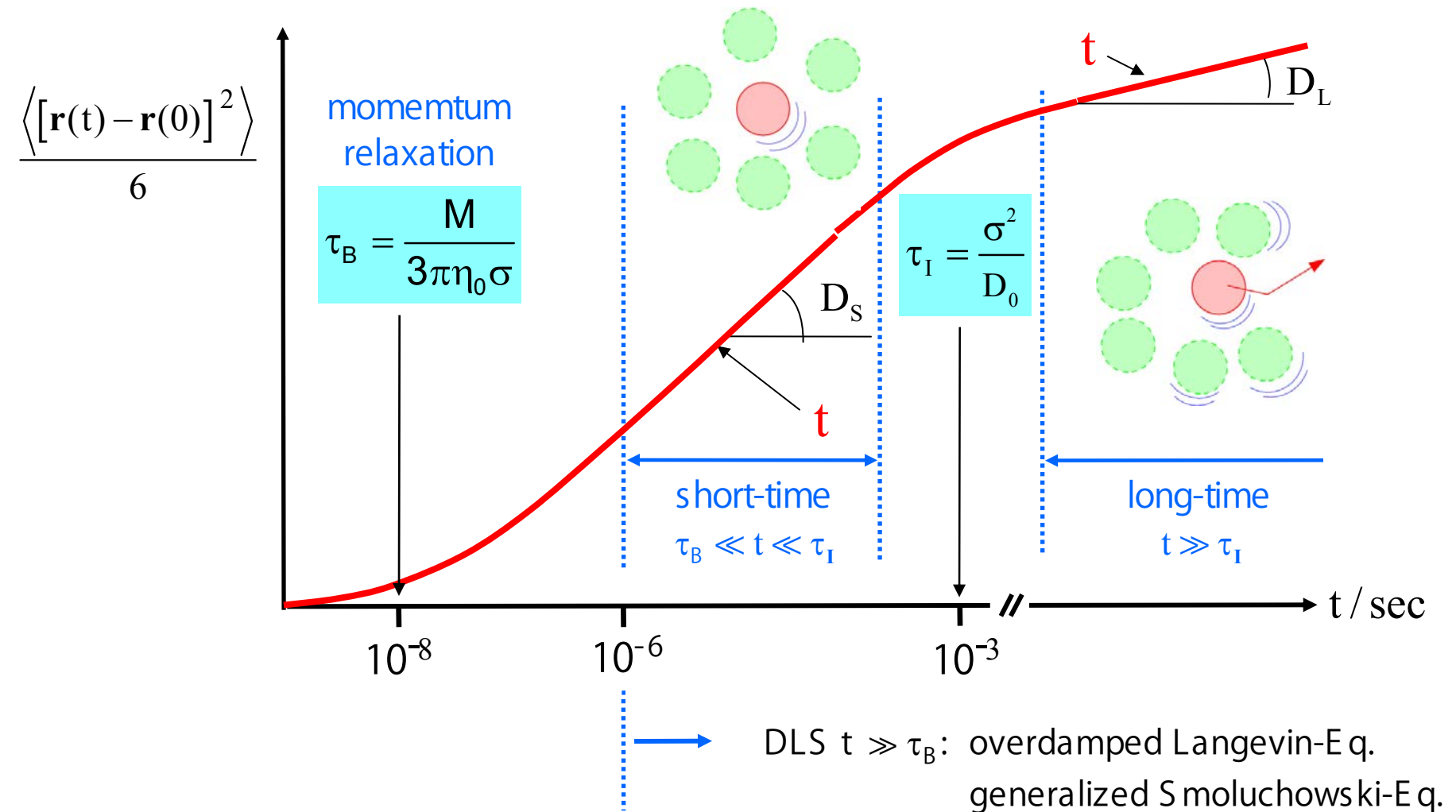
- Sensitive dependence on initial configuration for $N > 2 \rightarrow$ chaotic trajectories

HI: Non-Brownian sedimentation of many spheres



- meandering trajectories & fluctuating velocities
- hydrodynamic „diffusion“ due to HI
- existence & form of final stationary particle distribution $P_{\text{stat}}(\mathbf{r}^N)$ still under debate
- slowly sedimenting colloidal particles → Brownian trajectories, $P_{\text{stat}}(\mathbf{r}^N)$ existent

Dynamics on colloidal time scales



Dynamics on colloidal time scales

- quasi-inertia free motion on coarse-grained colloidal time- and length scales

$$\Delta t \gg \tau_B \approx 10^{-8} \text{ sec}$$

$$\Delta x \gg l_B = \sqrt{D_0 \tau_B} \approx 10^{-4} \sigma$$

“stopping distance”



Rhodospirillum bacteria (length $\sigma \approx 5 \mu\text{m}$)

Dynamics on colloidal time scales

Overdamped Langevin-Eq.

$$M\dot{\mathbf{V}}_i(t) = 0 = \mathbf{F}_i^{\text{DI}} + \mathbf{F}_i^{\text{H}} + \mathbf{K}_i^{\text{R}}$$

Random force
(solvent collisions)



Dynamic simulations

Generalized Smoluchowski Eq.

$$\frac{\partial}{\partial t} P(\mathbf{r}^N, t) + \sum_{i=1}^N \nabla_i \cdot [\mathbf{v}_i(\mathbf{r}^N) P(\mathbf{r}^N, t)] = 0$$

PDF

coarse-grained velocity from
force balance



Theoretical calculations

- pure configuration-space description for $t \gg \tau_B$

2. Salient static properties

- **Pair distribution function**
- **Static light scattering and structure factor**
- **Methods of calculation**

Pair distribution function

Canonical NVT-ensemble: $N \gg 1$ spherical particles in volume V at temperature T

$$\rho_N^{(n)}(\mathbf{r}_1, \dots, \mathbf{r}_n) = \underbrace{N(N-1)\dots(N-n+1)}_{\text{n out of N}} = \int d\mathbf{r}_{n+1} \dots d\mathbf{r}_N \underbrace{\frac{e^{-\beta U(\mathbf{r}^N)}}{Z_N}}_{\text{probability d.f. of } \mathbf{r}^N}$$

joint d.f. for $n \ll N$
particles at $\{\mathbf{r}_1, \dots, \mathbf{r}_n\} = \mathbf{r}^n$

$$Z_N(V, T) = \int d\mathbf{r}_1 \dots d\mathbf{r}_N e^{-\beta U} = \int d\mathbf{r}^N e^{-\beta U}$$

$$U(\mathbf{r}^N) = \sum_{i < j}^N u(|\mathbf{r}_i - \mathbf{r}_j|) = \sum_{i < j}^N u(r_{ij})$$

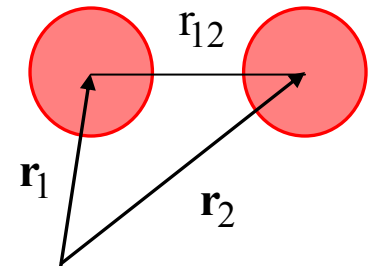
assume pair-wise additivity

Define pair distribution function as: $g_N(\mathbf{r}_1, \mathbf{r}_2) = \frac{\rho_N^{(2)}(\mathbf{r}_1, \mathbf{r}_2)}{\rho_N^{(1)}(\mathbf{r}_1)\rho_N^{(1)}(\mathbf{r}_2)} \rightarrow 1$ for $r = r_{12} \rightarrow \infty$

Isotropic fluid state (no crystal or external field) :

$$\rho_N^{(1)}(\mathbf{r}) = \frac{N}{V} = \rho : \text{average number density}$$

$$g_N(\mathbf{r}_1, \mathbf{r}_2) = g_N(|\mathbf{r}_1 - \mathbf{r}_2|) = g_N(r) : \text{NVT radial distribution function}$$



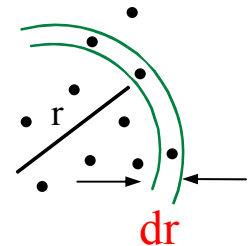
$$g_N(r) = \frac{\rho_N^{(2)}(r)}{\rho^2} = \frac{N(N-1)}{\rho^2} \int d\mathbf{r}_3 \dots d\mathbf{r}_N \frac{e^{-\beta U(\mathbf{r}^N)}}{Z_N}$$

$$g_N^{\text{id}}(r) = 1 - \frac{1}{N}$$

ideal gas :
 $U = 0$ and $Z_N = V^N$

- g_N measures pair correlations relative to ideal gas

$$\rho \int d\mathbf{r} g_N(r) = \frac{N(N-1)}{\rho} \underbrace{\int d\mathbf{r}_{12}}_{\frac{1}{V} \int d\mathbf{r}_1 d\mathbf{r}_2} \int d\mathbf{r}_3 \dots d\mathbf{r}_N e^{-\beta U(\mathbf{r}^N)} / Z_N = N-1$$



- $4\pi r^2 \rho g_N$ is average particle number in shell $[r, r+dr]$ (i.e. $g(r)$ is conditional pdf)

Thermodynamic limit for macroscopic system :

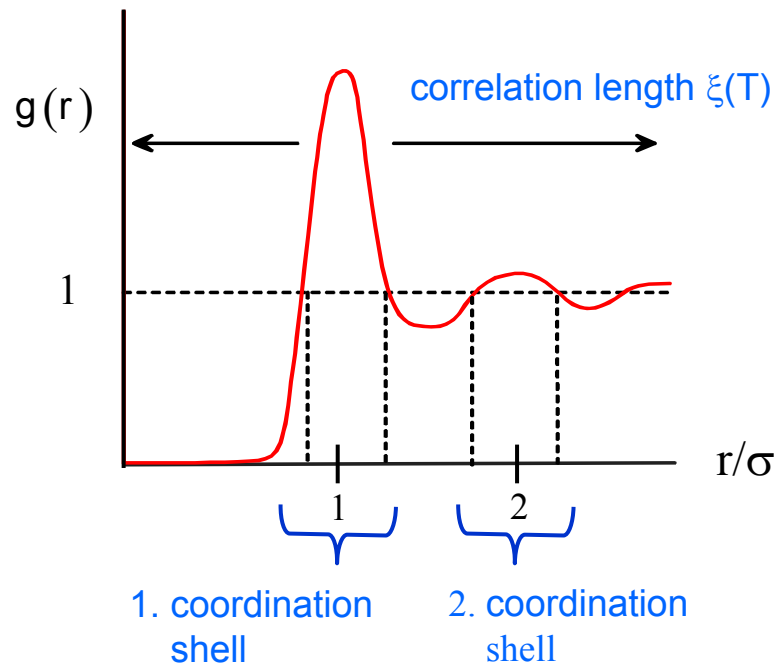
$$g(r) = \lim_{N, V \rightarrow \infty} g_N(r)$$

$\rho = N/V$ fixed

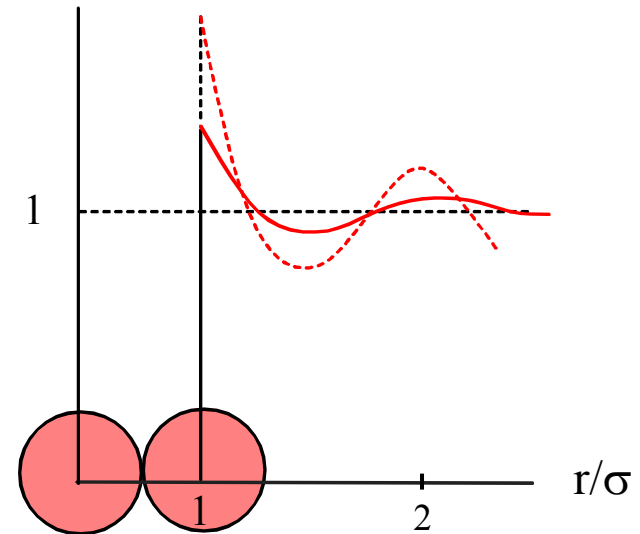
General behavior of $g(r)$:

- $g(r) \geq 0$, $g(r \rightarrow \infty) = 1$
- $g(r) \cong 0$, when $\beta u(r) \gg 1$
- $g(r) = \exp[-\beta u(r)]$ for $\rho \rightarrow 0$
- $g(r)$ continuous where $u(r)$ continuous

- Sketch of $g(r)$ for soft pair potential



- Sketch of $g(r)$ for hard-sphere dispersion

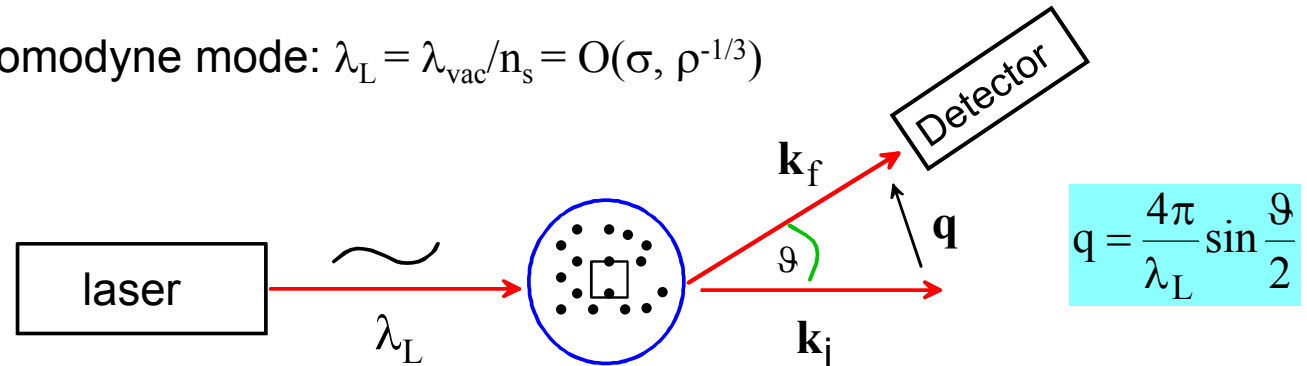


- jump at $r = \sigma$
- $g(r < \sigma) = 0$ since $u(r < \sigma) = \infty$
- $g(r) = \exp[-\beta u(r)] = \theta(r - \sigma)$ for $\rho = 0$

- Undulations in $g(r)$ more pronounced for higher density and lower temperature

Static light scattering and structure factor

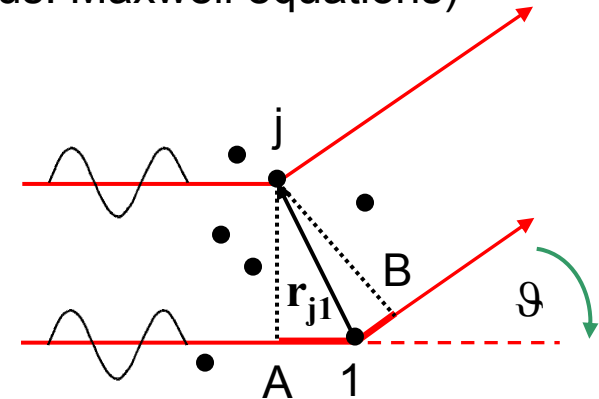
- Scattering in homodyne mode: $\lambda_L = \lambda_{\text{vac}}/n_s = O(\sigma, \rho^{-1/3})$



- Assumptions in basic scattering theory (more rigorous: Maxwell equations)

- point scatterers (Rayleigh) : $\sigma \ll \lambda_L$
- single scattering (1. Born approximation)
- no absorption

Quasi-elastic : $k_f \approx k_i = 2\pi/\lambda_L$ ($\frac{h\nu}{c^2} = m_{\text{ph}} \ll M$)



Phase difference between j and 1 : $\bar{\mathbf{B}}1 + \bar{\mathbf{A}}1 = \mathbf{k}_f \cdot \mathbf{r}_{j1} - \mathbf{k}_i \cdot \mathbf{r}_{j1} = \mathbf{q} \cdot \mathbf{r}_{j1}$

Scattered el. field amplitude at detector : $E_s(\mathbf{q}) \propto \frac{1}{\lambda_L^2 R} \sum_{j=1}^N \exp\{i \mathbf{q} \cdot (\mathbf{r}_j - \mathbf{r}_1)\}$

blue sky

$R \gg$ scatt. volume size

Time-averaged measured intensity :
$$I(\mathbf{q}) = \left\langle E_s E_s^* \right\rangle_T \propto \left\langle \sum_{l,j=1}^N \exp \left\{ i \mathbf{q} \cdot (\mathbf{r}_l - \mathbf{r}_j) \right\} \right\rangle_T$$

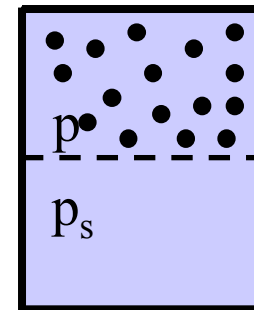
Ergodic system (fluid state) :
$$\lim_{T \rightarrow \infty} \langle \dots \rangle_T = \langle \dots \rangle_{N \gg 1}$$

$$\begin{aligned} I(\mathbf{q}) &\propto N + \left\langle \sum_{l \neq j}^N e^{i \mathbf{q} \cdot \mathbf{r}_{lj}} \right\rangle = N + N(N-1) \langle e^{i \mathbf{q} \cdot \mathbf{r}_{12}} \rangle = N + N(N-1) V \int d\mathbf{r}_{12} e^{i \mathbf{q} \cdot \mathbf{r}_{12}} \underbrace{\int d\mathbf{r}^{(N-2)} e^{-\beta U(\mathbf{r}^N)} / Z_N}_{\frac{1}{V^2} g_N(\mathbf{r}_{12})} \\ &= N \left\{ 1 + \rho \int d\mathbf{r} e^{i \mathbf{q} \cdot \mathbf{r}} [g_N(\mathbf{r}) - 1] \right\} + \underbrace{N \rho (2\pi)^3 \delta(\mathbf{q})}_{\substack{\text{forward contribution} \\ \text{(no correlation information)}}} \end{aligned}$$

Static structure factor in T-limit :
$$S(\mathbf{q}) = 1 + \rho \int d\mathbf{r} e^{i \mathbf{q} \cdot \mathbf{r}} [g(\mathbf{r}) - 1] = \lim_{\infty} \left\langle \frac{1}{N} \delta \rho(\mathbf{q}) \delta \rho(-\mathbf{q}) \right\rangle \geq 0$$

 ($N \rightarrow \infty, V \rightarrow \infty, \rho = N/V$ fixed)

$$\delta \rho(\mathbf{q}) = \int d\mathbf{r} e^{i \mathbf{q} \cdot \mathbf{r}} \left\{ \sum_{l=1}^N \delta(\mathbf{r} - \mathbf{r}_l) - \rho \right\} = \sum_{l=1}^N e^{i \mathbf{q} \cdot \mathbf{r}_l} - (2\pi)^3 \rho \delta(\mathbf{q})$$



Compressibility equation :

$$\lim_{q \rightarrow 0} S(\mathbf{q}) = \frac{\chi_T}{\chi_T^{\text{id}}} = k_B T \left(\frac{\partial \rho}{\partial p} \right)_T$$

Remarks about ordering of T - limit and $q \rightarrow 0$ limit

Periodic replication of system (scattering) volume $V = L^3$:

$$V\delta_{\mathbf{q},0} = \int_V d\mathbf{r} e^{i\mathbf{q}\cdot\mathbf{r}} \rightarrow (2\pi)^3 \delta(\mathbf{q})$$

$$\frac{1}{V} \sum_{\mathbf{q}} F(\mathbf{q}) \rightarrow \frac{1}{(2\pi)^3} \int_{\mathbb{R}^3} d\mathbf{q} F(\mathbf{q})$$

regular at $q = 0$

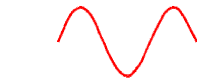
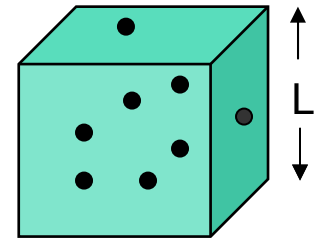
Applications :

$$\frac{(2\pi)^6}{V^2} \delta(\mathbf{q})^2 \rightarrow \delta_{\mathbf{q},0}^2 = \delta_{\mathbf{q},0} \rightarrow \frac{(2\pi)^3}{V} \delta(\mathbf{q})$$

$$S_N(\mathbf{q}) = \frac{1}{N} \left\langle |\delta\rho(\mathbf{q})|^2 \right\rangle_N \quad \delta\rho(\mathbf{q}) = \sum_{l=1}^N e^{i\mathbf{q}\cdot\mathbf{r}_l} - N\delta_{\mathbf{q},0}$$

$$\lim_{q \rightarrow 0} S(q) = \lim_{q \rightarrow 0} \lim_{N \rightarrow \infty} S_N(q) = \frac{\chi_T}{\chi_T^{\text{id}}} \neq \lim_{N \rightarrow \infty} \{S_N(q=0) = 0\} = 0$$

- First T-limit in NVT ensemble then $q \rightarrow 0$
- Several wavelengths $\lambda=2\pi/q$ should fit into V

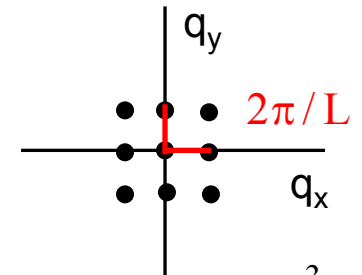


$$f(\mathbf{r} + \mathbf{n}L) = f(\mathbf{r})$$

vector with

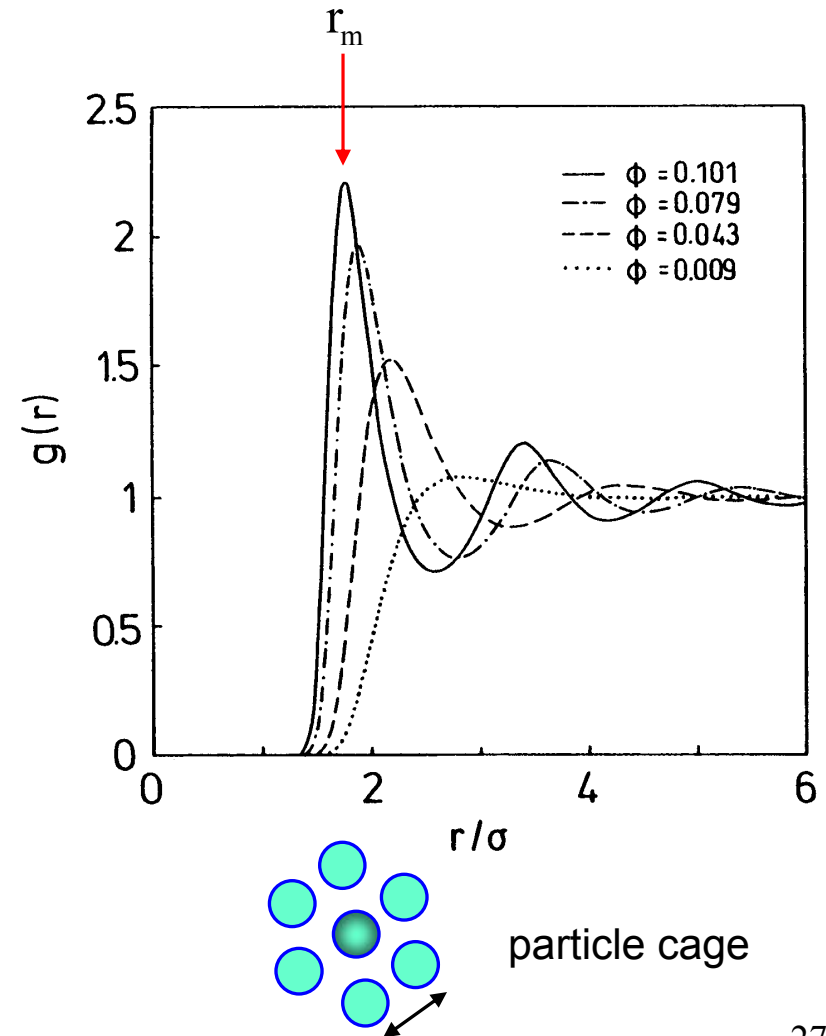
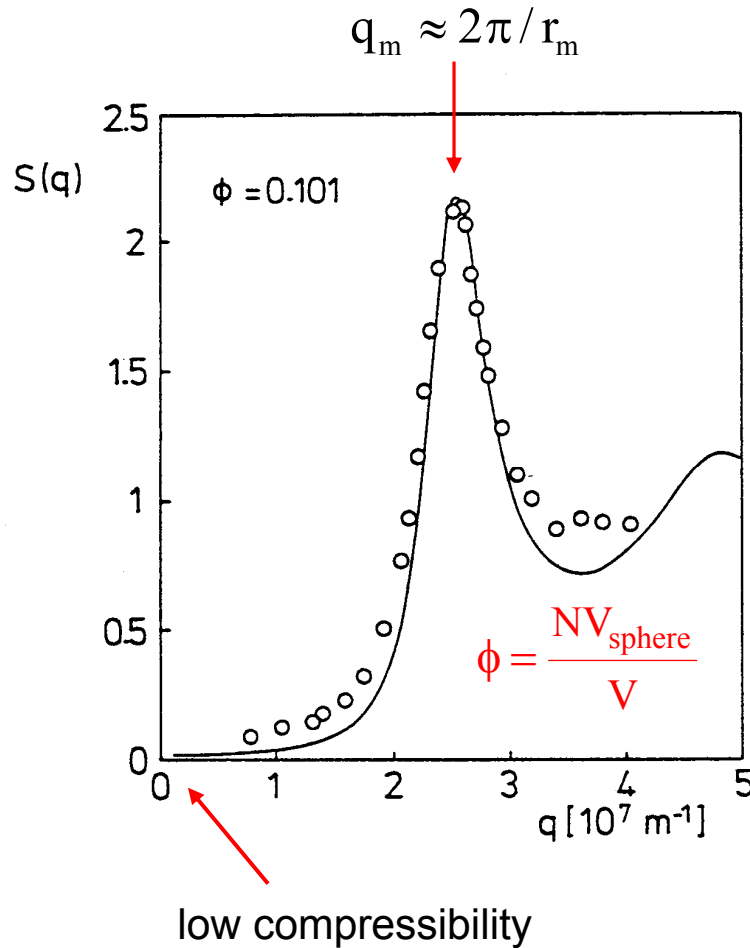
components $0, \pm 1, \pm 2, \dots$

$$f(\mathbf{r}) = e^{i\mathbf{q}\cdot\mathbf{r}} \Rightarrow \mathbf{q} = \frac{2\pi}{L} \mathbf{n}$$



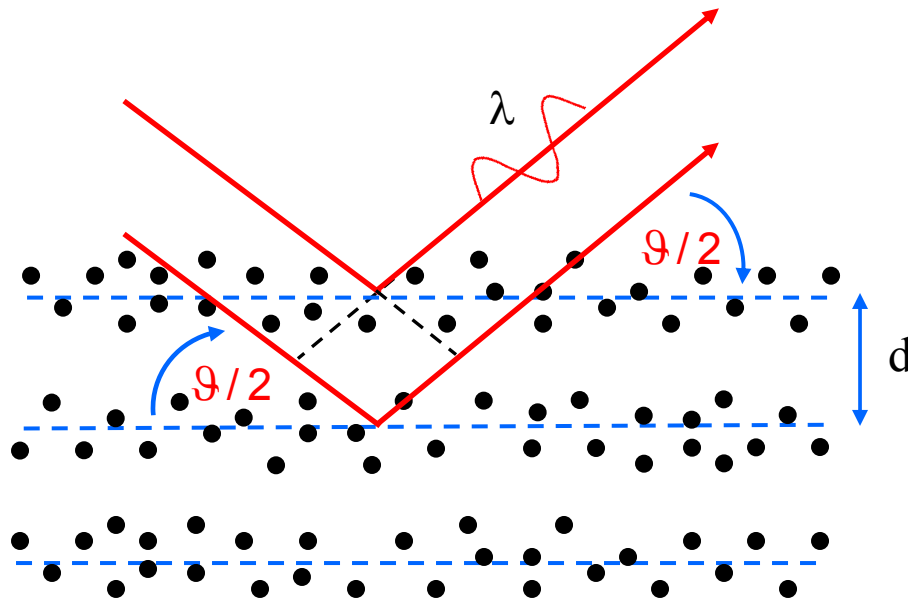
$$\text{density of } \mathbf{q} \text{ points} = \frac{(2\pi)^3}{V}$$

S(q) and g(r) for a charge-stabilized dispersion



(G. Nägele, Phys. Reports 272 (1996))

Interpretation: diffusive Bragg scattering from particle density waves



1. order constructive interference

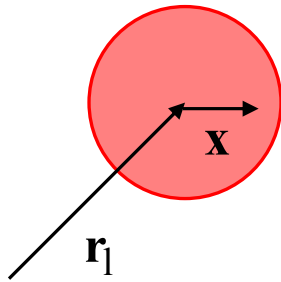
$$\frac{\lambda}{n_s} = 2d \sin \frac{\theta}{2}$$

$$q = \frac{4\pi n_s}{\lambda} \sin \frac{\theta}{2}$$

$$d \approx \frac{2\pi}{q}$$

typical spatial resolution for selected q

Point scatterers $\rightarrow$ weakly scattering colloidal spheres with $a = O(\lambda)$



$$E_s(\mathbf{q}) \propto \sum_{l=1}^N \int_{x < a} d\mathbf{x} e^{i\mathbf{q} \cdot [\mathbf{r}_l + \mathbf{x}]} \psi(\mathbf{x})$$

$$\propto \left(\int_{x < a} d\mathbf{x} e^{i\mathbf{q} \cdot \mathbf{x}} \psi(\mathbf{x}) \right) \sum_{l=1}^N e^{i\mathbf{q} \cdot \mathbf{r}_l}$$

$$\psi(\mathbf{x}) = \varepsilon_p(\mathbf{x}) - \varepsilon_s$$

local
scattering strength

$$I(\mathbf{q}) \propto \langle N \rangle \mathbf{P}(\mathbf{q}) S(\mathbf{q})$$

Single-particle form factor

Inherent assumptions :

- $\rightarrow$ isotropic spheres
- $\rightarrow$ Rayleigh-Gans-Debye (RGD) regime :
no phase difference of light through particle
and solvent, respectively, i.e

$$2\pi |n_p - n_s| a / \lambda < 0.1$$

$$\mathbf{P}(\mathbf{q}) = \left| \frac{\int_0^a d\mathbf{x} e^{i\mathbf{q} \cdot \mathbf{x}} \psi(\mathbf{x})}{\int_0^a d\mathbf{x} \psi(\mathbf{x})} \right|^2$$

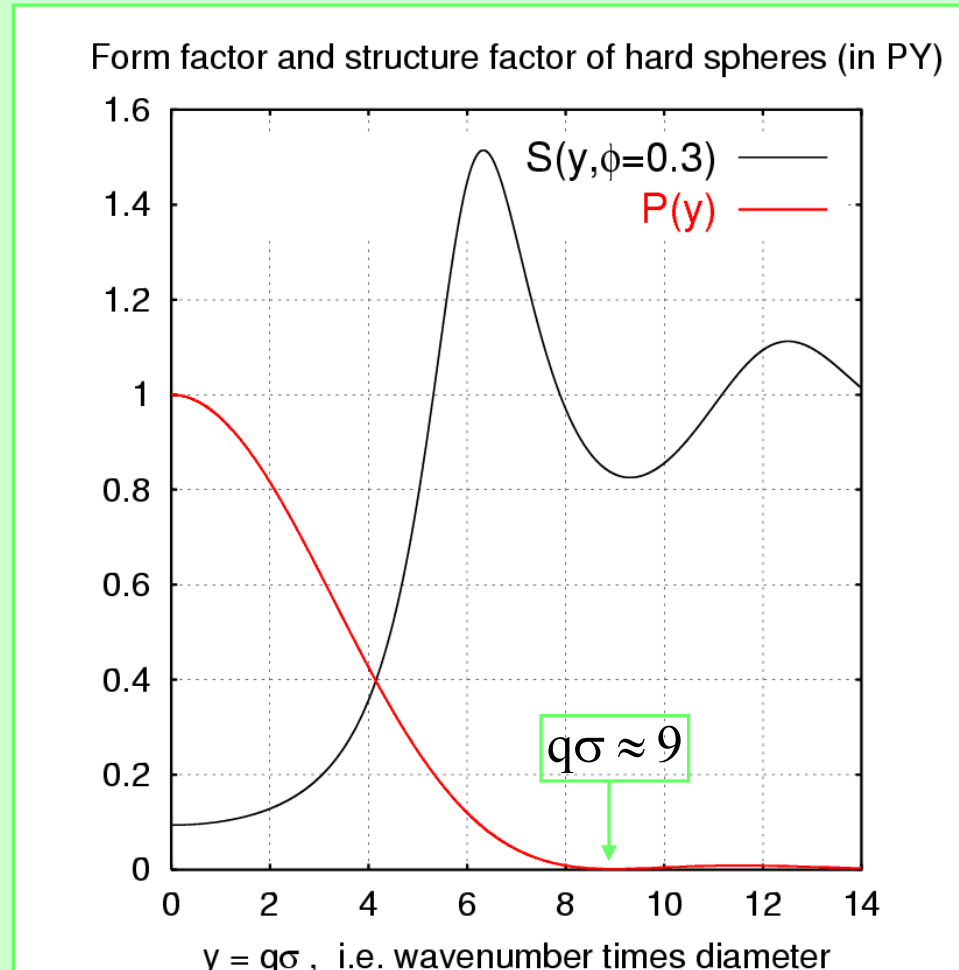
$$P(q = 0) = 1$$

$$P(q = \infty) = 0$$

Example: optically uniform colloidal spheres with $\Psi = \text{const}$

$$P(q) = \left(\frac{3j_1(qa)}{qa} \right)^2 = (b(q))^2$$

Formamplitude



- Large particles scatter more strongly in forward direction
- $q > 4.5/a$ not accessible by light scattering

Methods of calculation

- Computer simulations (Monte-Carlo, MD and BD)
- • Ornstein-Zernike-type integral equation schemes

Introduce total correlation function : $h(r_{12}) := g(r_{12}) - 1$ $h(r_{12}) \rightarrow 0$, for $r_{12} \rightarrow \infty$

Define direct correlation function $c(r)$ through Ornstein-Zernike equation :

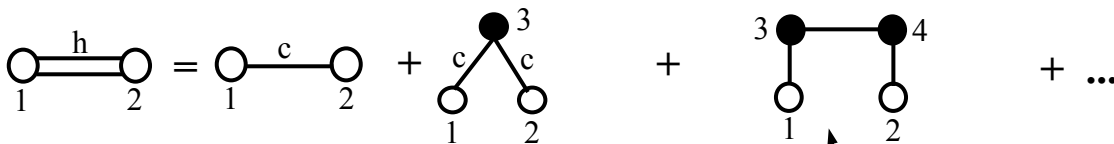
$$h(r_{12}) = c(r_{12}) + \rho \int d\mathbf{r}_3 c(r_{13}) h(r_{23})$$

total correlations
of 1 and 2

direct
correlations

indirect correlations of 1 and 2
through particles 3,4,...

$$h(r_{12}) = c(r_{12}) + \rho \int d\mathbf{r}_3 c(r_{13}) c(r_{23}) + \rho^2 \int d\mathbf{r}_3 d\mathbf{r}_4 c(r_{13}) c(r_{24}) c(r_{34}) + O(c^4)$$



$$\bullet = \rho \int d\mathbf{r}_i$$

indirect correlations of 1 and 2 through two
intermediate particles 3 and 4

General properties of $c(r)$: $c(r) = h(r) = e^{-\beta u(r)} - 1 + O(\rho)$

$$c(r) = -\beta u(r), \quad r \rightarrow \infty \quad \text{valid for all densities}$$

- $c(r)$ is more amenable to approximations than $g(r)$

- Fourier-transformed OZ equation from convolution theorem :

$$S(q) = 1 + \rho \int d\mathbf{r} e^{i\mathbf{q}\cdot\mathbf{r}} h(r) = 1 + \rho h(q) \quad h(q) = \int d\mathbf{r} e^{i\mathbf{q}\cdot\mathbf{r}} h(r) = \frac{4\pi}{q} \int_0^\infty dr r \sin(qr) h(r)$$

$$h(q) = c(q) + \rho c(q) h(q)$$

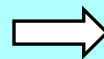
- Solving for Fourier-transformed $c(r)$ gives $S(q)$ in terms of $c(q)$:

$$S(q) = \frac{1}{1 - \rho c(q)} \geq 0$$

Ornstein-Zernike equation

+ approximate closure relation : $c(r) = \text{Functional of } h(r') \text{ \& } u(r')$

+ zero overlap condition (HC) : $g(r < \sigma) = 0$



Closed integral equation for $g(r) = h(r) - 1$

Examples of important closure relations

- Rescaled mean spherical approximation (RMSA) :

$$c(r) = -\beta u(r), \quad r > \sigma_{\text{eff}} > \sigma$$

$$g(r = \sigma_{\text{eff}}^+) = 0$$

- Hypernetted chain approximation (HNC)

$$c(r) = e^{-\beta u(r)} \cdot e^{\gamma(r)} - \gamma(r) - 1$$

$$\gamma(r) := h(r) - c(r)$$

- Percus-Yevick approximation (PY)

$$c(r) = e^{-\beta u(r)} \cdot [1 + \gamma(r)] - \gamma(r) - 1$$

- Rogers-Young mixing scheme (RY): thermodynamically partially self-consistent

$$c(r) = e^{-\beta u(r)} \cdot \left[1 + \frac{\exp\{\gamma(r) f(r)\} - 1}{f(r)} \right] - \gamma(r) - 1$$

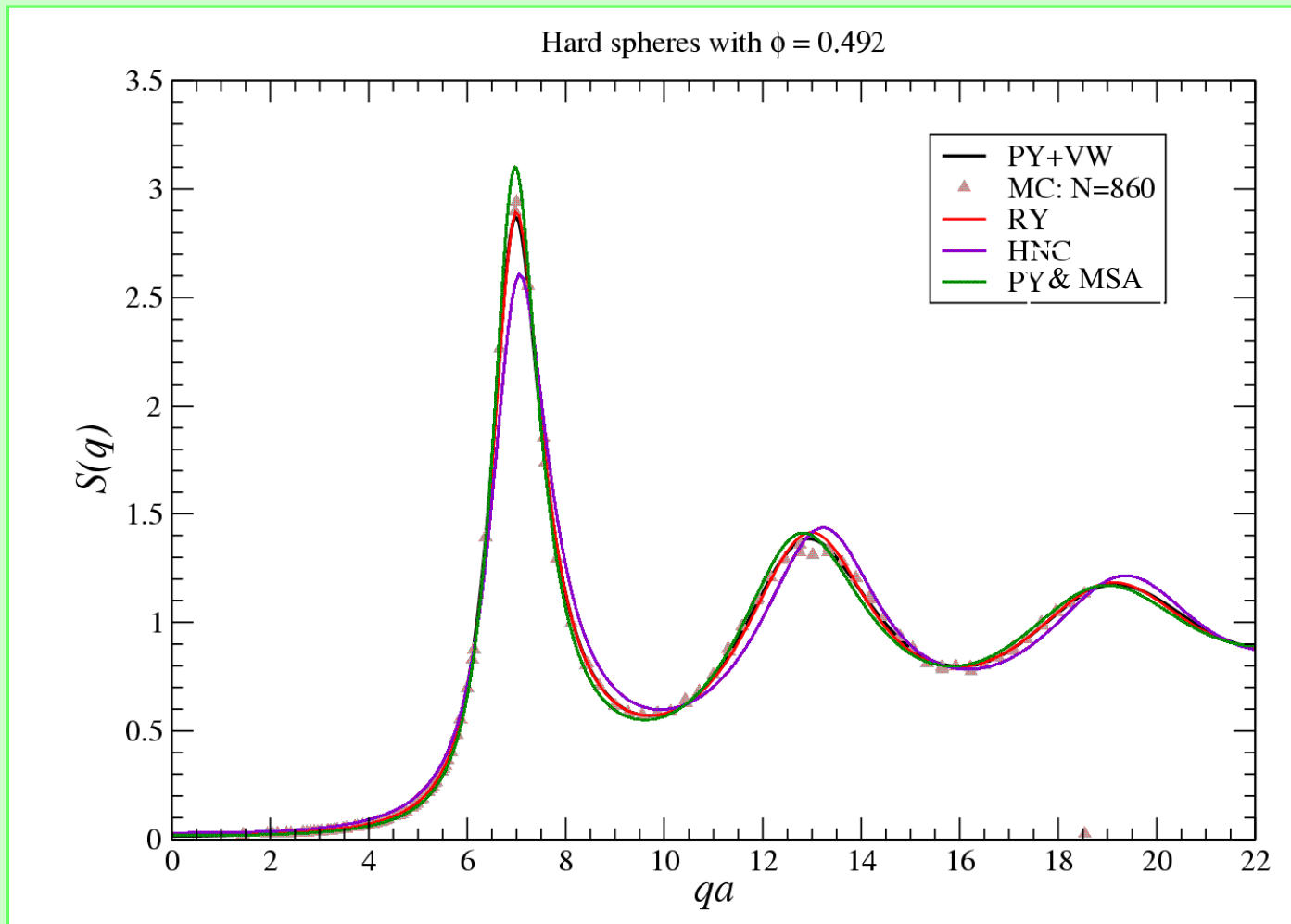
$$f(r) = 1 - e^{-\alpha r}$$

$$\alpha \rightarrow \infty : \text{HNC}$$

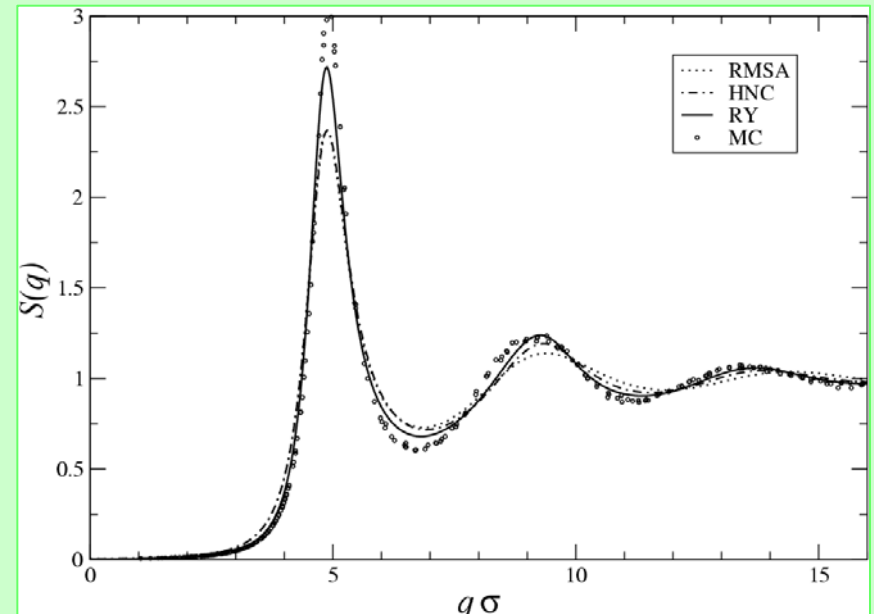
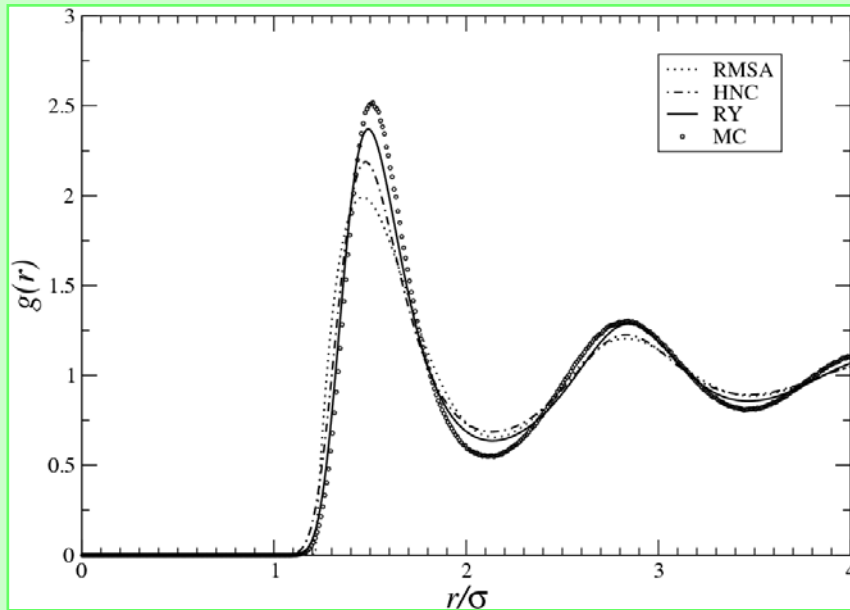
$$\alpha \rightarrow 0 : \text{PY}$$

$$\chi_T^{\text{Virial}} = \chi_T^{\text{Compr}}$$

determines α



Example: strongly coupled charge-stabilized colloidal spheres ($\phi = 0.185$)



Results by Banchio & Nägele :
see in Lecture Notes 14, Polish Academy of Science Publishing, Warsaw (2004)

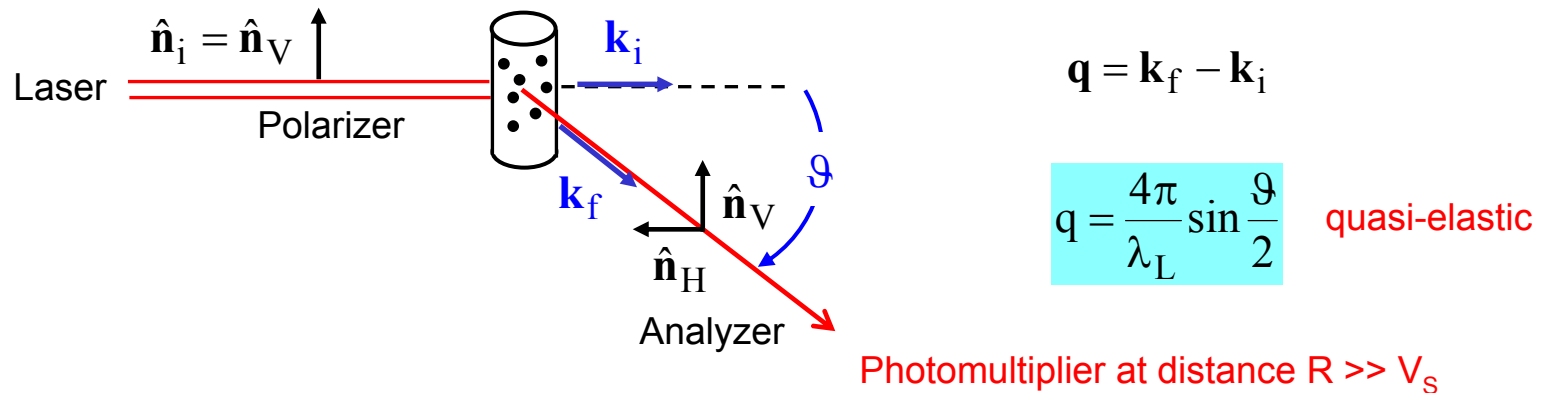
- For each $u(r)$, closures should be tested first against simulations

3. Dynamic light scattering

- **Basic scattering theory**
- **Dynamic correlation functions**

Basic scattering theory

- Homodyne scattering set-up :

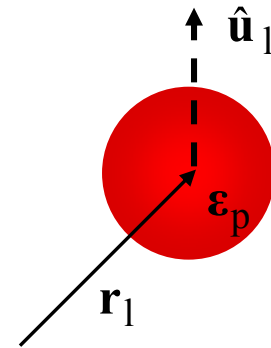


- Maxwell equations for non-magnetic and linear dielectric media
- Single scattering (1. Born approximation)
- RGD regime (superposition + s-waves)

- Scattered electric field strength at detector place :

$$\mathbf{E}_S(\mathbf{q}) \propto \frac{e^{i\mathbf{k}_i \cdot \mathbf{R}}}{\lambda^2 R} \mathbf{E}_0 \sum_{l=1}^N e^{i\mathbf{q} \cdot \mathbf{r}_l} \hat{\mathbf{n}}_f \cdot (\mathbf{1} - \hat{\mathbf{k}}_f \hat{\mathbf{k}}_f) \cdot \mathbf{B}_l(\mathbf{q}) \cdot \hat{\mathbf{n}}_i$$

far-field electric field $\perp$ propagation direction



$$\mathbf{B}_l(\mathbf{q}) = \frac{1}{\epsilon_s} \int_{x \leq a} d\mathbf{x} e^{i\mathbf{q} \cdot \mathbf{x}} [\boldsymbol{\epsilon}_p(\mathbf{x}) - \epsilon_s \mathbf{1}] \quad \text{form amplitude tensor of sphere } l$$

$$\mathbf{B}_l(\mathbf{q}) = \frac{V_a}{\epsilon_s} b(\mathbf{q}) \left\{ \left(\epsilon_p^{\parallel} - \epsilon_s \right) \hat{\mathbf{u}}_l \hat{\mathbf{u}}_l + \left(\epsilon_p^{\perp} - \epsilon_s \right) \left(\mathbf{1} - \hat{\mathbf{u}}_l \hat{\mathbf{u}}_l \right) \right\}$$

homog. sphere with single optical axis pointing along unit vector $\hat{\mathbf{u}}_l$

form amplitude of isotrop & uniform sphere

- VV – geometry : measuring non-depolarized el. field comp.
- VH – geometry : measuring depolarized el. field comp $\rightarrow$ rotational diffusion
- Optically isotropic sphere : $\epsilon_p = \epsilon_p \mathbf{1} \rightarrow$ zero VH – single scattering

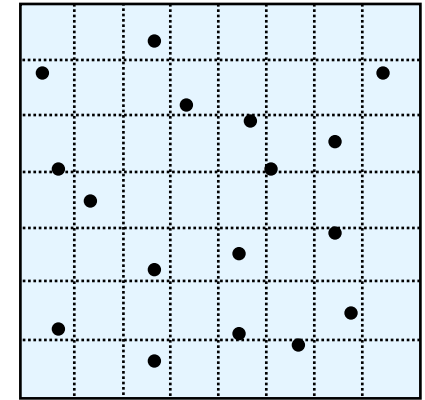
Siegert relation: polarized scattering from isotropic & monodisperse colloidal spheres

Homodyne DLS: determines intensity autocorrelation function (IACF)

$$g_I(\mathbf{q}, t) = \langle I_s(\mathbf{q}, 0) I_s(\mathbf{q}, t) \rangle = \left\langle E_s(\mathbf{q}, 0) E_s^*(\mathbf{q}, 0) \cdot E_s(\mathbf{q}, t) E_s^*(\mathbf{q}, t) \right\rangle$$

$$\begin{aligned} g_I(\mathbf{q}, t) = & \left\langle E_s(\mathbf{q}, 0) E_s^*(\mathbf{q}, 0) \right\rangle \left\langle E_s(\mathbf{q}, t) E_s^*(\mathbf{q}, t) \right\rangle \\ & + \left\langle E_s(\mathbf{q}, 0) E_s(\mathbf{q}, t) \right\rangle \left\langle E_s^*(\mathbf{q}, 0) E_s^*(\mathbf{q}, t) \right\rangle \\ & + \left\langle E_s(\mathbf{q}, 0) E_s^*(\mathbf{q}, t) \right\rangle \left\langle E_s^*(\mathbf{q}, 0) E_s(\mathbf{q}, t) \right\rangle \end{aligned}$$

time
average



> Correlation length

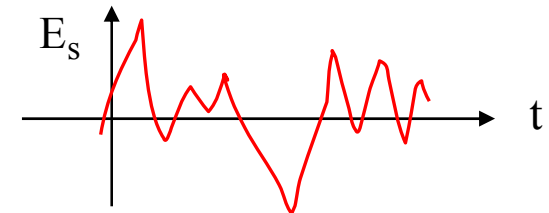
Central limit theorem: - each cell includes many scatterers
- E_s is complex central Gaussian random variable

$$g_I(\mathbf{q}, t) = \langle I_s(\mathbf{q}) \rangle^2 + 0 + \langle E_s(-\mathbf{q}, 0) E_s(\mathbf{q}, t) \rangle^2$$

isotropic
fluid phase

time-indep. mean
in equilibrium

translational invariance of homog. system



$$\left\langle e^{i\mathbf{q}\cdot[\mathbf{r}_j+\mathbf{r}_l]} \right\rangle = \left\langle e^{i\mathbf{q}\cdot[\mathbf{r}_j+\mathbf{a}+\mathbf{r}_l+\mathbf{a}]} \right\rangle = \underbrace{\left\langle e^{i\mathbf{q}\cdot[\mathbf{r}_j+\mathbf{r}_l]} \right\rangle}_{=0} e^{2i\mathbf{q}\cdot\mathbf{a}} \quad \text{spatial homogeneity}$$

$$\left\langle e^{i\mathbf{k}_1\cdot\mathbf{r}_1} e^{i\mathbf{k}_2\cdot\mathbf{r}_2} \dots e^{i\mathbf{k}_n\cdot\mathbf{r}_n} \right\rangle = \delta_{\mathbf{k}_1+\mathbf{k}_2+\dots+\mathbf{k}_n,0} \left\langle e^{i\mathbf{k}_1\cdot\mathbf{r}_1} e^{i\mathbf{k}_2\cdot\mathbf{r}_2} \dots e^{i\mathbf{k}_n\cdot\mathbf{r}_n} \right\rangle$$

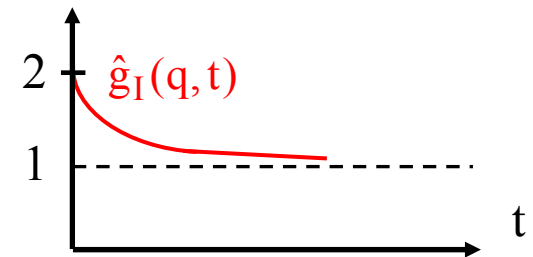
$$g_E(\mathbf{q}, t) = \left\langle E_s^*(\mathbf{q}, 0) E_s(\mathbf{q}, t) \right\rangle \quad \text{el. field autocorrelation function (EFAC)}$$

$$g_E(\mathbf{q}, t) = \left[g_I(\mathbf{q}, t) - \langle I_s(\mathbf{q}) \rangle^2 \right]^{1/2} \quad \text{Siegert relation for stationary, ergodic system}$$

(time average $\rightarrow$ ensemble average)

$$\hat{g}_E(\mathbf{q}, t) = g_E(\mathbf{q}, t) / \langle I_s(\mathbf{q}) \rangle \quad \rightarrow \quad \hat{g}_E(\mathbf{q}, 0) = 1$$

$$\hat{g}_I(\mathbf{q}, t) = g_I(\mathbf{q}, t) / \langle I_s(\mathbf{q}) \rangle^2 \quad \rightarrow \quad \hat{g}_I(\mathbf{q}, 0) = \langle I_s(\mathbf{q})^2 \rangle / \langle I_s(\mathbf{q}) \rangle^2$$



$$\hat{g}_I(\mathbf{q}, t) = 1 + [\hat{g}_E(\mathbf{q}, t)]^2$$

$$0 \leq \left\langle \left[I_s(\mathbf{q}) - \langle I_s(\mathbf{q}) \rangle \right]^2 \right\rangle = \langle I_s(\mathbf{q})^2 \rangle - \langle I_s(\mathbf{q}) \rangle^2 \quad \rightarrow \quad \text{in general, only valid that : } \hat{g}_I(\mathbf{q}, 0) \geq 1$$

Dynamic correlation functions

- Homodyne DLS experiment + Siegert relation :

$$g_E(\mathbf{q}, t) \propto \langle N \rangle P(\mathbf{q}) S(\mathbf{q}, t) \quad \leftarrow \text{dynamic structure factor} \\ (t > \tau_{\text{DLS}} \approx 1 \mu\text{sec})$$

$$S(\mathbf{q}, t) = \lim_{\infty} \left\langle \frac{1}{N} \delta\rho(-\mathbf{q}, 0) \delta\rho(\mathbf{q}, t) \right\rangle = \lim_{\infty} \left\{ \frac{1}{N} \sum_{j,l=1}^N \left\langle e^{i\mathbf{q} \cdot [\mathbf{r}_j(t) - \mathbf{r}_l(0)]} \right\rangle - N \delta_{\mathbf{q},0} \right\}$$

$$S(\mathbf{q}) = S(\mathbf{q}, 0) = 1 + \rho \int d\mathbf{r} e^{i\mathbf{q} \cdot \mathbf{r}} [g(\mathbf{r}) - 1] \quad \delta\rho(\mathbf{q}) = \sum_{l=1}^N e^{i\mathbf{q} \cdot \mathbf{r}_l} - N \delta_{\mathbf{q},0}$$

$$S(\mathbf{q}, t) = G(\mathbf{q}, t) + S_d(\mathbf{q}, t) \quad \leftarrow \text{split in self- and distinct parts}$$

$$S_d(\mathbf{q}, t) = \lim_{\infty} \left\langle (N-1) e^{i\mathbf{q} \cdot [\mathbf{r}_1(t) - \mathbf{r}_2(0)]} - N \delta_{\mathbf{q},0} \right\rangle = \rho \int d\mathbf{r} e^{i\mathbf{q} \cdot \mathbf{r}} \left\{ \underbrace{\lim_{\infty} \langle V \delta(\mathbf{r} - \mathbf{r}_1(t) + \mathbf{r}_2(0)) \rangle}_{g_d(\mathbf{r}, t)} - 1 \right\}$$

$$S_d(\mathbf{q}, t) = \rho \int d\mathbf{r} e^{i\mathbf{q} \cdot \mathbf{r}} \{g_d(\mathbf{r}, t) - 1\}$$

$$g_d(\mathbf{r}, 0) = g(\mathbf{r})$$

$g_d(\mathbf{r}, t)$: distinct van Hove
real-space function
(2d – experiments)

- Self-dynamic scattering function $G(q,t)$:

$$G(q,t) = \lim_{\infty} \left\langle e^{i\mathbf{q} \cdot [\mathbf{r}_1(t) - \mathbf{r}_1(0)]} \right\rangle = \rho \int d\mathbf{r} e^{i\mathbf{q} \cdot \mathbf{r}} g_s(\mathbf{r}, t)$$

$$g_s(\mathbf{r}, t) = \lim_{\infty} \left\langle \delta(\mathbf{r} - \mathbf{r}_1(t) + \mathbf{r}_1(0)) \right\rangle$$

self van Hove function
(single-particle conditional pdf)

- Small-q expansion for isotropic system :

$$G(q,t) = 1 - \frac{1}{2} \sum_{\alpha=1}^d q_{\alpha}^2 \underbrace{\left\langle [x_{\alpha 1}(t) - x_{\alpha 1}(0)]^2 \right\rangle}_{\left\langle [\mathbf{r}_1(t) - \mathbf{r}_1(0)]^2 \right\rangle / d} + O(q^4)$$

Mean squared displacement

$$W(t) = \frac{1}{2d} \left\langle [\mathbf{r}_1(t) - \mathbf{r}_1(0)]^2 \right\rangle$$

$d = 1, 2$ and 3 (dimensionality)

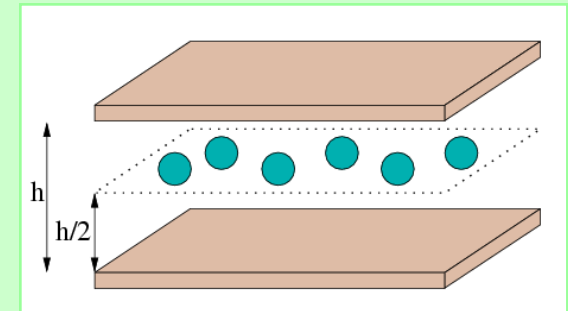
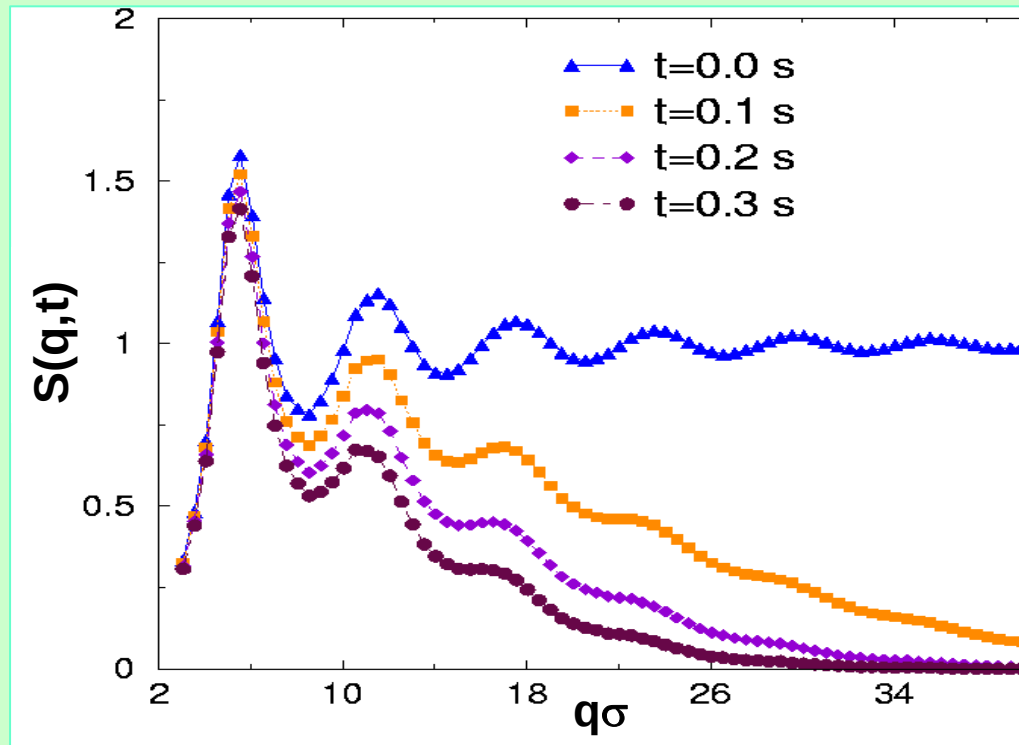
- Expansion in cumulant form :

$$G(q,t) = \exp \left\{ -q^2 W(t) \right\} \cdot \left[1 + \text{non-Gaussian terms of } O(q^4) \right]$$

$$g_s(\mathbf{r}, t) = (4\pi W(t))^{-d/2} \exp \left\{ -\frac{r^2}{4W(t)} \right\} + \text{non-Gaussian terms}$$

Small in fluid phase but:
dynamic heterogeneities
In colloidal glasses

Example: Quasi-2D dynamic structure factor of charged colloidal spheres

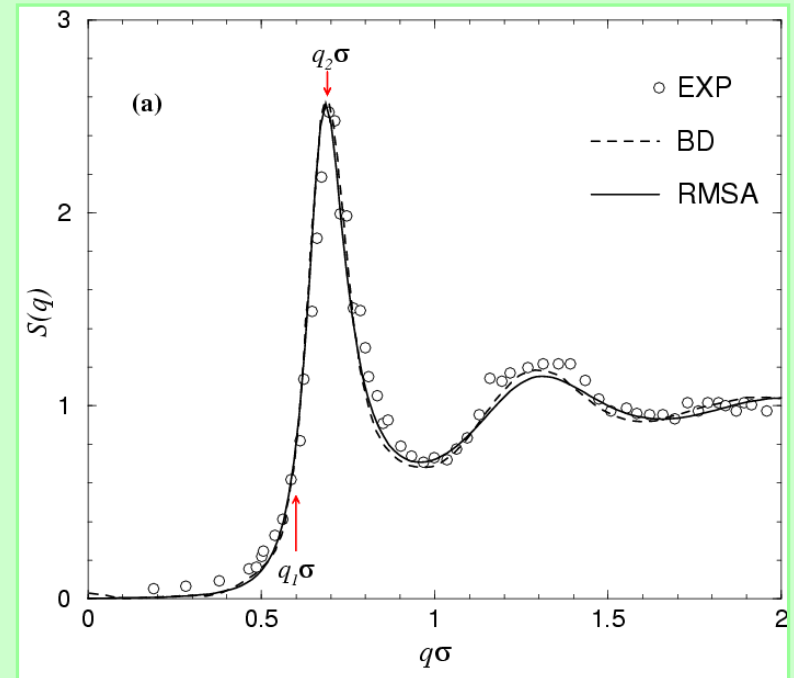
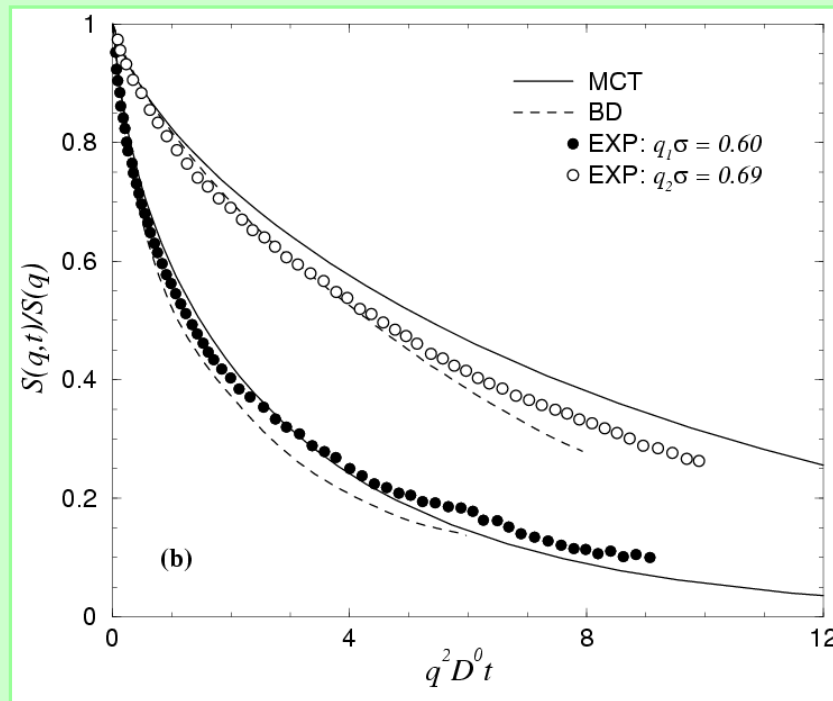


(Courtesy: J.L. Arauz-Lara, Univ. of San Luis Potosi)

$$S(q, t = 0) = S(q)$$

$$S(q, t \rightarrow \infty) = 0 \quad (\text{in fluid phase})$$

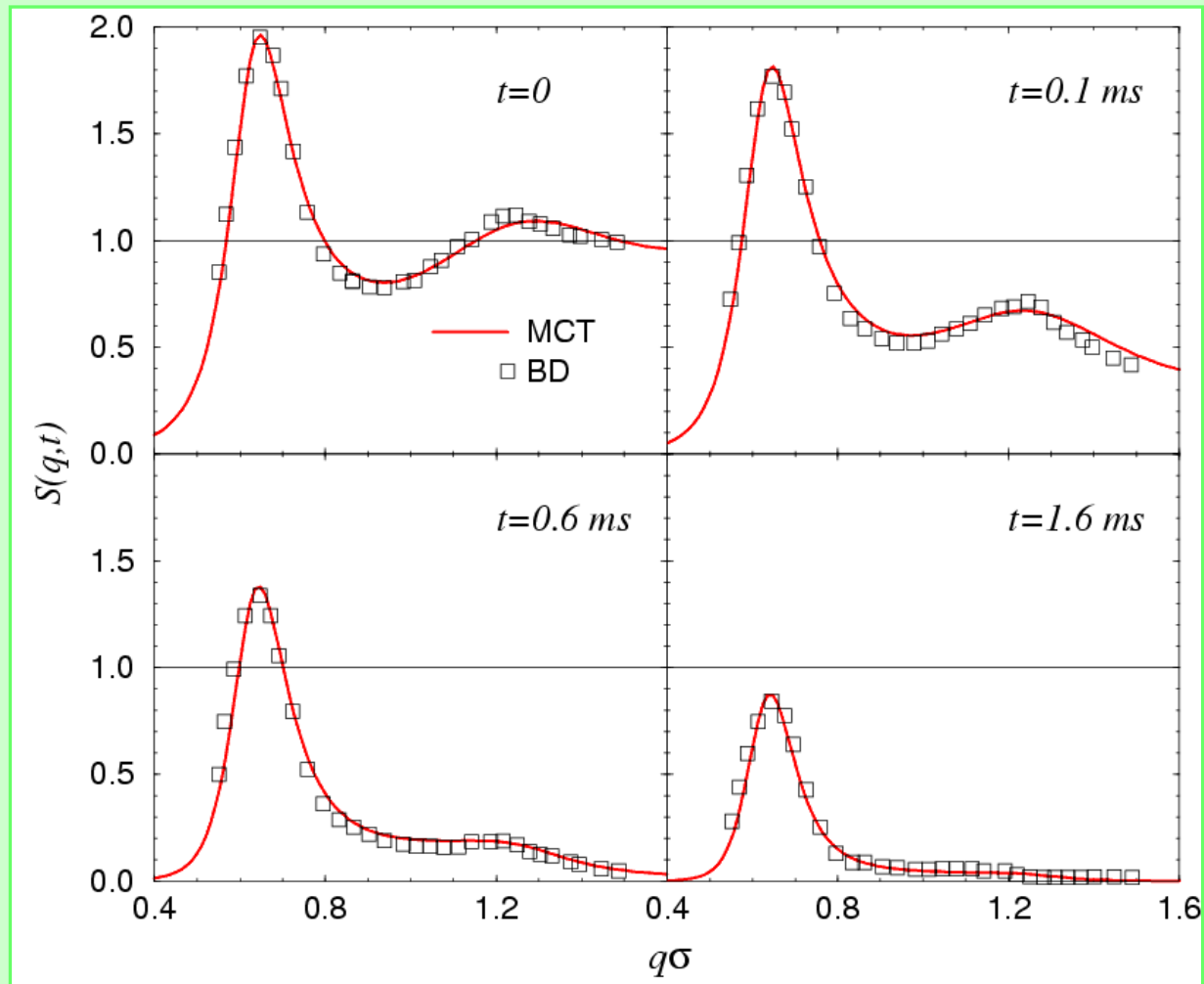
Example: Dynamic structure factor of 3D charge-stabilized dispersion



(Banchio, Nägele & Bergenholtz, J. Chem. Phys. 113 (2000))

- Density autocorrelation function $S(q,t)$ decays monotonically in t
- Valid for any regular autocorrelation function at colloidal time scales

Example: Dynamic structure factor of 3D charge-stabilized dispersion



BD : Gaylor et al., J. Phys. A (1980)

Theory : Banchio, Nägele & Bergenholtz, J. Chem. Phys. (2000)

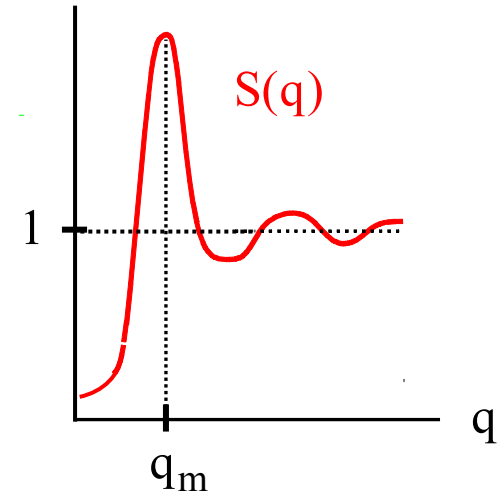
How to measure $G(q,t)$ and $W(t)$ using DLS ?

- Large- q measurement :

$$S(q,t) = G(q,t) + S_d(q,t) \approx G(q,t) \quad (q > q_m)$$

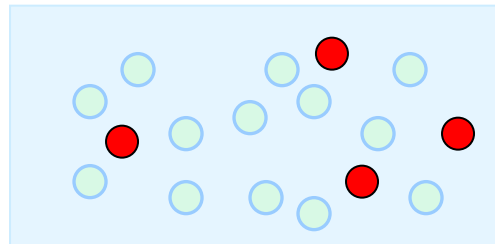
$$S_d(q,0) = S(q) - 1$$

$$G(q,0) = 1$$



- Binary mixture of, w/r to interactions, identical tracer and host spheres

$$g_E(q,t) \propto G(q,t)$$

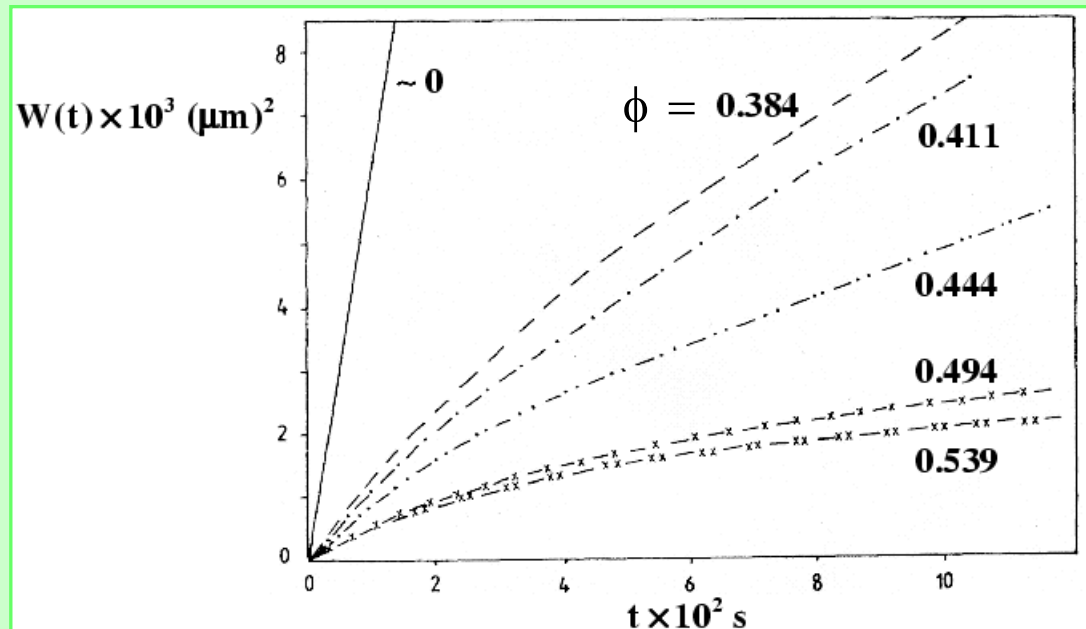


$$(\rho_T \ll \rho_H)$$

- DLS: typical resolution of correlation times

$$1 \mu\text{sec} < t < \text{sec. to days}$$

Example: Silica tracer spheres in index-matched PMMA sphere solution



(van Megen et al., J. Chem. Phys. 85 (1986))

- Plot - $\log G(q,t)/q^2$ versus q^2 and extrapolate to $q \rightarrow 0$ (then zero non-Gaussian contr.)
- Strong many-body influence of HI for $\phi > 0.2$

4. Theoretical description of colloid dynamics

- **Single particle dynamics in very dilute dispersions**
- **Colloidal time and length scales**
- **Generalized Smoluchowski diffusion equation for dense systems**

Single particle dynamics in very dilute dispersions

- Langevin equation for a single colloidal sphere :

$$M \frac{d}{dt} \mathbf{v}(t) = -\zeta_0 \mathbf{v}(t) + \mathbf{F}(t) \quad (t \gg \tau_s)$$

Gaussian & Markovian
random solvent forces

$$\langle F_\alpha(t) \rangle_F = 0$$

$$\langle F_\alpha(t) F_\beta(t') \rangle_F = 2 \Gamma \delta_{\alpha\beta} \delta(t - t') \quad \text{isotropic white noise}$$

$$\langle \mathbf{v}(t) \rangle_F = \mathbf{v}_0 e^{-t/\tau_B}$$

$$\tau_B = M / \zeta_0$$

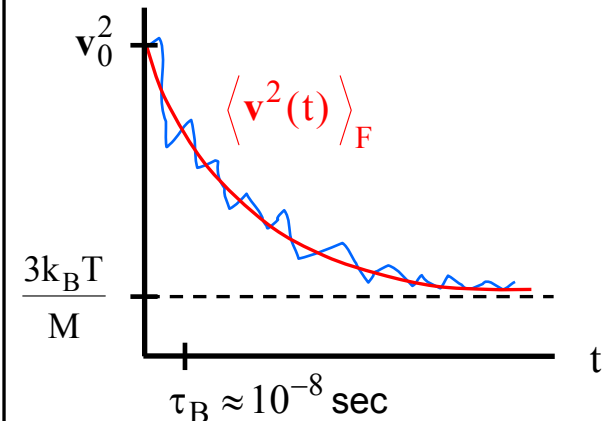
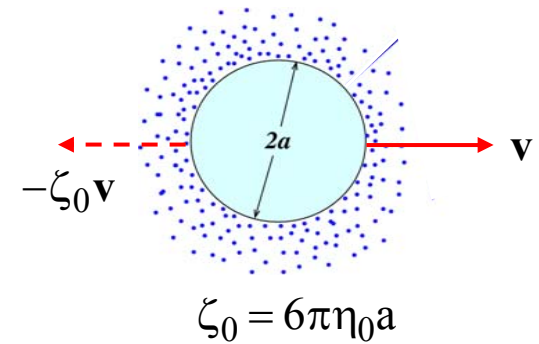
momentum
relaxation time

$$\mathbf{v}(t) = \mathbf{v}_0 e^{-t/\tau_B} + \int_0^t du e^{-(t-u)/\tau_B} \mathbf{F}(u) / M$$

$$\langle \mathbf{v}^2(t) \rangle_F = \mathbf{v}_0^2 e^{-2t/\tau_B} + \frac{3\Gamma}{M\zeta_0} (1 - e^{-2t/\tau_B}) \quad (t \gg \tau_B)$$

$$\Gamma = k_B T \zeta_0$$

Fluctuation-dissipation relation



$$\langle \mathbf{v}^2 \rangle_{eq} = \frac{3k_B T}{M} \quad \text{equipartition theorem}$$

- Ensemble of independent particles in equilibrium → stationarity in time

$$\langle \dots \rangle = \int d\mathbf{r}_0 \int d\mathbf{v}_0 P_{\text{eq}}(\mathbf{r}_0, \mathbf{v}_0) \langle \dots \rangle_F \quad P_{\text{eq}}(\mathbf{r}_0, \mathbf{v}_0) = \frac{1}{V} \left(\frac{M}{2\pi k_B T} \right)^{3/2} e^{-\frac{M}{2k_B T} \mathbf{v}_0^2}$$

$$\phi_v(|t' - t''|) = \frac{1}{d} \langle \mathbf{v}(t') \cdot \mathbf{v}(t'') \rangle \quad \text{velocity autocorrelation function (VAF)}$$

$$\phi_v(t) = \frac{1}{3} \langle \mathbf{v}(t) \cdot \mathbf{v}_0 \rangle = \frac{k_B T}{M} e^{-t/\tau_B} \quad \text{single-sphere VAF}$$

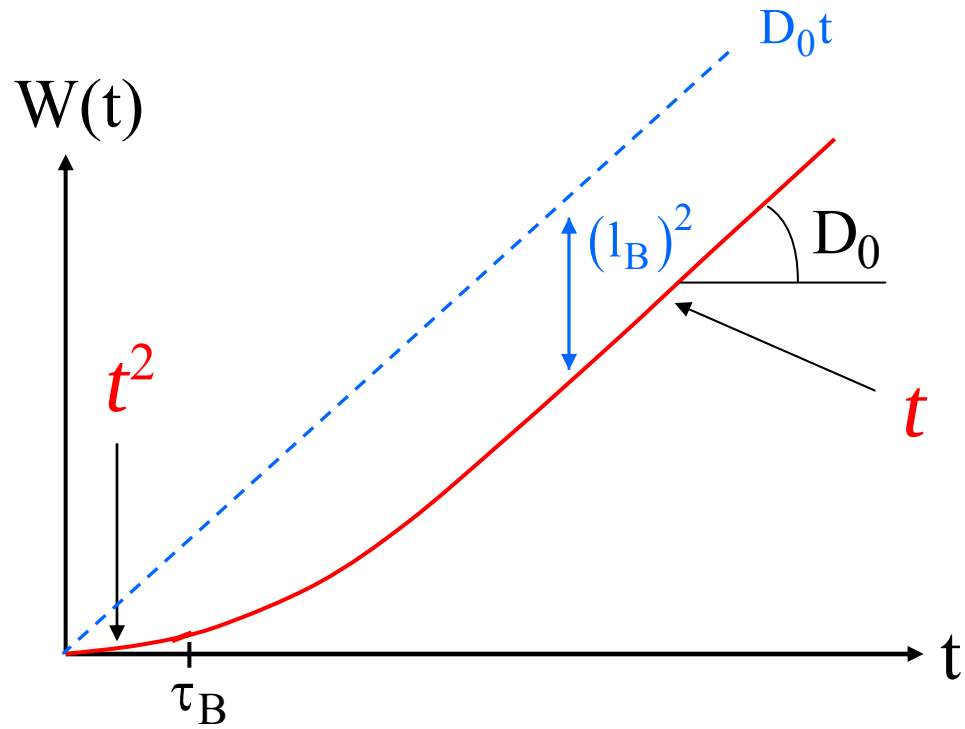
$$\mathbf{r}(t) - \mathbf{r}_0 = \int_0^t dt' \mathbf{v}(t') \quad \longrightarrow \quad W(t) = \frac{1}{2d} \langle (\mathbf{r}(t) - \mathbf{r}_0)^2 \rangle = \frac{1}{2} \int_0^t dt' \int_0^t dt'' \phi_v(|t' - t''|)$$

$$W(t) = \int_0^t du (t - u) \phi_v(u) \quad \text{Ornstein-Fürth formula for stationary system}$$

$$W(t) = D_0 t \left[1 - \frac{\tau_B}{t} (1 - e^{-t/\tau_B}) \right] \rightarrow \begin{cases} \frac{k_B T}{2M} t^2 & (\tau_s \ll t \ll \tau_B) \\ D_0 (t - \tau_B) & (\tau_B \ll t) \end{cases}$$

$$D_0 = \frac{k_B T}{\zeta_0} \quad \text{single-sphere translational Stokes-Einstein relation}$$

Single-sphere mean squared displacement (MSD)



- Displacement $\Delta \mathbf{r} = \mathbf{r}(t) - \mathbf{r}_0$ is central Gaussian random variable w/r to $\langle \dots \rangle$

$$P(\Delta \mathbf{r}, t) = \prod_{\alpha=1}^3 \left(2\pi \sigma_{\Delta x_{\alpha}} \right)^{-1/2} \exp \left\{ -\frac{(\Delta x_{\alpha})^2}{2 \sigma_{\Delta x_{\alpha}}^2} \right\} \quad \sigma_{\Delta x_{\alpha}}^2 = \langle (\Delta x_{\alpha})^2 \rangle = 2W(t)$$

$$P(\Delta \mathbf{r}, t) = (4\pi W(t))^{-3/2} \exp \left\{ -\frac{(\Delta \mathbf{r})^2}{4 W(t)} \right\} \quad P(\Delta \mathbf{r}, t=0) = \delta(\Delta \mathbf{r})$$

- Pdf is fundamental solution of diffusion-like equation:
(not a Fokker-Planck equation, since $\Delta \mathbf{r}$ Gaussian but non-Markovian)

$$\frac{\partial}{\partial t} P(\Delta \mathbf{r}, t) = D^*(t) \nabla^2 P(\Delta \mathbf{r}, t) \quad D^*(t) = \frac{d}{dt} W(t) = D_0 \left[1 - e^{-t/\tau_B} \right]$$

- Single-particle self-dynamic structure factor :

$$G(q, t) = \int d(\Delta \mathbf{r}) e^{i\mathbf{q} \cdot \Delta \mathbf{r}} P(\Delta \mathbf{r}, t) = e^{-q^2 W(t)} \rightarrow e^{-q^2 D_0 t}$$

$$\Delta t \gg \tau_B \quad \& \quad \Delta x \gg \sqrt{D_0 \tau_B}$$

Overdamped (positional) Langevin equation for a single particle

- Time required to diffuse a distance comparable to $a = 100$ nm :

$$\tau_I = \frac{a^2}{D_0} \approx 10^{-3} \text{ sec} \longrightarrow \tau_I \gg \tau_B$$

Momenta relaxed long before observable change in particle configuration

- Inertia-effects non-observable for times $t \gg \tau_B$ so that $dv/dt \approx 0$

$$\mathbf{v}(t) = \frac{1}{\zeta_0} \mathbf{F}(t) \equiv \mathbf{v}^B(t) \quad (\Delta t \gg \tau_B \quad \& \quad \Delta x \gg \sqrt{D_0 \tau_B})$$

$$\langle v_\alpha^B(t) \rangle = 0$$

Gaussian & Markovian (i.e. local in time)
random velocity

$$\langle v_\alpha^B(t) v_\beta^B(t') \rangle = 2 D_0 \delta_{\alpha\beta} \delta(t - t') \quad \text{white additive noise}$$

$$\phi_v(t) = 2 D_0 \delta(t)$$

Overdamped (positional) Langevin equation for a single free particle

$$\mathbf{r}(t) - \mathbf{r}_0 = \int_0^t dt' \mathbf{v}^B(t') \equiv \Delta \mathbf{r}^B(t) \quad \langle \Delta \mathbf{r}^B(t) \rangle = 0$$

$$\langle \Delta \mathbf{r}^B(t) \Delta \mathbf{r}^B(t) \rangle = 2 D_0 \mathbf{1} \delta(t)$$

- $\Delta \mathbf{r}^B$ is Gaussian of zero mean and variance $2 D_0 \mathbf{1} \delta(t)$

$$(\mathbf{1})_{\alpha\beta} = \delta_{\alpha\beta}$$

$$\mathbf{u} \mathbf{w} := \mathbf{u} \cdot \mathbf{w}^T$$

$$P(\Delta \mathbf{r}^B, t) = (4\pi D_0 t)^{-3/2} \exp \left\{ -\frac{(\Delta \mathbf{r}^B)^2}{4 D_0 t} \right\}$$

$$(\mathbf{u} \mathbf{w})_{\alpha\beta} = u_\alpha w_\beta$$

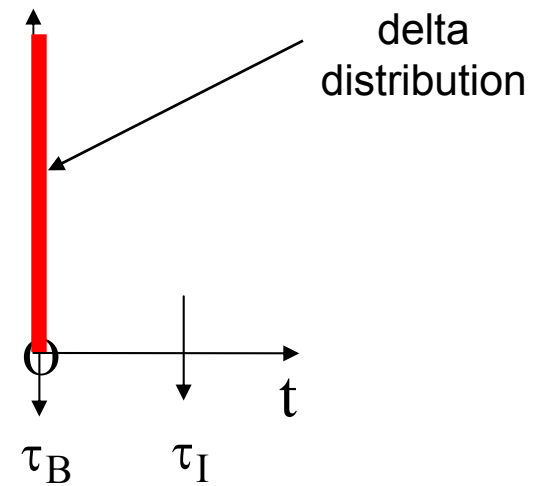
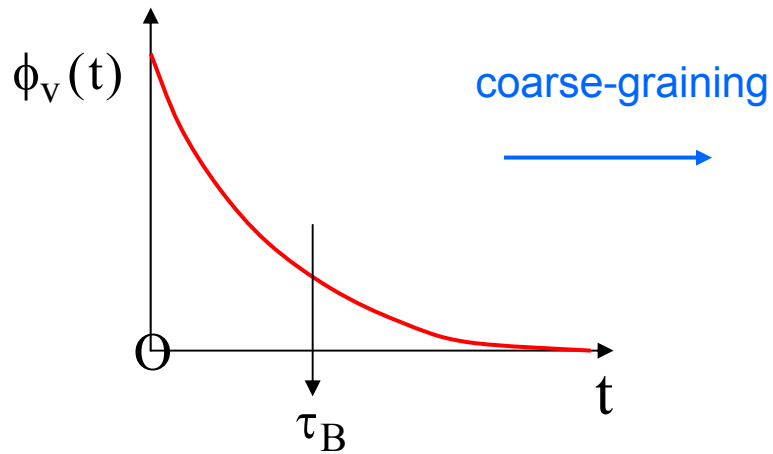
$$W(t) = \langle (\Delta \mathbf{r}^B)^2 \rangle / 6 = D_0 t \quad \text{MSD for } t \gg \tau_B$$

dyadic notation

$$\frac{\partial}{\partial t} P(\Delta \mathbf{r}^B, t) = D_0 \nabla^2 P(\Delta \mathbf{r}^B, t)$$

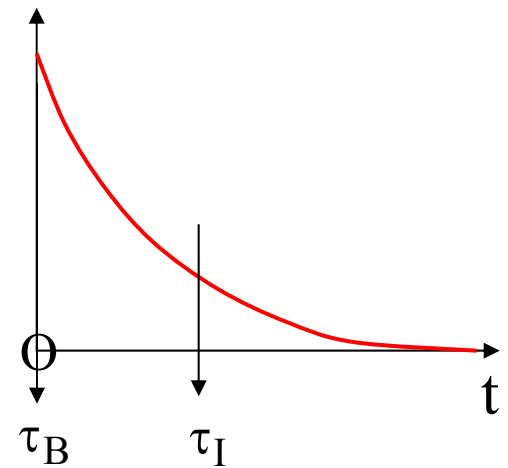
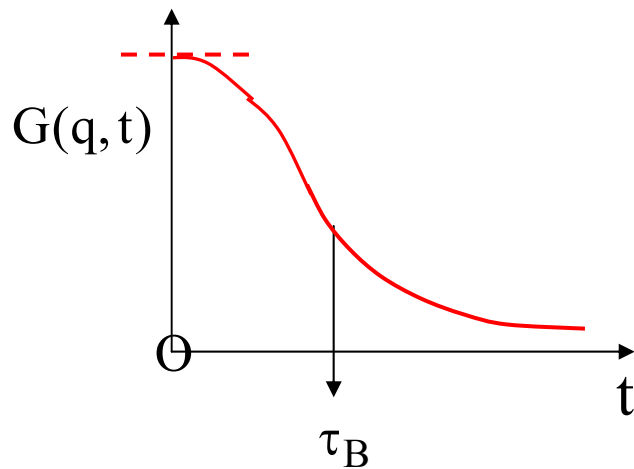
Smoluchowski eq. for free particle
statistically equiv. to positional Langevin eq.

$$G(\mathbf{q}, t) = \int d(\Delta \mathbf{r}^B) e^{i\mathbf{q} \cdot \Delta \mathbf{r}^B} P(\Delta \mathbf{r}^B, t) = e^{-q^2 D_0 t}$$



- Green-Kubo relation for free particle :

$$D_0 = \int_0^{\infty} dt \phi_v(t)$$



Retarded free particle Langevin equation

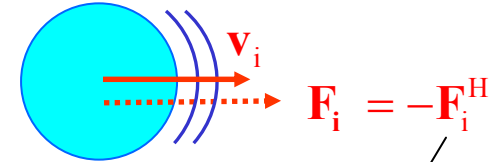
$$M \frac{d}{dt} \mathbf{v}(t) = - \int_{-\infty}^t du \gamma(t-u) \mathbf{v}(u) + \mathbf{F}^R(t) \quad (t \gg \tau_s)$$

Retarded solvent response

$$\langle F_{\alpha}^R(t) \rangle_F = 0$$

$$\langle F_{\alpha}^R(t) F_{\beta}^R(t') \rangle_F = k_B T \delta_{\alpha\beta} \gamma(|t - t'|)$$

Gaussian & non-Markovian random force



Friction force on sphere by surrounding solvent

- $\gamma(t)$ from linearized Navier-Stokes equation of incompressible fluid

$$\rho_s \frac{\partial \mathbf{u}(\mathbf{r}, t)}{\partial t} = -\nabla p(\mathbf{r}, t) + \eta_0 \nabla^2 \mathbf{u}(\mathbf{r}, t)$$

$$\nabla \cdot \mathbf{u}(\mathbf{r}, t) = 0$$

$$(t \gg \tau_c = a/c \approx 10^{-10} \text{ sec})$$

$$\boldsymbol{\sigma}(\mathbf{r}, t) = -p(\mathbf{r}, t) \mathbf{1} + \eta_0 \left[\nabla \mathbf{u} + (\nabla \mathbf{u})^T \right]$$

$$Re = \frac{\text{inertial force}}{\text{viscous force}} = \frac{\rho_s \sigma v_{th}}{\eta_0} \ll 1$$

$$\rho_s \frac{\partial \mathbf{u}(\mathbf{r}, t)}{\partial t} = \nabla \cdot \boldsymbol{\sigma}(\mathbf{r}, t)$$

$\boldsymbol{\sigma}(\mathbf{r}, t)$: Stress tensor of incompr. Newtonian fluid

$$\mathbf{F}^H(t) = \int_S dS \underbrace{\boldsymbol{\sigma}(\mathbf{r}, t) \cdot \hat{\mathbf{n}}(\mathbf{r})}_{\text{fluid force/area on sphere at element } dS \text{ at } \mathbf{r} \text{ exerted by surrounding fluid}}$$

fluid force/area on sphere at element dS at $\mathbf{r}$ exerted by surrounding fluid

$$\mathbf{F}^H(t) = - \int_{-\infty}^t du \underbrace{\gamma(t-u)}_{\text{Stokes-Boussinesq solution}} \mathbf{v}(u)$$

Stokes-Boussinesq solution

$$\frac{\partial}{\partial t} [\nabla \times \mathbf{u}(\mathbf{r}, t)] = \frac{\eta_0}{\rho_s} \Delta [\nabla \times \mathbf{u}(\mathbf{r}, t)]$$

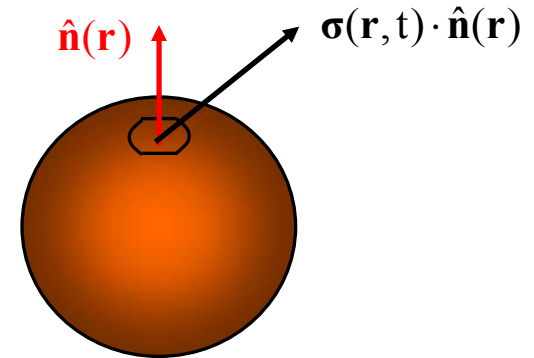
vorticity (shear-wave) diffusion due to unsteady particle motion

$$\frac{\partial}{\partial t} \omega(\mathbf{q}, t) = - \frac{\eta_0}{\rho_s} q^2 \omega(\mathbf{q}, t)$$

$$q = a^{-1} \rightarrow \omega(\mathbf{q}, t) / \omega(\mathbf{q}, 0) = e^{-t/\tau_\eta}$$

$$\tau_\eta = a^2 \frac{\rho_s}{\eta_0} = \frac{9}{2} \left(\frac{\rho_s}{\rho_p} \right) \tau_B$$

viscous hydrodynamic relaxation time for unsteady particle disturbances



$$\omega(\mathbf{q}, t) = \frac{1}{2} \int d\mathbf{r} e^{i\mathbf{q} \cdot \mathbf{r}} \nabla \times \mathbf{u}(\mathbf{r}, t)$$

$$\nabla \rightarrow -i\mathbf{q}$$

$$\Delta \rightarrow -q^2$$

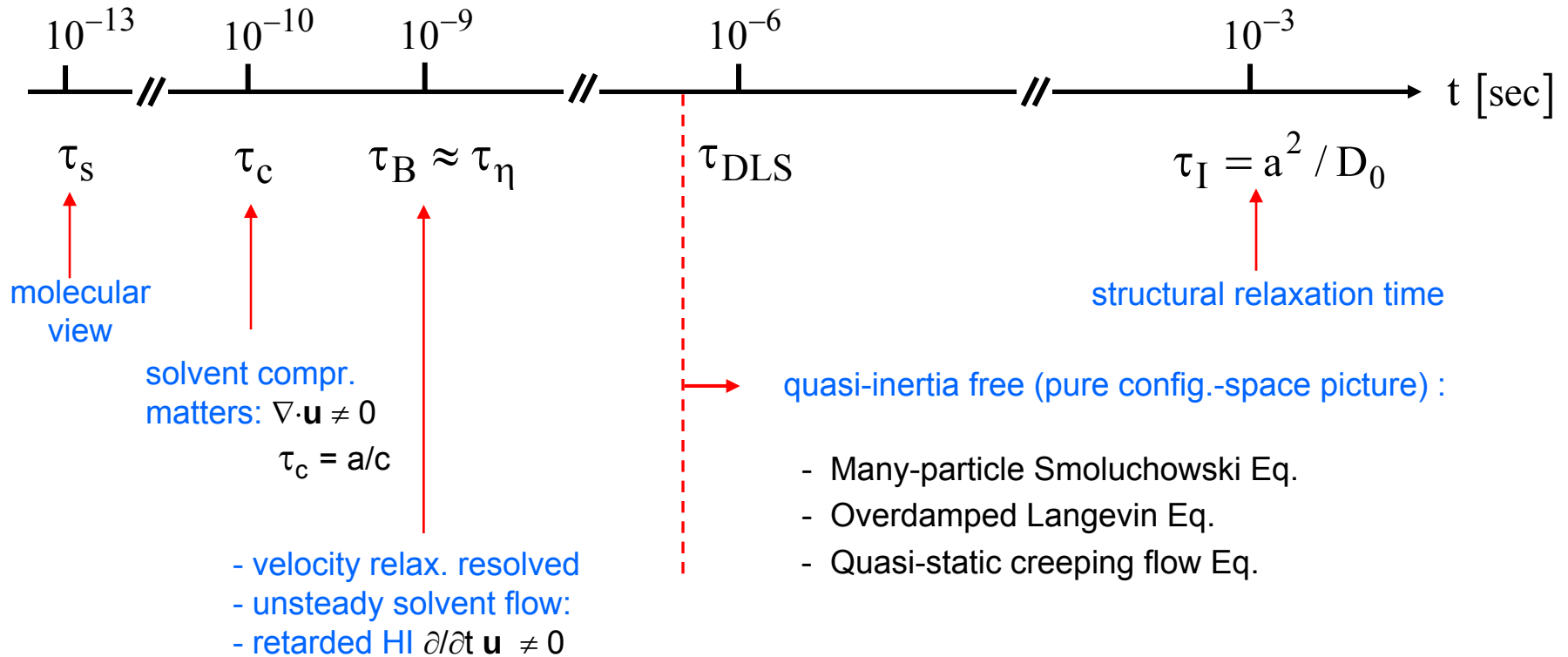
- Hydrodynamic long-time tails from Boussinesq solution for $t \simeq \tau_\eta$

$$\phi_v(t) = \frac{d^2}{dt^2} W(t) \approx \frac{1}{9\sqrt{\pi}} \frac{k_B T}{M} \left(\frac{t}{\tau_\eta} \right)^{-3/2}$$
$$W(t) \approx D_0 t \left[1 - \frac{2}{\sqrt{\pi}} \left(\frac{t}{\tau_\eta} \right)^{-1/2} \right] \rightarrow D_0 t$$

Tail resolvable using DLS for micron-sized spheres

- Non-retarded Langevin-eq. applicable to colloids only for $t \gg \tau_B \approx \tau_\eta$
- Non-retarded Langevin-eq. applicable to aerosols for $t \simeq \tau_B \gg \tau_\eta$

Colloidal time scales



$\tau_B = M / \zeta_0$ transl. momentum relaxation time ($\zeta_0 = 6\pi\eta_0 a$)

$\tau_\eta = a^2 \rho_s / \eta_0 = 4.5 (\rho_s / \rho_p) \tau_B$ viscous relaxation time (vorticity diffusion)
 (for aerosols: $\tau_\eta \ll \tau_B \Rightarrow$ non-retarded Langevin-eq. for $t \sim \tau_B$)

Interacting particles: $a \rightarrow \xi(\phi, \dots)$ (interaction/correlation length)

Generalized Smoluchowski diffusion equation for dense systems

- N torque-free colloidal spheres in unbounded and quiescent (!) solvent
- Assume spherically symmetric direct pair interactions $u(r)$

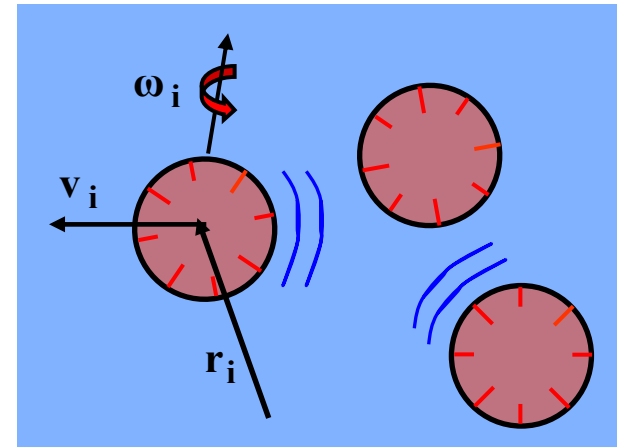
→ translational degrees of freedom decouple from rotational ones

Probability conservation of configurational Pdf :

$$\frac{\partial}{\partial t} P(\mathbf{r}^N, t) + \sum_{i=1}^N \nabla_i \cdot \left(\mathbf{v}_i(\mathbf{r}^N) P(\mathbf{r}^N, t) \right) = 0$$

Quasi-inertia free motion for $t \gg \tau_B \approx \tau_\eta$

$$\text{total force on } i = \mathbf{0} = \mathbf{F}_i^p + \mathbf{F}_i^{\text{ex}} + \mathbf{F}_i^H + \mathbf{F}_i^B$$



$$\mathbf{F}_i^p = -\nabla_i U(\mathbf{r}^N) = -\sum_{l=1}^N \nabla_i u(r_{il}) \quad \text{direct forces}$$

$$\mathbf{F}_i^{\text{ex}} = -\nabla_i U^{\text{ex}}(\mathbf{r}^N) \quad \text{external forces (e.g. gravity)}$$

$$\mathbf{F}_i^H = -\sum_{l=1}^N \zeta_{il}(\mathbf{r}^N) \cdot \mathbf{v}_l \quad \text{hydrodyn. force on } i \text{ (by surrounding fluid)}$$

$$\mathbf{F}_i^B = -k_B T \nabla_i \ln P \quad \text{Brownian force (drives diffusion)}$$

Solve for the $\mathbf{v}_i$ using generalized hydrodynamic Stokes-Einstein relation :

$$\sum_{l=1}^N \boldsymbol{\zeta}_{il}(\mathbf{r}^N) \cdot \mathbf{D}_{lj}(\mathbf{r}^N) = k_B T \delta_{ij} \mathbf{1} \quad \boldsymbol{\zeta}(X) \cdot \mathbf{D}(X) = k_B T \mathbf{1} \quad (X = \mathbf{r}^N)$$

real, symmetric + pos. definite $3N \times 3N$ matrix

$$\mathbf{v}_i = -\beta \sum_{l=1}^N \mathbf{D}_{il}(\mathbf{r}^N) \cdot [\mathbf{F}_l^H = -\mathbf{F}_l^p - \mathbf{F}_l^{\text{ex}} - \mathbf{F}_l^B] = \sum_{l=1}^N \mathbf{D}_{il}(\mathbf{r}^N) \cdot [\beta \mathbf{F}_l^p + \beta \mathbf{F}_l^{\text{ex}} - \nabla_l \ln P(\mathbf{r}^N, t)]$$

Insertion in continuity eq. leads to generalized Smoluchowski equation (GSE) :

$$\frac{\partial}{\partial t} P(\mathbf{r}^N, t) = \hat{O}(\mathbf{r}^N) P(\mathbf{r}^N, t)$$

$$\hat{O}(\mathbf{r}^N) = \sum_{i,j=1}^N \nabla_i \cdot \mathbf{D}_{ij} \cdot [\nabla_j - \beta (\mathbf{F}_j^p + \mathbf{F}_j^{\text{ex}})]$$

Smoluchowski differential operator

Choice of Brownian forces was such that :

$$\hat{O}(\mathbf{r}^N) e^{-\beta[U + U^{\text{ex}}]} = 0 \quad \text{i.e.} \quad e^{-\beta[U + U^{\text{ex}}]} \quad \text{is stationary solution}$$

$$P(\mathbf{r}^N, t) \rightarrow P_{\text{eq}}(\mathbf{r}^N) \propto e^{-\beta U} \quad (t \rightarrow \infty \ \& \ U^{\text{ex}} = 0) \quad \text{H-theorem of Smoluchowski dynamics}$$

For hydrodynamically non-interacting spheres is :

$$\mathbf{D}_{ij}(\mathbf{r}^N) = D_0 \delta_{ij} \mathbf{1} \quad \text{i.e.} \quad \mathbf{v}_i = - \sum_{l=1}^N \underbrace{\beta \mathbf{D}_{il}(\mathbf{r}^N)}_{\text{Translational-translational (tt) hydrodynamic mobilities}} \cdot \mathbf{F}_l^H \rightarrow -\beta D_0 \mathbf{F}_i^H$$

$$\hat{\mathcal{O}}(\mathbf{r}^N) = D_0 \sum_{i=1}^N \nabla_i \cdot \left[\nabla_i - \beta \left(\mathbf{F}_i^p + \mathbf{F}_i^{\text{ex}} \right) \right]$$

Translational-translational (tt)
hydrodynamic mobilities
(linear velocity-force relations
implied by linearity of hydrodyn.
eqs. for fluid motion)

For totally non-interacting spheres is :

$$\hat{\mathcal{O}}_0(\mathbf{r}^N) = D_0 \sum_{i=1}^N \nabla_i^2 \longrightarrow \text{(sum of) single-particle diffusion equations}$$

Irreversibility of overdamped Brownian dynamics („H-Theorem“)

$$P_{\text{eq}}(\mathbf{r}^N) = \frac{e^{-\beta U(\mathbf{r}^N)}}{\int d\mathbf{x}^N e^{-\beta U(\mathbf{x}^N)}} = \frac{e^{-\beta U(\mathbf{r}^N)}}{Z} \quad \text{equilibrium Pdf ; } U^{\text{ex}} = 0$$

Consider free-energy-type functional $A[P]$ on solution space of GSE defined by

$$A([P], t) = \int d\mathbf{r}^N P(\mathbf{r}^N, t) [k_B T \ln P + U] \longrightarrow A[P_{\text{eq}}] = -k_B T \ln Z$$

$$\begin{aligned} \frac{dA}{dt} &= \int d\mathbf{r}^N \left\{ \frac{\partial P}{\partial t} [k_B T \ln P + U] + k_B T \frac{\partial P}{\partial t} \right\} \\ \frac{dA}{dt} &= \int d\mathbf{r}^N \left\{ \sum_{i,j} \nabla_i \cdot \mathbf{D}_{ij} \cdot \underbrace{(\nabla_j P + \beta P \nabla_j U)}_{P \nabla_j \ln(P/P_{\text{eq}})} [k_B T \ln P + U] + k_B T \sum_{i,j} \nabla_i \cdot \mathbf{D}_{ij} \cdot \underbrace{(\nabla_j P + \beta P \nabla_j U)}_{P \nabla_j \ln(P/P_{\text{eq}})} \right\} \end{aligned}$$

Integrate by parts : surface terms vanish for $P = 0$ and $\text{grad } P = 0$ on system boundaries (zero flux)

$$\frac{dA}{dt} = -k_B T \int d\mathbf{r}^N P \left\{ \sum_{i,j} [\nabla_i \ln(P/P_{\text{eq}})] \cdot \mathbf{D}_{ij} \cdot [\nabla_j \ln(P/P_{\text{eq}})] \right\} < 0$$

$$\begin{aligned} \mathbf{D}_{ij} &= \mathbf{D}_{ji} \\ \sum_{i,j} \mathbf{D}_{ij} : \mathbf{f}_i^* \mathbf{f}_j &> 0 \end{aligned}$$

$A([P], t)$ decays monotonically in time until its minimum $A[P_{\text{eq}}]$ is reached where $dA/dt = 0$ ⁶⁴

More „fundamental“ derivations of GSE :

- Murphy & Aguirre, J. Chem. Phys. (1972) : from many-sphere Fokker-Planck eq.
- Roux, Physica A (1992) : from fluctuating hydrodynamics

5. Hydrodynamic mobility problem of many spheres

- **General properties of hydrodynamic interaction**
- **Method of induced forces**
- **Motion along a liquid-gas interface**

General properties of hydrodynamic interaction

- Hydrodynamic mobility tensors in GSE follow from associated creeping flow BV problem
- Quasi-stationary fluid flow for $t \gg \tau_\eta \approx \tau_B$

$$0 = -\nabla p(\mathbf{r}) + \eta_0 \nabla^2 \mathbf{u}(\mathbf{r}) = \nabla \cdot \boldsymbol{\sigma}(\mathbf{r})$$

Linear Stokes' eq.
for fluid flow field
(zero total force density)

$$\nabla \cdot \mathbf{u}(\mathbf{r}) = 0$$

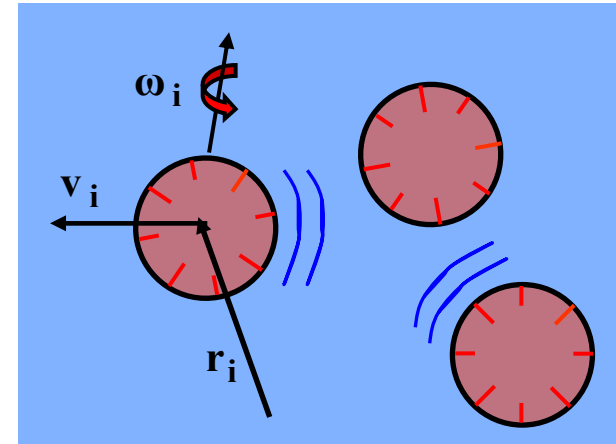
Incompressibility of fluid

$$\boldsymbol{\sigma}(\mathbf{r}) = -p(\mathbf{r}) \mathbf{1} + \eta_0 \left[\nabla \mathbf{u} + (\nabla \mathbf{u})^T \right]$$

Stress tensor

$$\mathbf{u}(\mathbf{r}) = \mathbf{v}_i + \boldsymbol{\omega}_i \times (\mathbf{r} - \mathbf{r}_i) \quad \text{for } \mathbf{r} \text{ on sphere surface } S_i \text{ (stick inner BC)}$$

$$\mathbf{u}(\mathbf{r}) \rightarrow 0, \quad |\mathbf{r}| \rightarrow \infty \quad \text{outer BC for quiescent and unbound fluid}$$



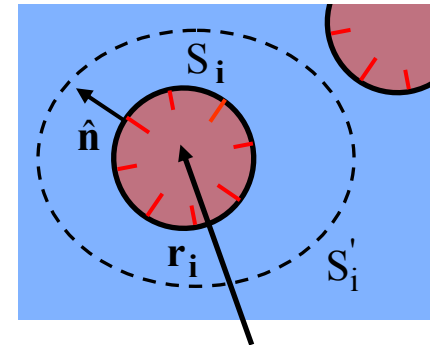
Helmholtz (1868) :

- Unique solution $\mathbf{u}(\mathbf{r})$ for given BC's on inner and outer fluid boundaries
- Stokes flow has minimal dissipation of all $\mathbf{u}(\mathbf{r})$ with $\text{div } \mathbf{u}(\mathbf{r}) = 0$

- Hydrodynamic force and torque on surface of sphere i

$$\mathbf{F}_i^H = \int_{S_i} dS \boldsymbol{\sigma}(\mathbf{r}; \mathbf{r}^N) \cdot \hat{\mathbf{n}}(\mathbf{r})$$

$$\mathbf{T}_i^H = \int_{S_i} dS (\mathbf{r} - \mathbf{r}_i) \times \boldsymbol{\sigma}(\mathbf{r}; \mathbf{r}^N) \cdot \hat{\mathbf{n}}(\mathbf{r})$$



- Forces and torques are transmitted through fluid since $\text{div } \boldsymbol{\sigma} = 0$ within fluid
- Friction problem for quiescent fluid: linearity of Stokes flow implies that :

$$\begin{pmatrix} \mathbf{F}^H \\ \mathbf{T}^H \end{pmatrix} = - \underbrace{\begin{pmatrix} \zeta^{tt}(\mathbf{X}) & \zeta^{tr}(\mathbf{X}) \\ \zeta^{rt}(\mathbf{X}) & \zeta^{rr}(\mathbf{X}) \end{pmatrix}}_{\text{3N x 3N each, depend only on X}} \cdot \begin{pmatrix} \mathbf{v} \\ \boldsymbol{\omega} \end{pmatrix}$$

← Supervector / -matrix notation :

$$\mathbf{v} = (\mathbf{v}_1, \dots, \mathbf{v}_N)^T \text{ et cetera}$$

3N x 3N each,
depend only on X

- Torque-free spheres: $\mathbf{T}^H = 0 \rightarrow$ eliminate $\boldsymbol{\omega}$ in favor of $\mathbf{v}$

$$\mathbf{F}^H = - \underbrace{\left[\zeta^{tt} - \zeta^{tr} \cdot (\zeta^{rr})^{-1} \cdot \zeta^{rt} \right]}_{=:\zeta(\mathbf{X})} \cdot \mathbf{v}$$

- Relate to inverse mobility problem since mobilities needed as input in GSE

$$\begin{pmatrix} \mathbf{v} \\ \boldsymbol{\omega} \end{pmatrix} = -\beta \begin{pmatrix} \mathbf{D}^{tt}(\mathbf{X}) & \mathbf{D}^{tr}(\mathbf{X}) \\ \mathbf{D}^{rt}(\mathbf{X}) & \mathbf{D}^{rr}(\mathbf{X}) \end{pmatrix} \cdot \begin{pmatrix} \mathbf{F}^H \\ \mathbf{T}^H = \mathbf{0} \end{pmatrix} \longrightarrow \mathbf{v} = -\beta \mathbf{D}^{tt}(\mathbf{X}) \cdot \mathbf{F}^H$$

- Solving the hydrodynamic Stokes-Einstein relation for $\mathbf{D}^{tt}$ gives

$$\underbrace{\begin{pmatrix} \zeta^{tt} & \zeta^{tr} \\ \zeta^{rt} & \zeta^{rr} \end{pmatrix}}_{\text{symmetric \& positive definite } 6N \times 6N \text{ matrices}} \cdot \underbrace{\begin{pmatrix} \mathbf{D}^{tt} & \mathbf{D}^{tr} \\ \mathbf{D}^{rt} & \mathbf{D}^{rr} \end{pmatrix}}_{\text{symmetric \& positive definite } 6N \times 6N \text{ matrices}} = k_B T \begin{pmatrix} \mathbf{1} & \mathbf{0} \\ \mathbf{0} & \mathbf{1} \end{pmatrix}$$

$$\mathbf{D}(\mathbf{X}) = \mathbf{D}^{tt}(\mathbf{X}) = k_B T \left[\zeta^{tt} - \zeta^{tr} \cdot (\zeta^{rr})^{-1} \cdot \zeta^{rt} \right]^{-1} = k_B T \boldsymbol{\zeta}(\mathbf{X})^{-1} \longrightarrow \text{GSE}$$

- Symmetry follows from Lorentz' reciprocal theorem of Stokes flow or Green-Kubo form of $\mathbf{D}$

$$\longrightarrow \quad \mathbf{D}_{ij}^{tt} = \mathbf{D}_{ji}^{tt} \quad \mathbf{D}_{ij}^{rr} = \mathbf{D}_{ji}^{rr} \quad \mathbf{D}_{ij}^{rt} = \mathbf{D}_{ji}^{tr}$$

- Without hydrodynamic interactions (very dilute system) is :

$$\mathbf{D}_{ij}^{tt} = D_0 \delta_{ij} \mathbf{1} \quad \mathbf{D}_{ij}^{rr} = \mathbf{D}_0^r \delta_{ij} \mathbf{1} \quad \mathbf{D}_{ij}^{rt} = \mathbf{0} = \mathbf{D}_{ij}^{tr}$$

$$D_0 = \frac{k_B T}{6\pi\eta_0 a}$$

$$\mathbf{F}_i^H = -6\pi\eta_0 a \mathbf{v}_i \quad (6 \rightarrow 4 : \text{perfect slip})$$

$$D_0^r = \frac{k_B T}{8\pi\eta_0 a^3}$$

$$\mathbf{T}_i^H = -8\pi\eta_0 a^3 \boldsymbol{\omega}_i \quad (8 \rightarrow 0 : \text{perfect slip})$$

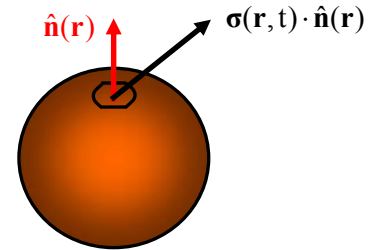
Positive definiteness of hydrodynamic mobility matrices

- Rate of heat-dissipated energy created by sphere's motion relative to fluid :

$$\frac{dE}{dt} = \sum_{i=1}^N \int_{S_i} dS \mathbf{u}(\mathbf{r}) \cdot \underbrace{[-\boldsymbol{\sigma}(\mathbf{r}) \cdot \hat{\mathbf{n}}(\mathbf{r})]}_{\text{force/area on fluid caused by surface element } dS} > 0$$

$$\mathbf{v}_i + \boldsymbol{\omega}_i \times (\mathbf{r} - \mathbf{r}_i)$$

force/area on fluid caused by surface element dS



$$\frac{dE}{dt} = - \sum_{i=1}^N \left[\mathbf{v}_i \cdot \mathbf{F}_i^H + \boldsymbol{\omega}_i \cdot \mathbf{T}_i^H \right] = (\mathbf{v}, \boldsymbol{\omega}) \cdot \begin{pmatrix} \boldsymbol{\zeta}^{tt} & \boldsymbol{\zeta}^{tr} \\ \boldsymbol{\zeta}^{rt} & \boldsymbol{\zeta}^{rr} \end{pmatrix} \cdot \begin{pmatrix} \mathbf{v} \\ \boldsymbol{\omega} \end{pmatrix} = \beta \left(\mathbf{F}^H, \mathbf{T}^H \right) \cdot \begin{pmatrix} \mathbf{D}^{tt} & \mathbf{D}^{tr} \\ \mathbf{D}^{rt} & \mathbf{D}^{rr} \end{pmatrix} \cdot \begin{pmatrix} \mathbf{F}^H \\ \mathbf{T}^H \end{pmatrix} > 0$$

- $\mathbf{v}$ and $\boldsymbol{\omega}$ can be chosen arbitrarily : $\mathbf{D}^{tt}(\mathbf{X})$ and $\mathbf{D}^{rr}(\mathbf{X})$ positive definite

- From Stokes equation follows additionally that, with : $\mathbf{e}(\mathbf{r}) = \left[\nabla \mathbf{u} + (\nabla \mathbf{u})^T \right] / 2$

$$\frac{dE}{dt} = 2\eta_0 \int_V d\mathbf{r} \mathbf{e}(\mathbf{r}) : \mathbf{e}(\mathbf{r}) = 2\eta_0 \int_V d\mathbf{r} \sum_{\alpha, \beta=1}^3 (e_{\alpha\beta})^2 > 0$$

rate of strain tensor

Point-force solution

- Find solution of Stokes eq. for a point force $\mathbf{F}$ acting on quiescent & unbound fluid at $\mathbf{r}$:

$$-\nabla p(\mathbf{r}) + \eta_0 \nabla^2 \mathbf{u}(\mathbf{r}) = -\mathbf{f}(\mathbf{r}) \quad \nabla \cdot \mathbf{u}(\mathbf{r}) = 0 \quad \mathbf{f}(\mathbf{r}) = \mathbf{F} \delta(\mathbf{r})$$

 volumetric force density
on fluid

- The solution for outer BC $\mathbf{u}(\mathbf{r} \rightarrow \infty) = 0$ and $p(\mathbf{r} \rightarrow \infty) = 0$ is :

$$p(\mathbf{r}) = \mathbf{Q}_0(\mathbf{r}) \cdot \mathbf{F} \quad \mathbf{Q}_0(\mathbf{r}) = \frac{1}{4\pi r^2} \hat{\mathbf{r}}$$

$$\mathbf{u}(\mathbf{r}) = \mathbf{T}_0(\mathbf{r}) \cdot \mathbf{F} \quad \mathbf{T}_0(\mathbf{r}) = \frac{1}{8\pi\eta_0 r} (\mathbf{1} + \hat{\mathbf{r}} \hat{\mathbf{r}})$$

 Oseen tensor

$$(\mathbf{T}_0)_{\alpha\beta}(\mathbf{r}) = \frac{1}{8\pi\eta_0 r} \left(\delta_{\alpha\beta} + \frac{x_\alpha x_\beta}{r^2} \right)$$

$$\nabla \cdot \mathbf{u}(\mathbf{r}) = 0 \Rightarrow \nabla \cdot \mathbf{T}_0(\mathbf{r}) = 0 \quad \text{including } \mathbf{r} = 0$$

- Superposition gives flow-field due to N pointlike particles at positions $\{\mathbf{r}_i\}$:

$$\mathbf{f}(\mathbf{r}') = -\sum_{i=1}^N \mathbf{F}_i^H \delta(\mathbf{r}' - \mathbf{r}_i) \quad \longrightarrow \quad \mathbf{u}(\mathbf{r}) = \int d\mathbf{r}' \mathbf{T}_0(\mathbf{r} - \mathbf{r}') \cdot \mathbf{f}(\mathbf{r}') = -\sum_{i=1}^N \mathbf{T}_0(\mathbf{r} - \mathbf{r}_i) \cdot \mathbf{F}_i^H$$

 fluid force on particle i

- Assume stick BC: particles move with same velocity as fluid in contact, i.e. $\mathbf{u}(\mathbf{r}_i) = \mathbf{v}_i$
- To avoid unphysical divergence (drawback of pointforce appr.) assume pointforce solution for particle i to describe additional velocity change due to (N - 1) particles - HI alone :

$$\mathbf{v}_i \approx \mathbf{v}_i^0 + \Delta \mathbf{v}_i^{(N-1)}$$

$$\mathbf{v}_i^0 = -\beta D_0 \mathbf{F}_i^H \quad (D_0 = \frac{k_B T}{6\pi\eta_0 a})$$

$$\Delta \mathbf{v}_i^{(N-1)} = -\sum_{l \neq i}^N \mathbf{T}_0(\mathbf{r}_i - \mathbf{r}_l) \cdot \mathbf{F}_l^H$$

assumed
to be finite

- Comparison with gen. Stokes friction law for torque-free spheres identifies mobilities as:

$$\mathbf{v}_i = -\sum_{l=1}^N \beta \mathbf{D}_{il}(\mathbf{r}^N) \cdot \mathbf{F}_l^H \quad \Rightarrow \quad \mathbf{D}_{ii}(\mathbf{r}^N) = D_0 \mathbf{1}$$

$$\mathbf{D}_{ij}(\mathbf{r}^N) = k_B T \mathbf{T}_0(\mathbf{r}_i - \mathbf{r}_j) = D_0 \frac{3a}{4r_{ij}} [\mathbf{1} + \hat{\mathbf{r}}_{ij} \hat{\mathbf{r}}_{ij}] \quad (i \neq j)$$

valid up to $O(a^2 / r^2)$

- Real justification follows from considering finite-sized spheres of radius a

Derivation of fundamental solution (Oseen tensor) for unbounded fluid

$$-\nabla p(\mathbf{r}) + \eta_0 \nabla^2 \mathbf{u}(\mathbf{r}) = -\mathbf{f}(\mathbf{r}) \quad \nabla \cdot \mathbf{u}(\mathbf{r}) = 0$$

$$\downarrow \quad \downarrow$$

$$i\mathbf{q} p(\mathbf{q}) - \eta_0 q^2 \mathbf{u}(\mathbf{q}) = -\mathbf{f}(\mathbf{q}) \quad \mathbf{q} \cdot \mathbf{u}(\mathbf{q}) = 0$$

$$i\mathbf{q} \cdot \mathbf{q} p(\mathbf{q}) - \eta_0 q^2 \underbrace{\mathbf{q} \cdot \mathbf{u}(\mathbf{q})}_{=0} = -\mathbf{q} \cdot \mathbf{f}(\mathbf{q}) \Rightarrow$$

$$p(\mathbf{q}) = i \frac{\mathbf{q} \cdot \mathbf{f}(\mathbf{q})}{q^2} \Rightarrow \mathbf{u}(\mathbf{q}) = \frac{1}{\eta_0 q^2} [\mathbf{1} - \hat{\mathbf{q}} \hat{\mathbf{q}}] \cdot \mathbf{f}(\mathbf{q}) \Rightarrow \text{use convolution theorem}$$

$$\mathbf{u}(\mathbf{q}) = \int d\mathbf{r} e^{i\mathbf{q} \cdot \mathbf{r}} \mathbf{u}(\mathbf{r}) \text{ et cetera}$$

$$\nabla \rightarrow -i\mathbf{q}$$

$$\int d\mathbf{q} e^{-i\mathbf{q} \cdot \mathbf{r}} A(\mathbf{q}) B(\mathbf{q}) =$$

$$= (2\pi)^3 \int d\mathbf{r}' A(\mathbf{r} - \mathbf{r}') B(\mathbf{r}')$$

$$\mathbf{u}(\mathbf{r}) = \int d\mathbf{r}' \mathbf{T}_0(\mathbf{r} - \mathbf{r}') \cdot \mathbf{f}(\mathbf{r}')$$

$$p(\mathbf{r}) = \int d\mathbf{r}' \mathbf{Q}_0(\mathbf{r} - \mathbf{r}') \cdot \mathbf{f}(\mathbf{r}')$$

$$\mathbf{T}_0(\mathbf{r}) = \frac{1}{(2\pi)^3} \int d\mathbf{q} e^{-i\mathbf{q} \cdot \mathbf{r}} \frac{1}{\eta_0 q^2} [\mathbf{1} - \hat{\mathbf{q}} \hat{\mathbf{q}}] = \frac{1}{8\pi\eta_0 r} [\mathbf{1} + \hat{\mathbf{r}} \hat{\mathbf{r}}]$$

$$\mathbf{Q}_0(\mathbf{r}) = \frac{1}{(2\pi)^3} \int d\mathbf{q} e^{-i\mathbf{q} \cdot \mathbf{r}} \left(i \frac{\mathbf{q}}{q^2} \right) = \frac{-1}{(2\pi)^3} \nabla_r \int d\mathbf{q} e^{-i\mathbf{q} \cdot \mathbf{r}} \frac{1}{q^2} = \frac{1}{4\pi r^3} \mathbf{r}$$

Point-force solution

- Find solution of Stokes eq. for a point force $\mathbf{F}$ acting on quiescent & unbound fluid at $\mathbf{r}$:

$$-\nabla p(\mathbf{r}) + \eta_0 \nabla^2 \mathbf{u}(\mathbf{r}) = -\mathbf{f}(\mathbf{r}) \quad \nabla \cdot \mathbf{u}(\mathbf{r}) = 0 \quad \mathbf{f}(\mathbf{r}) = \mathbf{F} \delta(\mathbf{r})$$

↑
volumetric force density
on fluid

- The solution for outer BC $\mathbf{u}(\mathbf{r} \rightarrow \infty) = 0$ and $p(\mathbf{r} \rightarrow \infty) = 0$ is :

$$p(\mathbf{r}) = \mathbf{Q}_0(\mathbf{r}) \cdot \mathbf{F} \quad \mathbf{Q}_0(\mathbf{r}) = \frac{1}{4\pi r^2} \hat{\mathbf{r}}$$

$$\mathbf{u}(\mathbf{r}) = \mathbf{T}_0(\mathbf{r}) \cdot \mathbf{F} \quad \mathbf{T}_0(\mathbf{r}) = \frac{1}{8\pi\eta_0 r} (\mathbf{1} + \hat{\mathbf{r}} \hat{\mathbf{r}})$$

↑
Oseen tensor

$$(\mathbf{T}_0)_{\alpha\beta}(\mathbf{r}) = \frac{1}{8\pi\eta_0 r} \left(\delta_{\alpha\beta} + \frac{x_\alpha x_\beta}{r^2} \right)$$

$$\nabla \cdot \mathbf{u}(\mathbf{r}) = 0 \Rightarrow \nabla \cdot \mathbf{T}_0(\mathbf{r}) = 0 \quad \text{including } \mathbf{r} = 0$$

- Superposition gives flow-field due to N pointlike particles at positions $\{\mathbf{r}_i\}$:

$$\mathbf{f}(\mathbf{r}') = -\sum_{i=1}^N \mathbf{F}_i^H \delta(\mathbf{r}' - \mathbf{r}_i) \quad \longrightarrow \quad \mathbf{u}(\mathbf{r}) = \int d\mathbf{r}' \mathbf{T}_0(\mathbf{r} - \mathbf{r}') \cdot \mathbf{f}(\mathbf{r}') = -\sum_{i=1}^N \mathbf{T}_0(\mathbf{r} - \mathbf{r}_i) \cdot \mathbf{F}_i^H$$

↑
fluid force on particle i

- Assume stick BC: particles move with same velocity as fluid in contact, i.e. $\mathbf{u}(\mathbf{r}_i) = \mathbf{v}_i$
- To avoid unphysical divergence (drawback of pointforce appr.) assume pointforce solution for particle i to describe additional velocity change due to $(N - 1)$ particles - HI alone :

$$\mathbf{v}_i \approx \mathbf{v}_i^0 + \Delta \mathbf{v}_i^{(N-1)}$$

$$\mathbf{v}_i^0 = -\beta D_0 \mathbf{F}_i^H \quad \left(D_0 = \frac{k_B T}{6\pi\eta_0 a} \right)$$

$$\Delta \mathbf{v}_i^{(N-1)} = -\sum_{l \neq i}^N \mathbf{T}_0(\mathbf{r}_i - \mathbf{r}_l) \cdot \mathbf{F}_l^H$$

assumed
to be finite

- Comparison with gen. Stokes friction law for torque-free spheres identifies mobilities as:

$$\mathbf{v}_i = -\sum_{l=1}^N \beta \mathbf{D}_{il}(\mathbf{r}^N) \cdot \mathbf{F}_l^H \quad \Rightarrow \quad \mathbf{D}_{ii}(\mathbf{r}^N) = D_0 \mathbf{1}$$

$$\mathbf{D}_{ij}(\mathbf{r}^N) = k_B T \mathbf{T}_0(\mathbf{r}_i - \mathbf{r}_j) = D_0 \frac{3a}{4r_{ij}} [\mathbf{1} + \hat{\mathbf{r}}_{ij} \hat{\mathbf{r}}_{ij}] \quad (i \neq j)$$

valid up to $O(a^2 / r^2)$

- Real justification follows from considering finite-sized spheres of radius a

Derivation of fundamental solution (Oseen tensor) for unbounded fluid

$$-\nabla p(\mathbf{r}) + \eta_0 \nabla^2 \mathbf{u}(\mathbf{r}) = -\mathbf{f}(\mathbf{r}) \quad \nabla \cdot \mathbf{u}(\mathbf{r}) = 0$$

$$\downarrow \quad \downarrow$$

$$i\mathbf{q} p(\mathbf{q}) - \eta_0 q^2 \mathbf{u}(\mathbf{q}) = -\mathbf{f}(\mathbf{q}) \quad \mathbf{q} \cdot \mathbf{u}(\mathbf{q}) = 0$$

$$i\mathbf{q} \cdot \mathbf{q} p(\mathbf{q}) - \eta_0 q^2 \underbrace{\mathbf{q} \cdot \mathbf{u}(\mathbf{q})}_{=0} = -\mathbf{q} \cdot \mathbf{f}(\mathbf{q}) \Rightarrow$$

$$p(\mathbf{q}) = i \frac{\mathbf{q} \cdot \mathbf{f}(\mathbf{q})}{q^2} \Rightarrow \mathbf{u}(\mathbf{q}) = \frac{1}{\eta_0 q^2} [\mathbf{1} - \hat{\mathbf{q}} \hat{\mathbf{q}}] \cdot \mathbf{f}(\mathbf{q}) \Rightarrow \text{use convolution theorem}$$

$$\mathbf{u}(\mathbf{q}) = \int d\mathbf{r} e^{i\mathbf{q} \cdot \mathbf{r}} \mathbf{u}(\mathbf{r}) \text{ et cetera}$$

$$\nabla \rightarrow -i\mathbf{q}$$

$$\int d\mathbf{q} e^{-i\mathbf{q} \cdot \mathbf{r}} A(\mathbf{q}) B(\mathbf{q}) =$$

$$= (2\pi)^3 \int d\mathbf{r}' A(\mathbf{r} - \mathbf{r}') B(\mathbf{r}')$$

$$\mathbf{u}(\mathbf{r}) = \int d\mathbf{r}' \mathbf{T}_0(\mathbf{r} - \mathbf{r}') \cdot \mathbf{f}(\mathbf{r}')$$

$$p(\mathbf{r}) = \int d\mathbf{r}' \mathbf{Q}_0(\mathbf{r} - \mathbf{r}') \cdot \mathbf{f}(\mathbf{r}')$$

$$\mathbf{T}_0(\mathbf{r}) = \frac{1}{(2\pi)^3} \int d\mathbf{q} e^{-i\mathbf{q} \cdot \mathbf{r}} \frac{1}{\eta_0 q^2} [\mathbf{1} - \hat{\mathbf{q}} \hat{\mathbf{q}}] = \frac{1}{8\pi\eta_0 r} [\mathbf{1} + \hat{\mathbf{r}} \hat{\mathbf{r}}]$$

$$\mathbf{Q}_0(\mathbf{r}) = \frac{1}{(2\pi)^3} \int d\mathbf{q} e^{-i\mathbf{q} \cdot \mathbf{r}} \left(i \frac{\mathbf{q}}{q^2} \right) = \frac{-1}{(2\pi)^3} \nabla_r \int d\mathbf{q} e^{-i\mathbf{q} \cdot \mathbf{r}} \frac{1}{q^2} = \frac{1}{4\pi r^3} \mathbf{r}$$

- have employed that :

$$\int d\mathbf{q} = \int_0^\infty dq q^2 \int_{4\pi} d\Omega_q$$

$$\int d\Omega_q e^{\pm i\mathbf{q}\cdot\mathbf{r}} \mathbf{1} = 4\pi j_0(qr) \mathbf{1}$$

$$\int d\Omega_q e^{\pm i\mathbf{q}\cdot\mathbf{r}} \hat{\mathbf{q}} \hat{\mathbf{q}} = 4\pi \left[\frac{j_1(qr)}{qr} \mathbf{1} - j_2(qr) \hat{\mathbf{r}} \hat{\mathbf{r}} \right]$$

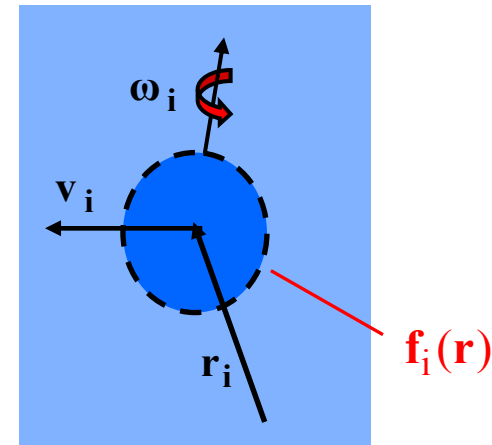
$$j_2(x) = \frac{3j_1(x)}{x} - j_0(x)$$

Method of induced forces

- Replace spheres by fluid in rigid-body motion according to stick inner BCs
- Introduce config.-dependent induced force densities on fluid which enforce BCs
- BV problem identical to original one outside of spheres
- Assume incident flow field $\mathbf{u}_0$ (non-quiescent unbound fluid)

$$\mathbf{f}(\mathbf{r}; \mathbf{X}) = \sum_{i=1}^N \mathbf{f}_i(\mathbf{r}) \quad \mathbf{f}_i(\mathbf{r}) = -\delta(|\mathbf{r} - \mathbf{r}_i| - a^+) \boldsymbol{\sigma}(\mathbf{r}; \mathbf{X}) \cdot \hat{\mathbf{n}}(\mathbf{r})$$

$$\mathbf{u}(\mathbf{r}) - \mathbf{u}_0(\mathbf{r}) = \int_{V_i^+} d\mathbf{r}' \mathbf{T}_0(\mathbf{r} - \mathbf{r}') \cdot \mathbf{f}_i(\mathbf{r}') + \sum_{l \neq i} \int_{V_l^+} d\mathbf{r}' \mathbf{T}_0(\mathbf{r} - \mathbf{r}') \cdot \mathbf{f}_l(\mathbf{r}')$$



$$\mathbf{u}(\mathbf{r}) = \mathbf{v}_i + \boldsymbol{\omega}_i \times (\mathbf{r} - \mathbf{r}_i) \quad (\text{inside sphere } i)$$

$$\mathbf{u}(\mathbf{r} \rightarrow \infty) = \mathbf{u}_0(\mathbf{r})$$

incident flow due to infinite
distant forces / boundaries

$$-\nabla p_0(\mathbf{r}) + \eta_0 \nabla^2 \mathbf{u}_0(\mathbf{r}) = 0 \quad \nabla \cdot \mathbf{u}_0(\mathbf{r}) = 0 \quad (\text{homog. Stokes eq.}) \Rightarrow \Delta p_0(\mathbf{r}) = 0$$

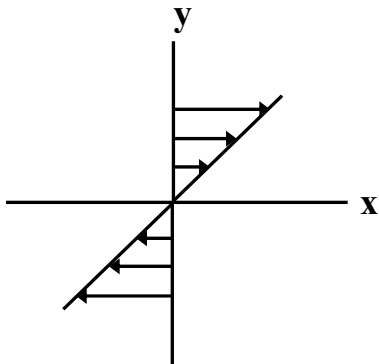
$$\Rightarrow \nabla^2 \nabla^2 \mathbf{u}_0(\mathbf{r}) = 0 \quad (\text{bi-harmonic} \rightarrow \text{mean value property})$$

Important example : simple linear shear flow

$$\mathbf{u}_0(\mathbf{r}) = \dot{\gamma} \mathbf{\Gamma} \cdot \mathbf{r} = \dot{\gamma} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \boldsymbol{\omega}_0 \times \mathbf{r} + \mathbf{e}_0 : \mathbf{r}$$

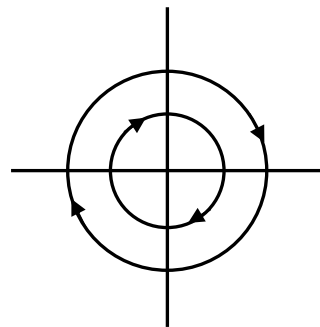
$$\boldsymbol{\omega}_0(\mathbf{r}) = \frac{1}{2} \nabla \times \mathbf{u}_0(\mathbf{r}) = \frac{1}{2} \dot{\gamma} \boldsymbol{\varepsilon} : \mathbf{\Gamma} = -\frac{1}{2} \dot{\gamma} \hat{\mathbf{z}}$$

$$\mathbf{e}_0(\mathbf{r}) = \frac{1}{2} \left[(\nabla \mathbf{u}_0)(\mathbf{r}) + (\nabla \mathbf{u}_0)^T(\mathbf{r}) \right] - \frac{1}{3} \text{Tr}(\nabla \mathbf{u}_0(\mathbf{r})) = \frac{1}{2} \dot{\gamma} [\mathbf{\Gamma} + \mathbf{\Gamma}^T]$$



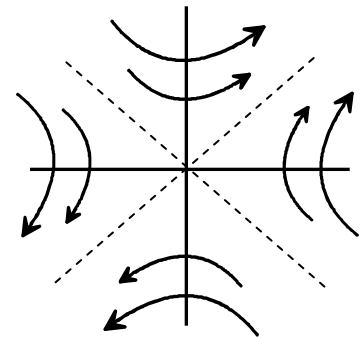
(Simple shear flow)

=



(Pure rotation)

+



(Extensional flow)

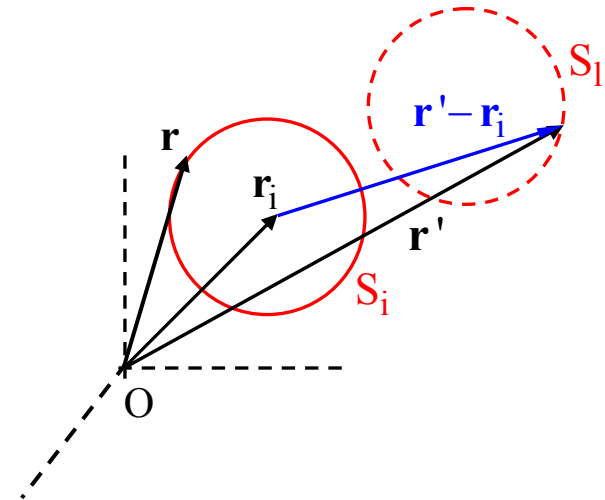
Mean-value property of bi-harmonic functions

$$\nabla \cdot \mathbf{u}_0(\mathbf{x}) = 0 \quad \nabla^2 \nabla^2 \mathbf{u}_0(\mathbf{x}) = 0$$

$$\nabla \cdot \mathbf{T}_0(\mathbf{x}) = 0 \quad \nabla^2 \nabla^2 \mathbf{T}_0(\mathbf{x}) = 0 \quad (\text{all } \mathbf{x})$$

$$\langle \mathbf{u}_0(\mathbf{r}) \rangle_{S_i} \equiv \frac{1}{4\pi a^2} \int_{S_i} dS \mathbf{u}_0(\mathbf{r}) = \mathbf{u}_0(\mathbf{r}_i) + \frac{a^2}{6} (\nabla^2 \mathbf{u}_0)(\mathbf{r}_i)$$

$$\frac{1}{4\pi a^2} \int_{S_i} dS \mathbf{T}_0(\mathbf{r} - \mathbf{r}') = \begin{cases} \left(\mathbf{1} + \frac{a^2}{6} \nabla^2 \right) \mathbf{T}_0(\mathbf{r}' - \mathbf{r}_i) & |\mathbf{r}' - \mathbf{r}_i| \geq a \\ \frac{1}{6\pi\eta_0 a} \mathbf{1} & |\mathbf{r}' - \mathbf{r}_i| \leq a \end{cases}$$



„Proof“ of mean-value theorem by Taylor expansion around center of sphere i :

$$\mathbf{u}_0(\mathbf{r}) = \sum_{n=0}^{\infty} \frac{(\mathbf{r} - \mathbf{r}_i)^n \odot \nabla^n}{n!} \mathbf{u}_0(\mathbf{r}) \Big|_{\mathbf{r}=\mathbf{r}_i} = \mathbf{u}_0(\mathbf{r}_i) + (\mathbf{r} - \mathbf{r}_i) \cdot \nabla \mathbf{u}_0(\mathbf{r}_i) + \frac{1}{2} (\mathbf{r} - \mathbf{r}_i)(\mathbf{r} - \mathbf{r}_i) : \nabla \nabla \mathbf{u}_0(\mathbf{r}_i) + \dots$$

$$\nabla^2 \nabla^2 \mathbf{u}_0 = 0 \quad \nabla \cdot \mathbf{u}_0 = 0$$

$$\int_{\mathbf{x}=\mathbf{a}} dS \underbrace{\mathbf{x} \dots \mathbf{x} \mathbf{x}}_{\text{odd factors}} = 0 \quad \text{since odd integrands } (\mathbf{x} = \mathbf{r} - \mathbf{r}_i)$$



$$\int_{S_i} dS \mathbf{u}_0(\mathbf{r}) = 4\pi a^2 \mathbf{u}_0(\mathbf{r}_i) + 0 + \underbrace{\left(\frac{1}{2} \int_{S_i} dS \mathbf{x} \mathbf{x} \right)}_{\frac{4\pi}{6} a^4 \mathbf{1}} : \nabla \nabla \mathbf{u}_0(\mathbf{r}_i) + 0$$

$$\int_{S_i} dS \mathbf{u}_0(\mathbf{r}) = 4\pi a^2 \left(\mathbf{1} + \frac{a^2}{6} \nabla^2 \right) \mathbf{u}_0(\mathbf{r}_i)$$

- Integrate induced-force eq. over surface of singled out sphere i w/r to $\mathbf{r}$

- Use mean-value properties and :
$$\int_{S_i^+} dS \mathbf{u}(\mathbf{r}) = \int_{S_i^+} dS [\mathbf{v}_i + \boldsymbol{\omega} \times (\mathbf{r} - \mathbf{r}_i)] = 4\pi a^2 \mathbf{v}_i$$

$$\mathbf{F}_i^H = - \int_{V_i^+} d\mathbf{r}' \mathbf{f}_i(\mathbf{r}')$$

- Leads to exact result for hydrodynamic force on sphere i :

$$\mathbf{F}_i^H = -6\pi\eta_0 a \left[\mathbf{v}_i - \left(\mathbf{1} + \frac{a^2}{6} \nabla_i^2 \right) (\mathbf{u}_{N-1}(\mathbf{r}_i; \mathbf{X}) + \mathbf{u}_0(\mathbf{r}_i)) \right]$$

generalized translational
Faxén law (stick BC)

$$\mathbf{u}_{N-1}(\mathbf{r}_i; \mathbf{X}) = \sum_{l \neq i}^N \int_{V_l^+} d\mathbf{r}' \mathbf{T}_0(\mathbf{r} - \mathbf{r}') \cdot \mathbf{f}_l(\mathbf{r}', \mathbf{X})$$

Flow part due to N -1 spheres except sphere i
But: $\mathbf{f}_i$ fullfills full N - sphere stick BCs

Applications of generalized Faxén law

$$\mathbf{F}_i^H = -6\pi\eta_0 a \left[\mathbf{v}_i - \left(\mathbf{1} + \frac{a^2}{6} \nabla^2 \right) \mathbf{u}_0(\mathbf{r} = \mathbf{r}_i) \right]$$

- Single-sphere Faxén law
- Stokes friction law when $\mathbf{u}_0 = 0$

$$\mathbf{f}_i(\mathbf{r}; \mathbf{X}) \rightarrow -\mathbf{F}_i^H \delta(\mathbf{r} - \mathbf{r}_i) \quad 6\pi\eta_0 a \rightarrow \zeta_0$$

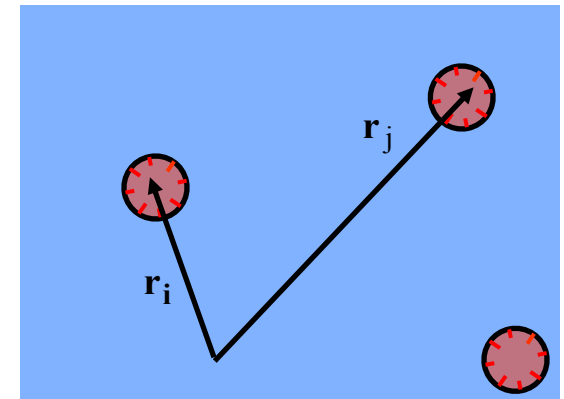
$$\mathbf{v}_i - \mathbf{u}_0(\mathbf{r}_i) = -\frac{1}{\zeta_0} \mathbf{F}_i^H - \sum_{l \neq i}^N \mathbf{T}_0(\mathbf{r}_i - \mathbf{r}_l) \cdot \mathbf{F}_l^H$$

- Point-particle limit with incident flow

- Dilute suspension where : $|\mathbf{r}_i - \mathbf{r}_j| \gg a$, $\mathbf{f}_l(\mathbf{r}') \rightarrow -\mathbf{F}_l^H / V_{sp}$

Expand $\mathbf{T}_0(\mathbf{r}' - \mathbf{r}_i)$ around $|\mathbf{r}_l - \mathbf{r}_i|$ to leading order

Use that :
$$\nabla^2 \mathbf{T}_0(\mathbf{r}) = \frac{1}{4\pi\eta_0 r^3} [1 - 3\hat{\mathbf{r}}\hat{\mathbf{r}}]$$



leads to Rotne – Prager approximation for t - t mobilities :

$$\mathbf{v}_i - \langle \mathbf{u}_0(\mathbf{r}) \rangle_{S_i} = -\beta \sum_{l=1}^N \underbrace{D_0 \{ \mathbf{1} \delta_{il} + (1 - \delta_{il}) \mathbf{T}_{RP}(\mathbf{r}_l - \mathbf{r}_i) \}}_{\mathbf{D}_{il}(\mathbf{r}^N) \approx \mathbf{D}_{il}^{RP}(\mathbf{r}_{il})} \cdot \mathbf{F}_l^H$$

$$\mathbf{D}_{il}(\mathbf{r}^N) \approx \mathbf{D}_{il}^{RP}(\mathbf{r}_{il})$$

$$\mathbf{T}_{RP}(\mathbf{r}) = \zeta_0 \left(\mathbf{1} + 2 \cdot \frac{a^2}{6} \nabla^2 \right) \mathbf{T}_0(\mathbf{r}) = \frac{3}{4} \left(\frac{a}{r} \right) (\mathbf{1} + \hat{\mathbf{r}} \hat{\mathbf{r}}) + \frac{1}{2} \left(\frac{a}{r} \right)^3 (\mathbf{1} - 3 \hat{\mathbf{r}} \hat{\mathbf{r}})$$

Note that in Rotne – Prager approximation is :

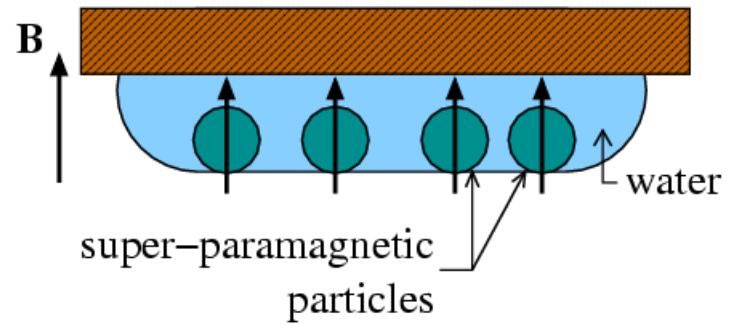
- HI pairwise additive
- Neglect of reflections

$$\nabla_i \cdot \mathbf{D}_{RP}(\mathbf{r}_{il}) = 0$$



Multipole expansions including reflections & more-body HI

Motion along a liquid-gas interface

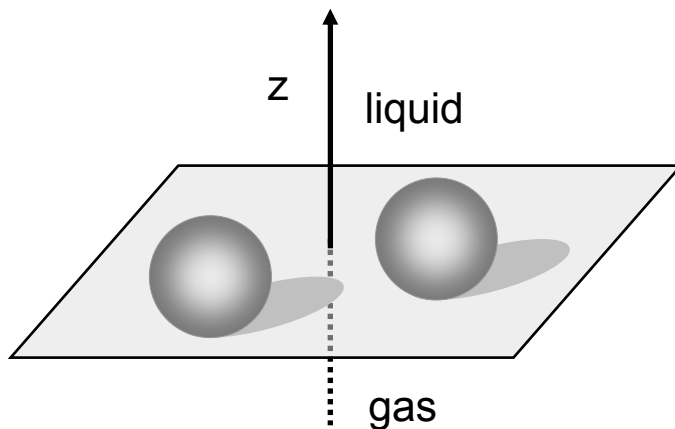


Calculation of hydrodynamic quasi-2D mobilities :

- assume ideally flat and thin interface (valid to very good accuracy)
- spheres touch interface in single point; only lateral motion
- creeping flow :

$$\eta_0 \Delta \mathbf{u}(\mathbf{r}) - \nabla p(\mathbf{r}) = 0, \quad \nabla \cdot \mathbf{u}(\mathbf{r}) = 0 \quad (\mathbf{r} \in V_{\text{liq}})$$

$$\mathbf{u}(\mathbf{r}) = \mathbf{V}_i + \boldsymbol{\Omega}_i \times (\mathbf{r} - \mathbf{r}_i), \quad (\mathbf{r} \in S_i, \text{ stick BC})$$



Free surface BC's :

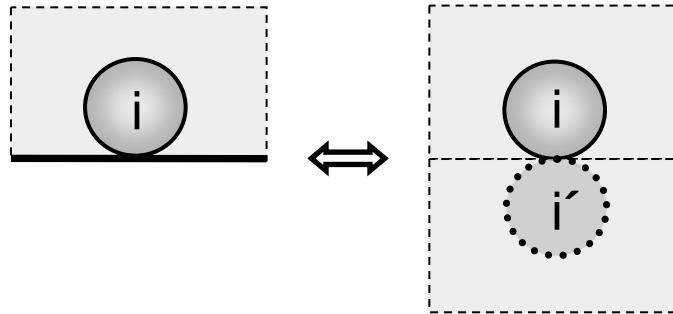
$$u_z(\mathbf{r})|_{z=0} = 0$$

$$\boldsymbol{\sigma}_{xz}(\mathbf{r})|_{z=0} = 0 = \boldsymbol{\sigma}_{yz}(\mathbf{r})|_{z=0}$$

(zero tangential stress)

- Free surface BC's accounted for by method of images

real:
N-sphere system



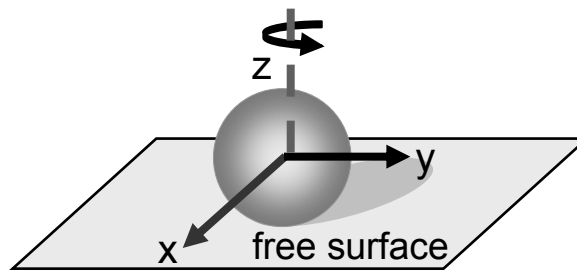
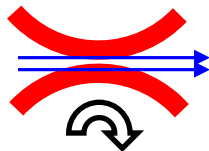
fictitious:
unbounded 2N-sphere system

$$\mathbf{u}(\mathbf{r}) - \mathbf{u}_0(\mathbf{r}) = \sum_{j=1}^N \int d\bar{\mathbf{r}} \left\{ \mathbf{T}_0(\mathbf{r} - \bar{\mathbf{r}}) + \mathbf{T}_0(\mathbf{r} - \bar{\mathbf{r}}') \cdot (1 - 2\hat{\mathbf{z}}\hat{\mathbf{z}}) \right\} \cdot \mathbf{f}_j(\bar{\mathbf{r}})$$

incident flow (+ reflection) 3D Oseen tensor reflection at $z=0$ force density on S_j

- Only 3 degrees of freedom due to lubrication

$$\begin{aligned} V_{iz} &= 0 \\ \Omega_{ix} &= \Omega_{iy} = 0 \end{aligned}$$



$$\begin{pmatrix} V_{1x} \\ V_{1y} \\ \Omega_{1z} \\ \vdots \\ V_{Nx} \\ V_{Ny} \\ \Omega_{Nz} \end{pmatrix} = \boldsymbol{\mu} \cdot \begin{pmatrix} F_{1x} \\ F_{1y} \\ T_{1z} \\ \vdots \\ F_{Nx} \\ F_{Ny} \\ T_{Nz} \end{pmatrix}$$

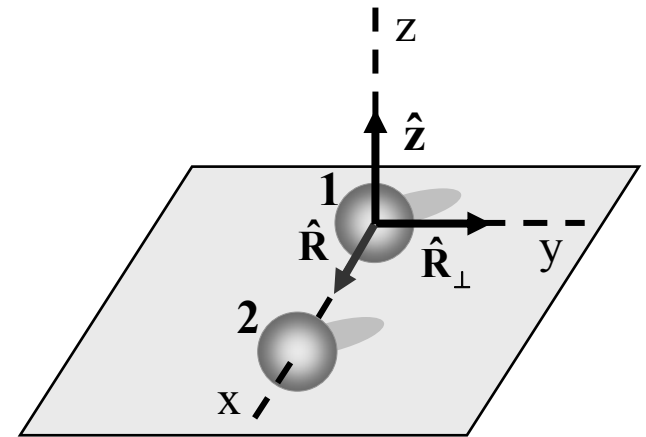
$\boldsymbol{\mu}$: N-sphere quasi-2D mobility

- Construct μ in form of multiple scattering series
- Use symmetry-adjusted multipole functions for spheres + images
 - numerical results for $N > 2$ spheres using truncated multipole expansions
 - analytic results for widely separated spheres

- Form of quasi-2D mobilities for two spheres :

$$\begin{pmatrix} V_{1L} \\ V_{1T} \end{pmatrix} = \mu_{11}^{tt} \begin{pmatrix} F_{1L} \\ F_{1T} \end{pmatrix} + \mu_{12}^{tt} \begin{pmatrix} F_{2L} \\ F_{2T} \end{pmatrix} + \mu_{11}^{tr} T_{1z} + \mu_{12}^{tr} T_{2z}$$

$$\Omega_{1z} = \mu_{11}^{rt} \begin{pmatrix} F_{1L} \\ F_{1T} \end{pmatrix} + \mu_{12}^{rt} \begin{pmatrix} F_{2L} \\ F_{2T} \end{pmatrix} + \mu_{11}^{rr} T_{1z} + \mu_{12}^{rr} T_{2z}$$



self mobilities: 1-1

distinct mobilities: 1-2

Longitudinal (x - x): $\parallel \hat{\mathbf{R}} = (\mathbf{r}_2 - \mathbf{r}_1) / r$

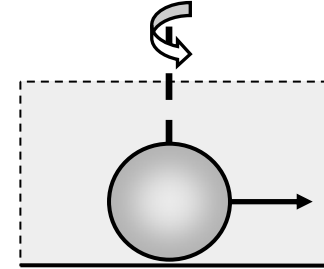
Transversal (y - y): $\parallel \hat{\mathbf{R}}_{\perp} = \hat{\mathbf{z}} \times \hat{\mathbf{R}}$

- Self-mobilities for $R = r/(2a) \gg 1$

$$\mu_{11}^{tt} = \frac{1}{6\pi\eta_0 a} \begin{pmatrix} 1.3799544... & 0 \\ 0 & 1.3799544... \end{pmatrix} + o(1/R^3)$$

$$\mu_{11}^{rr} = \frac{1.10920983...}{8\pi\eta_0 a^3} + o(1/R^3)$$

$$D_0^{r,2D} \approx 1.11 D_0^{r,3D}$$



$$D_0^{t,2D} \approx 1.38 D_0^{t,3D}$$

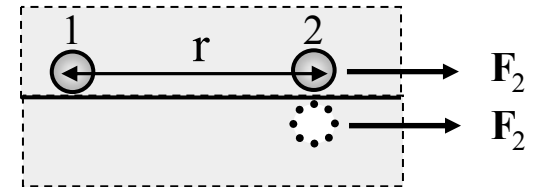
- Distinct mobilities for $R \gg 1$

Q-2D :

$$\mu_{12}^{tt} = \frac{1}{6\pi\eta_0 a} \left[\frac{1}{R} \begin{pmatrix} 3/2 & 0 \\ 0 & 3/4 \end{pmatrix} - \frac{1}{R^3} \begin{pmatrix} 1.159862... & 0 \\ 0 & 0.111686... \end{pmatrix} \right] + o(1/R^3)$$

3D :

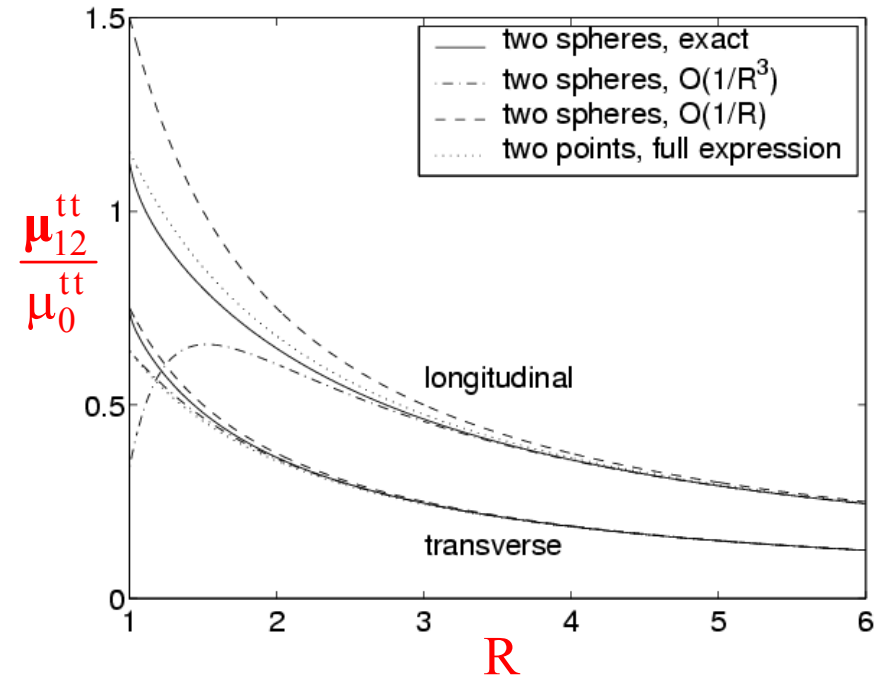
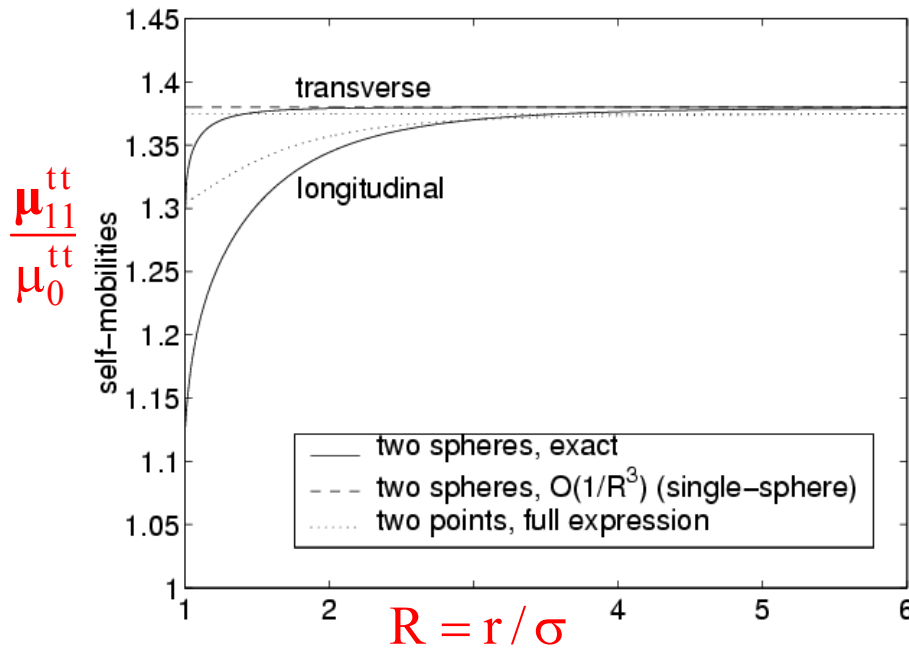
$$(\mu_{12}^{tt})_{RP}^{3D} = \frac{1}{6\pi\eta_0 a} \left[\frac{1}{R} \begin{pmatrix} 3/4 & 0 \\ 0 & 3/8 \end{pmatrix} - \frac{1}{R^3} \begin{pmatrix} 1/8 & 0 \\ 0 & -1/16 \end{pmatrix} \right]$$



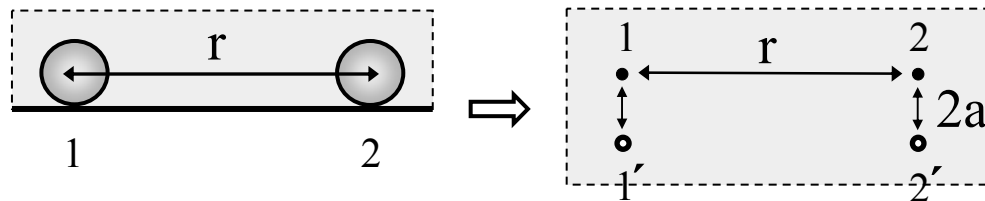
$$\mu_{12}^{tr} = \frac{\mu_0^{rt}}{4R^2} \begin{pmatrix} 0 \\ -1 \end{pmatrix} + o(1/R^3) , \quad \mu_{12}^{rr} = -\frac{\mu_0^{rr}}{8R^3} + o(1/R^3) , \quad \mu_0^{rt} = (4\pi\eta_0 a^2)^{-1}$$

$$\mu_{11}^{tr} = o(1/R^3) ,$$

Accuracy of long-distance approximations for 2-sphere mobilities



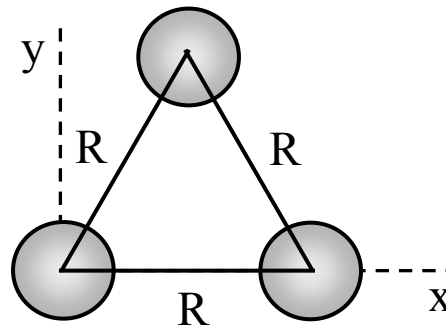
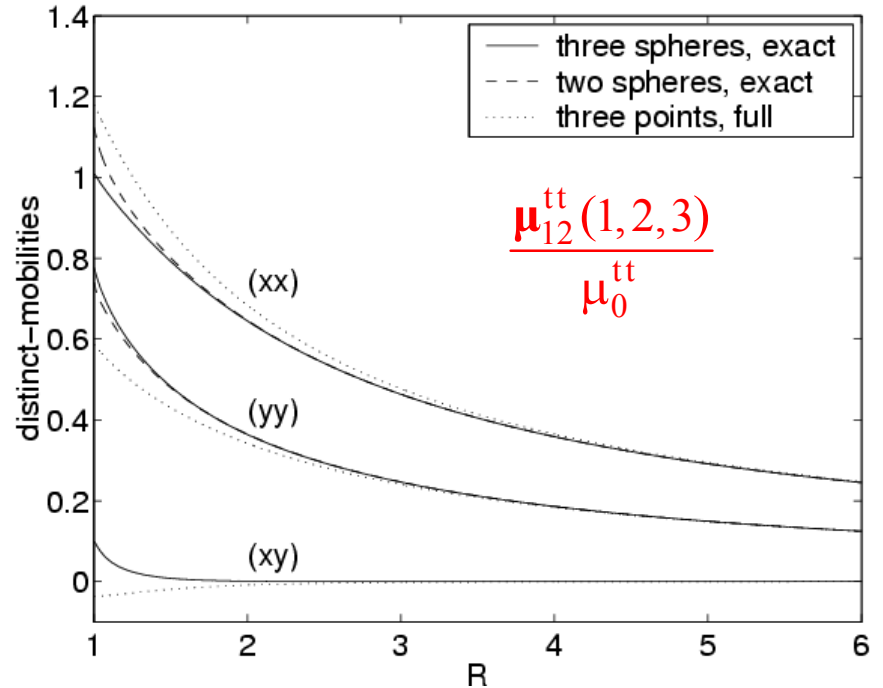
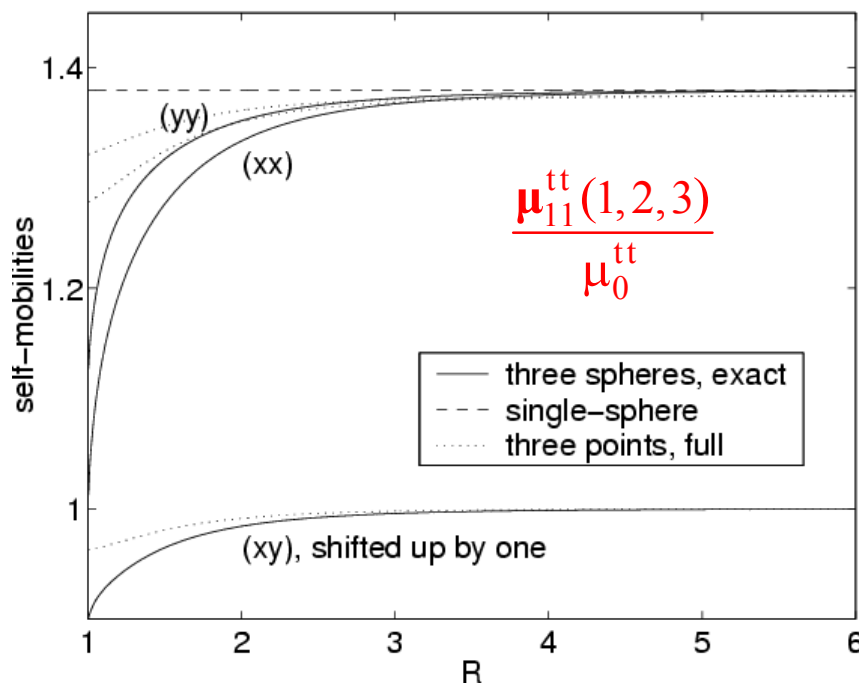
- Include also results from point-particle model (PPM)



$$\text{dist}(\mathbf{p} - \mathbf{p}') = 2a = \sigma$$

- PPM not pairwise additive for $N > 2$ due to vertical constraint forces

3-body mobilities for equilateral triangle



- $o(R^{-3})$ asymptotic form works well for $R = r/(2a) \geq 2.5$

Particles at free planar interface :

- quasi-2D mobilities salient input to simulation and theory
- experimental test of rotational constraints ?

6. Basic properties of Smoluchowski dynamics

- **Fundamental solution and time correlation functions**
- **Backward operator and eigenfunction expansion**
- **Brownian dynamics simulations**
- **Projection operators and memory equations**

Fundamental solution and time correlation functions

$$\frac{\partial}{\partial t} P(\mathbf{r}^N, t) = \hat{O}(\mathbf{r}^N) P(\mathbf{r}^N, t)$$

$$\int d\mathbf{r}^N P(\mathbf{r}^N, t) = 1$$

$$\begin{aligned} \hat{O}(\mathbf{r}^N) &= \sum_{i,j=1}^N \nabla_i \cdot \mathbf{D}_{ij} \cdot \left[\nabla_j - \beta (\mathbf{F}_j^p + \mathbf{F}_j^{\text{ex}}) \right] \\ &= \nabla \cdot \mathbf{D}(\mathbf{X}) \cdot \left[\nabla - \beta \mathbf{F}^T(\mathbf{X}) \right] \end{aligned}$$

real operator

- Conditional Pdf $P(\mathbf{r}^N, t | \mathbf{r}_0^N, 0)$ of finding config. $\mathbf{r}^N$ at t given system was earlier in $\mathbf{r}_0^N$ at $t=0$:

$$P(\mathbf{r}^N, t=0 | \mathbf{r}_0^N, 0) = \delta(\mathbf{r}^N - \mathbf{r}_0^N) \quad \text{system is with probability 1 in config. } \mathbf{r}_0^N \text{ at } t=0$$

$$P(\mathbf{r}^N, t | \mathbf{r}_0^N, 0) = e^{\hat{O}(\mathbf{r}^N)t} \delta(\mathbf{r}^N - \mathbf{r}_0^N) = \left[1 + t\hat{O} + \frac{t^2}{2}\hat{O}^2 + \dots \right] \delta(\mathbf{r}^N - \mathbf{r}_0^N) \quad \text{formal solution}$$

$$P(\mathbf{r}^N, t; \mathbf{r}_0^N, 0) = P(\mathbf{r}^N, t | \mathbf{r}_0^N, 0) P_{\text{in}}(\mathbf{r}_0^N) \quad \text{joint Pdf for system in } \mathbf{r}^N \text{ at } t \text{ and } \mathbf{r}_0^N \text{ at } t=0$$

- Knowledge of conditional & initial Pdf suffice to determine all relevant dynamic properties
- Example : equilibrium MSD for $P_{\text{in}}(\mathbf{r}^N) = P_{\text{eq}}(\mathbf{r}^N)$

$$\langle [\mathbf{r}_i(t) - \mathbf{r}_i(0)]^2 \rangle = \int d\mathbf{r}^N \int d\mathbf{r}_0^N P(\mathbf{r}^N, t | \mathbf{r}_0^N, 0) P_{\text{eq}}(\mathbf{r}_0^N) [\mathbf{r}_i - \mathbf{r}_{i0}]^2$$

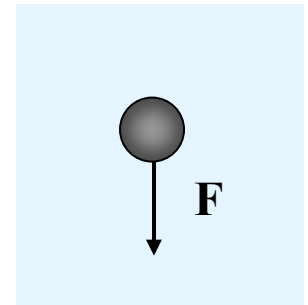
Example: fundamental solution for single particle under constant external force

$$\frac{\partial}{\partial t} P_1(\mathbf{r}, t) = D_0 \nabla^2 P_1(\mathbf{r}, t) - \beta D_0 \mathbf{F} \cdot \nabla P_1(\mathbf{r}, t) \quad (\text{unbound quiescent fluid})$$

$$P_1(\mathbf{r}, t | \mathbf{r}_0, 0) = (4\pi D_0 t)^{-3/2} \exp \left\{ -\frac{(\mathbf{r} - \mathbf{r}_0 - \beta D_0 \mathbf{F} t)^2}{4 D_0 t} \right\} \quad P_1(\mathbf{r}, 0 | \mathbf{r}_0, 0) = \delta(\mathbf{r} - \mathbf{r}_0)$$

$$\langle \mathbf{r}(t) - \mathbf{r}(0) \rangle = (\beta D_0 \mathbf{F}) t$$

$$\langle (\mathbf{r}(t) - \mathbf{r}(0))^2 \rangle = 6 D_0 t + (\beta D_0 \mathbf{F})^2 t^2$$



- Uniform diffusion in co-moving system with drift velocity $\beta D_0 \mathbf{F}$
- $P_1^{\text{eq}}(\mathbf{r}) = P_1(\mathbf{r}, t \rightarrow \infty) = V^{-1}$

- Equilibrium time correlation function of two configurational functions $A(X)$ and $B(X)$:

$$C_{AB}(t) = \left\langle A^*(\mathbf{r}^N(t)) B(\mathbf{r}^N(0)) \right\rangle := \int d\mathbf{r}^N \int d\mathbf{r}_0^N A^*(\mathbf{r}^N) B(\mathbf{r}_0^N) P(\mathbf{r}^N, t | \mathbf{r}_0^N, 0) P_{eq}(\mathbf{r}_0^N)$$

- Very often: A is Fourier component of a conserved density variable

$$A = A_{\mathbf{q}} \propto \int d\mathbf{r} e^{i\mathbf{q} \cdot \mathbf{r}} a(\mathbf{r}; X) \quad a(\mathbf{r}; X) = \sum_{j=1}^N a_j \delta(\mathbf{r} - \mathbf{r}_j)$$

$$A_{\mathbf{q}} = c_{\mathbf{q}} \equiv \frac{1}{\sqrt{N}} \sum_{l=1}^N e^{i\mathbf{q} \cdot \mathbf{r}_l} - \sqrt{N} \delta_{\mathbf{q},0}$$

$$A_{\mathbf{q}} = a_{\mathbf{q}} \equiv e^{i\mathbf{q} \cdot \mathbf{r}_1} - \delta_{\mathbf{q},0}$$

conserved property

$a_j = 1$: collective diffusion

$a_j = \delta_{j1}$: self-diffusion of 1

$$S(q, t) = \lim_{\infty} \left\langle c_{-\mathbf{q}}(0) c_{\mathbf{q}}(t) \right\rangle$$

Dynamic structure factor

$$G(q, t) = \lim_{\infty} \left\langle a_{-\mathbf{q}}(0) a_{\mathbf{q}}(t) \right\rangle$$

Self-dynamic structure factor

Backword operator and eigenfunction expansion

- Define two unitary products on space of configuration variables

$$(A | B) := \int d\mathbf{r}^N A^*(\mathbf{r}^N) B(\mathbf{r}^N)$$

↑
unweighted product

$$\langle A | B \rangle := \int d\mathbf{r}^N P_{\text{eq}}(\mathbf{r}^N) A^*(\mathbf{r}^N) B(\mathbf{r}^N) = \langle A^* B \rangle_{\text{eq}}$$

↑
weighted product

- Define backward Smoluchowski operator as adjoint operator w/r to $(..|..)$:

$$(\hat{O}_B A | B) = (A | \hat{O}_B B) \Rightarrow$$

$$\begin{aligned} \hat{O}_B(\mathbf{r}^N) &= \sum_{i,j=1}^N \left[\nabla_i + \beta (\mathbf{F}_i^p + \mathbf{F}_i^{\text{ex}}) \right] \cdot \mathbf{D}_{ij} \cdot \nabla_j \\ &= \left[\nabla + \beta \mathbf{F}^T(\mathbf{X}) \right] \cdot \mathbf{D}(\mathbf{X}) \cdot \nabla \end{aligned}$$

- Some useful properties of real backward Smoluchowski operator :

(a) $\langle \hat{O}_B A | B \rangle = \langle A | \hat{O}_B B \rangle$ self-adjoint w/r to weighted inner product

(b) $\hat{O}(A P_{\text{eq}}) = P_{\text{eq}} \hat{O}_B A$ for arbitrary $A(\mathbf{X})$ taken at **same** $\mathbf{X}$

- More on useful properties of backward Smoluchowski operator

(c) $\langle A | \hat{O}_B B \rangle = - \sum_{i,j=1}^N \left\langle \left(\nabla_i A^* \right) \cdot \mathbf{D}_{ij}(\mathbf{r}^N) \cdot \nabla_j B \right\rangle_{\text{eq}}$ for arbitrary A and B


 real and positive definite 3N x 3N matrix

(d) $\langle A | \hat{O}_B A \rangle \leq 0$ negative semi-definite w/r to $\langle \cdot | \cdot \rangle$

- Equilibrium time correlation functions are very conveniently expressed as :

(e) $C_{AB}(t) = \langle A | e^{\hat{O}_B t} B \rangle = \left\langle A^* \left(e^{\hat{O}_B t} B \right) \right\rangle_{\text{eq}} = \int d\mathbf{r}^N P_{\text{eq}}(\mathbf{r}^N) A^*(\mathbf{r}^N) \left(e^{\hat{O}_B t} B(\mathbf{r}^N) \right)$

- This allows formal definition : $A(t) := e^{\hat{O}_B t} A$ ($A = A(0)$)


 acts like
time-evolution operator

$$\dot{A} = \hat{O}_B A$$

- Example: coarse-grained drift velocity of particle i due to DI and HI :

$$\mathbf{v}_i^I(\mathbf{r}^N) := \hat{O}_B \mathbf{r}_i = \sum_{l=1}^N \left(\beta \mathbf{D}_{il} \cdot \mathbf{F}_l^T + \nabla_l \cdot \mathbf{D}_{il} \right) \rightarrow \beta \mathbf{D}_0 \cdot \mathbf{F}_i^T$$

- Backward op.is also very useful to express conditional or non-eq. averages :

$$\langle (\dots) \rangle_{\text{neq}}(t) = \int d\mathbf{r}^N P(\mathbf{r}^N, t) (\dots) \quad \langle (\dots) \rangle_{X_0}(t) = \int d\mathbf{r}^N P(\mathbf{r}^N, t | \mathbf{r}_0^N, 0) (\dots)$$

↑
arbitrary non-eq.
pdf solution of GSE

(e)

$$\langle A(\mathbf{r}^N) \rangle_{\text{neq}}(t) = \int d\mathbf{r}^N P(\mathbf{r}^N, t=0) e^{\hat{O}_B t} A(\mathbf{r}^N)$$

$$\langle A(\mathbf{r}^N) \rangle_{X_0}(t) = e^{\hat{O}_B(\mathbf{r}^N)t} A(\mathbf{r}^N) \Big|_{\mathbf{r}_0^N}$$

- Application to position vector of particle i :

$$\langle \mathbf{r}_i \rangle_{X_0}(\Delta t) = e^{\hat{O}_B(\mathbf{r}^N)\Delta t} \mathbf{r}_i \Big|_{X_0} = \mathbf{r}_i^0 + \hat{O}_B(\mathbf{r}^N) \mathbf{r}_i \Big|_{X_0} \Delta t + O(\Delta t^2)$$

$$\langle \mathbf{r}_i(\Delta t) - \mathbf{r}_i(0) \rangle_{X_0} \equiv \langle \Delta \mathbf{r}_i(\Delta t) \rangle_{X_0} = \mathbf{v}_i^I(\mathbf{r}_0^N)(\Delta t) + O(\Delta t^2)$$

$$\langle \Delta \mathbf{r}_i(\Delta t) \Delta \mathbf{r}_j(\Delta t) \rangle_{X_0} = 2\mathbf{D}_{ij}(X_0)\Delta t + O(\Delta t^2)$$



Brownian Dynamics
Simulations

- How is $v^I(X)$ related with velocity appearing in continuity eq. form of GSE ?

$$\frac{\partial}{\partial t} P(X, t) + \sum_{i=1}^N \nabla_i \cdot (\mathbf{v}_i(X, t) P(X, t)) = 0$$

$$\mathbf{v}_i(X, t) = -\beta \sum_{l=1}^N \mathbf{D}_{il} \cdot [\mathbf{F}_l^H = -\mathbf{F}_l^T - \mathbf{F}_l^B] = \sum_{l=1}^N \mathbf{D}_{il} \cdot [\beta \mathbf{F}_l^T - \nabla_l \ln P(X, t)]$$



$$\langle \mathbf{v}_i(X, t) \rangle_{\text{neq}}(t) = \int dX P(X, t) \mathbf{v}_i(X, t) = \langle \mathbf{v}_i^I(X) \rangle_{\text{neq}}(t)$$

Calculation of backward operator:

$\mathbf{D}(\mathbf{X}) = \mathbf{D}^T(\mathbf{X})$ is a real $3N \times 3N$ matrix

$$(A | \hat{O}B) := \int d\mathbf{X} A^* \nabla \cdot \mathbf{D}(\mathbf{X}) \cdot [\nabla - \beta \mathbf{F}^T(\mathbf{X})] B = - \int d\mathbf{X} (\nabla A^*) \cdot \mathbf{D}(\mathbf{X}) \cdot [\nabla - \beta \mathbf{F}^T(\mathbf{X})] B$$

partial integration

$$= \int d\mathbf{X} [B \beta \mathbf{F}^T(\mathbf{X}) \cdot \mathbf{D}(\mathbf{X}) \cdot \nabla A^*] - \int d\mathbf{X} \underbrace{(\nabla A^*) \cdot \mathbf{D}(\mathbf{X}) \cdot \nabla B}_{(\nabla B) \cdot \mathbf{D}(\mathbf{X}) \cdot \nabla A^*}$$

partial integration

$$= \int d\mathbf{X} B [\nabla + \beta \mathbf{F}^T(\mathbf{X})] \cdot \mathbf{D}(\mathbf{X}) \cdot \nabla A^* = \int d\mathbf{X} B \left([\nabla + \beta \mathbf{F}^T(\mathbf{X})] \cdot \mathbf{D}(\mathbf{X}) \cdot \nabla A \right)^*$$

$$= (\hat{O}_B A | B)$$

$\hat{O}_B(\mathbf{X})$

- surface integrals are assumed zero by appropriate outer BCs (U^{ex} may include wall potential)

Eigenfunction expansion

- $\hat{O}_B$ is real, self-adjoint and negative-semidefinite w/r to $\langle \dots | \dots \rangle \Rightarrow$
- Assuming completeness, $\hat{O}_B$ has ONB of real eigenfunctions $\{\phi_\lambda(X)\}$, with eigenvalues $\{-\lambda\} \leq 0$

$$\hat{O}_B \phi_\lambda = -\lambda \phi_\lambda \quad \hat{O}_B (\phi_0 \equiv 1) = 0 \cdot \phi_0 \quad \langle \phi_\lambda | \phi_\mu \rangle = \delta_{\mu\lambda} \quad \sum_\lambda \int |\phi_\lambda\rangle \langle \phi_\lambda| = \mathbf{1}$$

$$e^{O_B t} = e^{O_B t} \mathbf{1} = \sum_{\lambda \geq 0} \int e^{-\lambda t} |\phi_\lambda\rangle \langle \phi_\lambda| = |\phi_0\rangle \langle \phi_0| + \sum_{\lambda > 0} \int e^{-\lambda t} |\phi_\lambda\rangle \langle \phi_\lambda|$$

Spectral representation

$$P(X, t | X_0, 0) = e^{\hat{O}(X)t} \delta(X - X_0) = e^{\hat{O}_B(X_0)t} \delta(X - X_0) = P_{eq}(X) \left[1 + \sum_{\lambda > 0} \int e^{-\lambda t} \phi_\lambda(X_0) \phi_\lambda(X) \right]$$

$$P(X, t | X_0, 0) \rightarrow P_{eq}(X) \text{ for } t \rightarrow \infty$$

Conditional Pdf evolves monotonically towards equilibrium Pdf

$$P(X, t | X_0, 0) P_{eq}(X_0) = P(X_0, t | X, 0) P_{eq}(X)$$

Detailed balance relation ($t > 0$)

- Integration of detailed balance relation w/r to X shows that $\hat{O} P_{eq} = 0$

- Consequences for equilibrium time correlation functions in Smoluchowski dynamics :

$$C_{AB}(t) = \left\langle A \left| e^{\hat{O}_B t} B \right\rangle = \sum_{\lambda \geq 0} \int e^{-\lambda t} d\lambda \langle A | \phi_\lambda \rangle \langle \phi_\lambda | B \rangle \xrightarrow[t \rightarrow \infty]{} \langle A \rangle_{\text{eq}} \langle B \rangle_{\text{eq}} \quad \text{A and B uncorrelated at long times (fluid)}$$

- Regular autocorrelation functions $C_{AA}(t) \equiv C_A(t)$ are strictly monotonically decaying :

$$C_A(t) = \sum_{\lambda \geq 0} \int e^{-\lambda t} \underbrace{|\langle A | \phi_\lambda \rangle|^2}_{0 \leq p_A(\lambda)} \geq 0$$

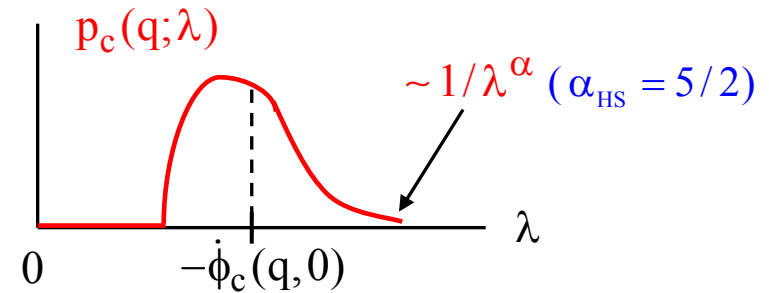
$$(-1)^n \frac{\partial^n}{\partial t^n} C_A(t) = \sum_{\lambda \geq 0} \int \lambda^n e^{-\lambda t} |\langle A | \phi_\lambda \rangle|^2 \geq 0$$

$0 \leq p_A(\lambda) : \text{spectral density of } C_A(t)$

- Largest eigenvalue of Smoluchowski operator is non-degenerate, since all eigenfunctions to $\lambda = 0$ must not change sign for all X

- Example: normalized dynamic structure factor with $A = c_{\mathbf{q}}$ and $\langle A \rangle_{\text{eq}} = 0$

$$0 \leq \phi_c(\mathbf{q}, t) \equiv \frac{S(\mathbf{q}, t)}{S(\mathbf{q})} = \int_0^\infty d\lambda e^{-\lambda t} p_c(\mathbf{q}; \lambda) \leq 1$$



$$\phi_c(\mathbf{q}, t \rightarrow \infty) \equiv \begin{cases} 0 & \text{fluid} \\ f_c(\mathbf{q}) > 0 & \text{„glass“} \end{cases}$$

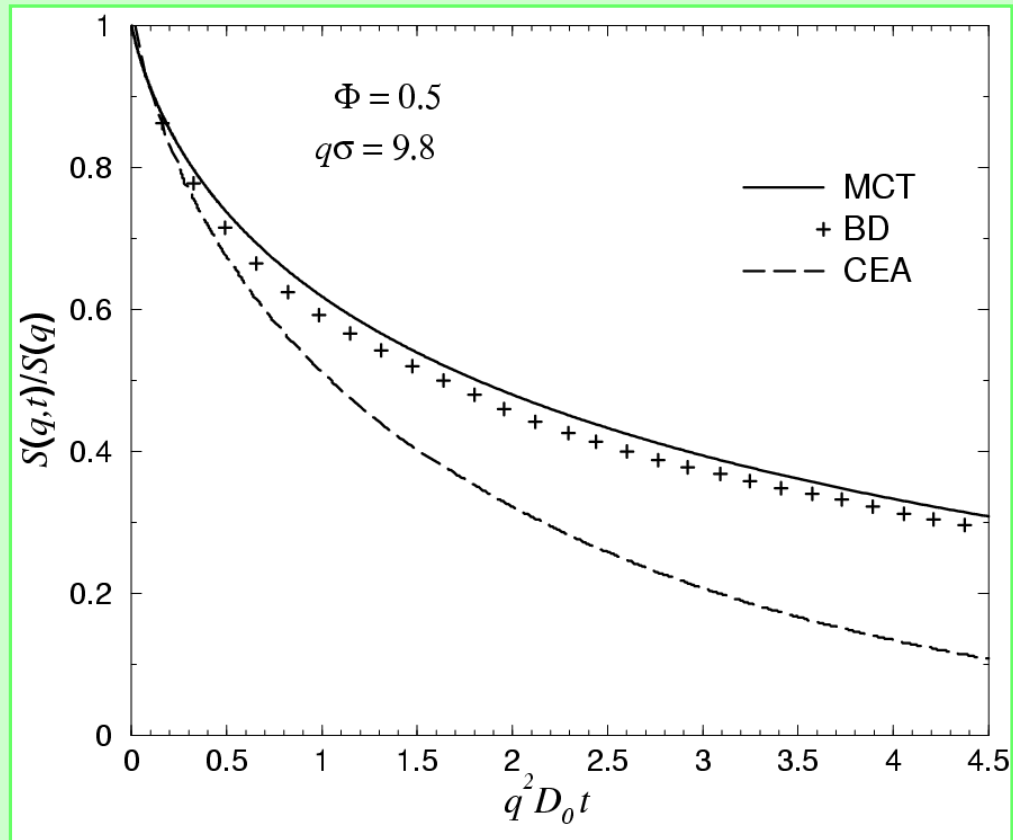
- Consider Laplace transform of $\phi_c(\mathbf{q}, t)$: $\tilde{\phi}_c(\mathbf{q}, z) \equiv \int_0^\infty dt e^{-zt} \phi_c(\mathbf{q}, t) \sim \frac{f_c(\mathbf{q})}{z} + \text{regular part}$

$$\tilde{\phi}_c(\mathbf{q}, z) \equiv \int_0^\infty d\lambda e^{-\lambda t} \frac{p_c(\mathbf{q}, \lambda)}{z + \lambda}$$

develops $1/z$ pole at glass point

singularities only on negative axis in complex z -plane:

Example: Dynamic structure factor of 3D hard-sphere dispersion



(Banchio, Nägele & Bergenholtz, J. Chem. Phys. 113 (2000))

- $S(q,t)$ decays strictly monotonically in t

Brownian dynamics simulations

- GSE : $\Delta \mathbf{r}^N(\Delta t) = \mathbf{r}^N(\Delta t) - \mathbf{r}^N(0)$ multivariate Gaussian random process to first order in Δt :

$$\langle \Delta \mathbf{r}_i(\Delta t) \rangle_{X_0} = \mathbf{v}_i^I(\mathbf{r}_0^N) \Delta t + O(\Delta t^2) \quad (\tau_B \ll \Delta t \ll \tau_I)$$

$$\langle \Delta \mathbf{r}_i(\Delta t) \Delta \mathbf{r}_j(\Delta t) \rangle_{X_0} = 2 \mathbf{D}_{ij}^{tt}(X_0) \Delta t + O(\Delta t^2)$$

- Stochastic finite difference equation for translational motion of torque-free spheres :

$$\Delta \mathbf{r}_i(\Delta t) = \sum_{l=1}^N \left(\beta \mathbf{D}_{il}^{tt}(X_0) \cdot \mathbf{F}_l^T(X_0) + \nabla_l \cdot \mathbf{D}_{il}^{tt}(X_0) \right) \Delta t + \Delta \mathbf{x}_i(\Delta t)$$



DI



Near-field HI



Central Gaussian displacement

$$\langle \Delta \mathbf{x}_i(\Delta t) \Delta \mathbf{x}_j(\Delta t) \rangle = 2 \mathbf{D}_{ij}^{tt}(X_0) \Delta t$$

Point particles w/o DI (obey Oseen-HI):

$$\langle \Delta \mathbf{x}_i(\Delta t) \rangle = 0$$

$$\Delta \mathbf{r}_i(\Delta t) = \Delta \mathbf{x}_i(\Delta t) \quad \text{Gaussian now}$$

- For $\mathbf{D} = \mathbf{D}(X)$, care needed for limit $\Delta t \rightarrow 0$ (Ito vs. Stratonovich)

Stokesian dynamics of non-Brownian spheres

$$\Delta \mathbf{r}_i(\Delta t) = \beta \sum_{l=1}^N \mathbf{D}_{il}^{tt}(\mathbf{X}_0) \cdot \mathbf{F}_l^T(\mathbf{X}_0) \Delta t + O((\Delta t)^2)$$

$$\mathbf{v}_i = \beta \sum_{l=1}^N \mathbf{D}_{il}(\mathbf{r}^N) \cdot [\mathbf{F}_l^p + \mathbf{F}_l^{\text{ex}}] \quad \frac{\partial}{\partial t} P(\mathbf{r}^N, t) + \sum_{i=1}^N \nabla_i \cdot (\mathbf{v}_i(\mathbf{r}^N) P(\mathbf{r}^N, t)) = 0$$

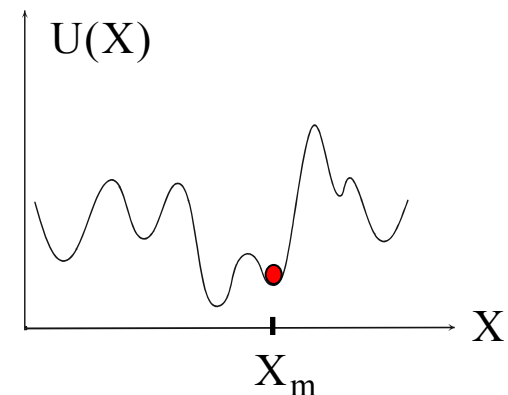
- First-order Stokes-Liouville equation of overdamped motion

$$\frac{\partial}{\partial t} P(\mathbf{r}^N, t) = \hat{O}_{\text{SL}}(\mathbf{r}^N) P(\mathbf{r}^N, t)$$

$$\hat{O}_{\text{SL}}(\mathbf{r}^N) = -\beta \sum_{i,j=1}^N \nabla_i \cdot \mathbf{D}_{ij} \cdot [\mathbf{F}_j^p + \mathbf{F}_j^{\text{ex}}]$$

Particles come to rest **without** external forcing at a configuration $\mathbf{X}_m$ where $U(\mathbf{X})$ has a local minimum

$$P(\mathbf{X}, t \rightarrow \infty) = \delta(\mathbf{X} - \mathbf{X}_m) \quad \text{may depend on start configuration}$$



$P(\mathbf{X}, t) = \text{const}$ stationary solution for constant external forcing (sedimentation) only when $\nabla \cdot \mathbf{D}(\mathbf{X}) = 0$ (i.e., for point particles only)

Example: Stokesian dynamics simulation of Q2D system

$$\Delta \mathbf{r} = \mathbf{R}_{\text{FU}}^{-1}(\mathbf{r}^N) \cdot \mathbf{F}^{\text{pot}} \Delta t + k_B T \nabla \cdot \mathbf{R}_{\text{FU}}^{-1}(\mathbf{r}^N) \Delta t + \Delta \mathbf{X}$$

translational-rotational
N-sphere displacement

DI

near-field HI

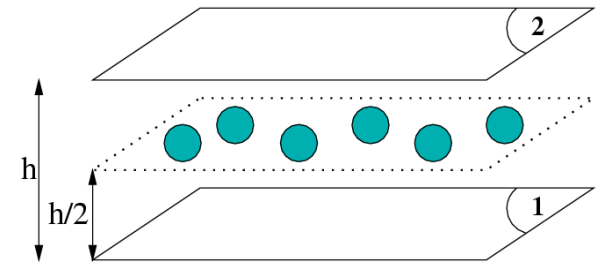
Gaußian
random step

$$\langle \Delta \mathbf{X} \Delta \mathbf{X} \rangle = 2k_B T \mathbf{R}_{\text{FU}}^{-1} \Delta t$$

mobility matrix
(5N × 5N)

$$\mathbf{F}^{\text{hyd}} = -\mathbf{R}_{\text{FU}}(\mathbf{r}^N) \cdot \mathbf{U} \quad \text{HI: multipole expansion + lubrication}$$

- Only mid-plane diffusion considered
- Superposition of single-wall geometry (stick BC)



$$\mathbf{F}_i^{\text{hyd}} = -\sum_{j=1}^N \left\{ \underbrace{\left(\mathbf{R}_{ij}^{\text{pp}} \right)_{\text{FU}}^{(1)}}_{\text{particle-particle HI \& first wall alone}} + \left(\mathbf{R}_{ij}^{\text{pp}} \right)_{\text{FU}}^{(2)} + \left[\underbrace{\left(\mathbf{R}_{ij}^{\text{pw}} \right)_{\text{FU}}^{(1)}}_{\text{particle-wall HI \& first wall alone}} + \left(\mathbf{R}_{ij}^{\text{pw}} \right)_{\text{FU}}^{(2)} \right] \delta_{ij} \right\} \cdot \mathbf{U}_j$$

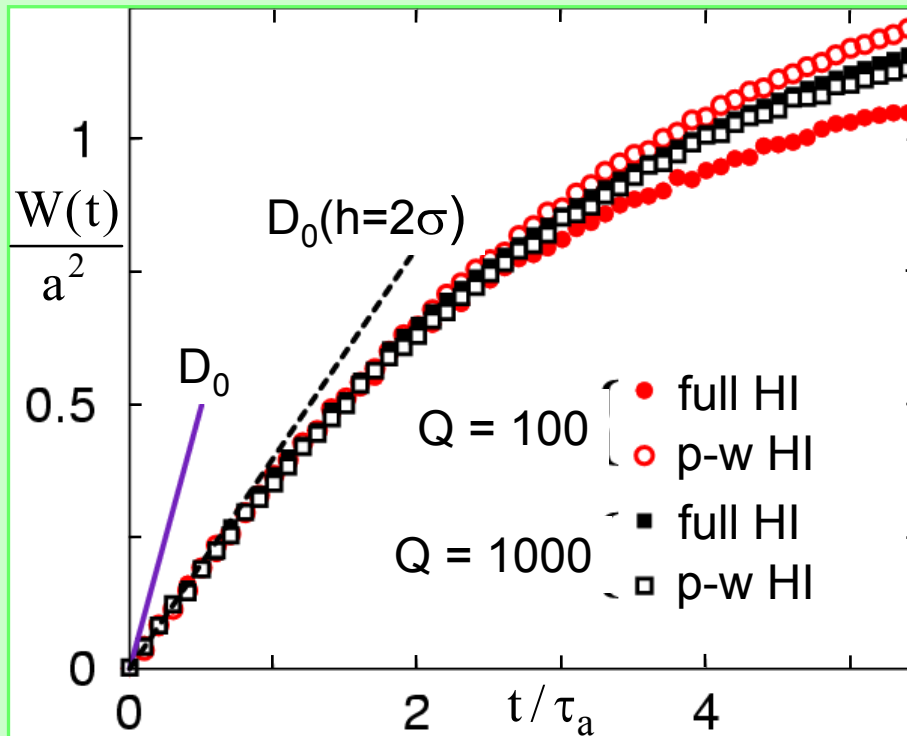
particle-particle HI
& first wall alone

particle-wall HI
& first wall alone

Bossis et al., Phys. Fluids A3 (1991)

Self-diffusion using Chang-Hone screened Coulomb potential

Task: assess individual relevance of p-w and p-p HI for dynamics



$$W(t) = \frac{\langle [\mathbf{r}(t) - \mathbf{r}(0)]^2 \rangle}{4}$$

$$\tau_a = a^2 / D_0$$

$$C = 0.063$$

$$h = 2\sigma$$

$$D_0(h) \approx 0.4D_0$$

$$\kappa^{-1}(h) \approx 0.9\sigma$$

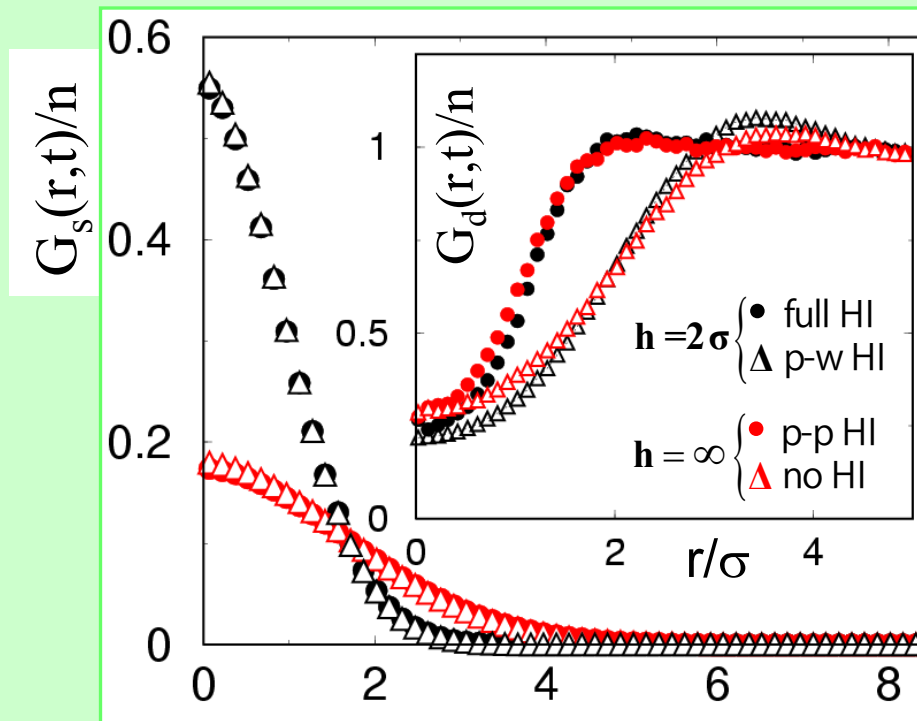
- Small hydrodynamic enhancement by p-p HI for strongly charged spheres
- Self-diffusion lowered for moderately charged or neutral spheres

Space-time correlations: van Hove functions

Conditional pdf : $G(\mathbf{r}, t) = \left\langle \sum_{i,j=1}^N [\mathbf{r} - \mathbf{r}_i(t) + \mathbf{r}_j(0)] / N \right\rangle = G_s(\mathbf{r}, t) + G_d(\mathbf{r}, t)$

Distinct part : $G_d(\mathbf{r}, 0) = n g(\mathbf{r})$, $n = N / A$

Self part : $G_s(\mathbf{r}, 0) = \delta(\mathbf{r})$, $G_s(\mathbf{r}, t) \approx \frac{1}{4\pi W(t)} \exp \left\{ -\frac{r^2}{4W(t)} \right\}$



$t = 3.5 \tau_a$

$C = 0.063$

$h = 2\sigma$

$Q = 10^3$

SD: Pesché & Nägele
PRE 62 (2000)

- Collective diffusion dominated by p-p HI and self-diffusion by p-w HI

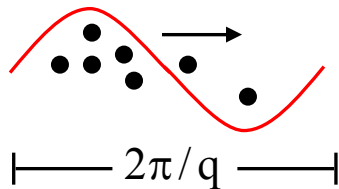
Projection operators and memory equations

- Evolution of conserved variable $A(X) = A_{\mathbf{q}}(X)$ in Brownian system :

$$A \equiv A_{\mathbf{q}} \propto \int d\mathbf{r} e^{i\mathbf{q} \cdot \mathbf{r}} \sum_{j=1}^N a_j \delta(\mathbf{r} - \mathbf{r}_j)$$

$$\frac{\partial}{\partial t} A_{\mathbf{q}} \equiv \hat{O}_B A_{\mathbf{q}} = i\mathbf{q} \cdot \mathbf{J}_{\mathbf{q}}^A \rightarrow 0, \quad q \rightarrow 0$$

slow, at least for q small



$$\hat{P}_A \equiv \frac{|A\rangle\langle A|}{\langle A|A\rangle}$$

projects on E_P
(slow-variable subspace)

$$\hat{Q}_A \equiv 1 - \hat{P}_A$$

projects on E_Q
(fast-variable subspace)

$$E = E_P \oplus E_Q$$

$$A_{\mathbf{q}} = c_{\mathbf{q}} \equiv \frac{1}{\sqrt{N}} \sum_{l=1}^N e^{i\mathbf{q} \cdot \mathbf{r}_l} - \sqrt{N} \delta_{\mathbf{q},0}$$

$$A_{\mathbf{q}} = a_{\mathbf{q}} \equiv e^{i\mathbf{q} \cdot \mathbf{r}_1} - \delta_{\mathbf{q},0}$$

$$S(q, t) = \lim_{\infty} \langle c_{\mathbf{q}} | e^{\hat{O}_B t} c_{\mathbf{q}} \rangle$$

dynamic structure factor

$$G(q, t) = \lim_{\infty} \langle a_{\mathbf{q}} | e^{\hat{O}_B t} a_{\mathbf{q}} \rangle$$

self-dynamic structure factor

$$\langle A_{\mathbf{q}} \rangle_{\text{eq}} = 0$$

- Memory equation for time evolution of $C_A(t)$:

$$e^{\hat{O}_B t} = e^{\hat{Q}_A \hat{O}_B t} + \int_0^t du e^{\hat{O}_B(t-u)} \hat{P}_A \hat{O}_B e^{\hat{Q}_A \hat{O}_B u}$$

$$\frac{\partial}{\partial t} C_A(t) = -\omega_A C_A(t) + \int_0^t du M_A(t-u) \frac{C_A(u)}{C_A(0)}$$

short-time
frequency

memory function

$$\omega_A = -\langle A | \hat{O}_B A \rangle_A / C_A(0)$$

$$f_A = \hat{Q}_A \hat{O}_B A$$

$$M_A(t) = \left\langle f_A \left| e^{\hat{Q}_A \hat{O}_B \hat{Q}_A t} f_A \right. \right\rangle$$

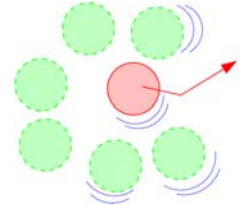
reduced time evolution operator

- force – force ACF in fast-variable subspace
- non-negative & strictly monotonically decaying

$$\frac{C_A(t)}{C_A(0)} = \begin{cases} \exp\{-\omega_A t\} & (\tau_B \ll t \ll \tau_I) \\ \text{slower \& non-exp. in general} & (t \sim \tau_I) \end{cases}$$

- Application: memory equation for dynamic structure factor :

$$\frac{\partial}{\partial t} S(q, t) = - \underbrace{q^2 D_0 \frac{H(q)}{S(q)}}_{\tau_B \ll t \ll \tau_I} S(q, t) + \underbrace{\int_0^t du M_c(q, t-u) \frac{S(q, u)}{S(q)}}_{t \gg \tau_I \text{ cage relaxation}}$$



$$f_{\mathbf{q}}^c = \hat{O}_B c_{\mathbf{q}} + q^2 D_0 \frac{H(q)}{S(q)} c_{\mathbf{q}} = i\mathbf{q} \cdot \frac{1}{\sqrt{N}} \sum_{i=1}^N \mathbf{v}_i^I + O(q^2)$$

- Hydrodynamic function describes short-time dynamics $\tau_B \ll t \ll \tau_I$:

$$H(q) = \lim_{\infty} \left\langle \frac{1}{ND_0 q^2} \sum_{i,j=1}^N \mathbf{q} \cdot \mathbf{D}_{ij}(\mathbf{r}^N) \cdot \mathbf{q} \exp[i\mathbf{q} \cdot (\mathbf{r}_i - \mathbf{r}_j)] \right\rangle_{eq} \quad H(q) \equiv 1 \text{ w/o HI}$$

$$H(q) = \frac{1}{D_0} \underbrace{\left\langle \hat{\mathbf{q}} \cdot \mathbf{D}_{11}(\mathbf{r}^N) \cdot \hat{\mathbf{q}} \right\rangle_{eq}}_{D_s} + \frac{1}{D_0} \underbrace{\left\langle N \sum_{i \neq j} \hat{\mathbf{q}} \cdot \mathbf{D}_{12}(\mathbf{r}^N) \cdot \hat{\mathbf{q}} \exp[i\mathbf{q} \cdot (\mathbf{r}_i - \mathbf{r}_j)] \right\rangle_{eq}}_{H_d(q)}$$



D_s : short-time self-diffusion



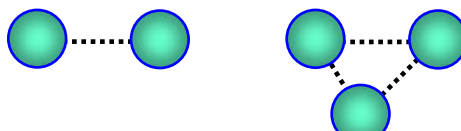
$H_d(q) \rightarrow 0$ for $q \rightarrow \infty$

7. Short-time dynamics

- **Methods of calculation**
- **Hydrodynamic function**
- **Sedimentation**
- **Smoluchowski equation with incident fluid flow**
- **Collective and gradient diffusion**
- **Rotational self-diffusion**

Methods of calculation (of short-time properties)

- Brownian/Stokesian dynamics and Lattice-Boltzmann computer simulations
 - Leading-order (i.e. zeroth-order) $\delta\gamma$ -method (Beenakker & Mazur, 1984, for HS)
 - expansion in renormalized density fluctuations $\delta\gamma$
 - approximate inclusion of many-body HI (ring-diagrams only)
 - truncated $1/r$ expansion of propagators
 - **HS**: works rather well for $\phi < 0.35$
 - **CS**: works well with ext. input for D_s (Banchio & Nägele, 2004)
- • Truncated hydrodynamic cluster expansion (systems with prevailing far-field HI)

$$\mathbf{D}_{ij}(\mathbf{r}^N) \approx D_0 \mathbf{1} \delta_{ij} + \underbrace{\Delta \mathbf{D}_{ij}^{(2)}(\mathbf{r}^N)}_{\text{2-sphere HI}} + \underbrace{\Delta \mathbf{D}_{ij}^{(3)}(\mathbf{r}^N)}_{\text{3-sphere HI}} \quad \leftarrow \text{static pair- \& tripllett distribution functions (charged systems)}$$


Truncated hydrodynamic cluster expansion :

$$\mathbf{D}_{ij}(\mathbf{r}^N) = D_0 \mathbf{1} \delta_{ij} + \underbrace{\Delta \mathbf{D}_{ij}^{(2)}(\mathbf{r}^N)}_{\text{2-body HI}} + \underbrace{\Delta \mathbf{D}_{ij}^{(3)}(\mathbf{r}^N)}_{\text{3-body HI}} + \dots$$

$$\Delta \mathbf{D}_{ij}^{(2)}(\mathbf{r}^N) = D_0 \left[\delta_{ij} \sum_{l \neq j}^N \boldsymbol{\omega}_{11}(\mathbf{r}_{lj}) + (1 - \delta_{ij}) \boldsymbol{\omega}_{12}(\mathbf{r}_{ij}) \right]$$

$\begin{cases} O(r^{-4}) : l \neq j \\ O(r^{-7}) : l = j \end{cases}$

pairwise-additive

Long-distance multipole expansion of 2-body HI :

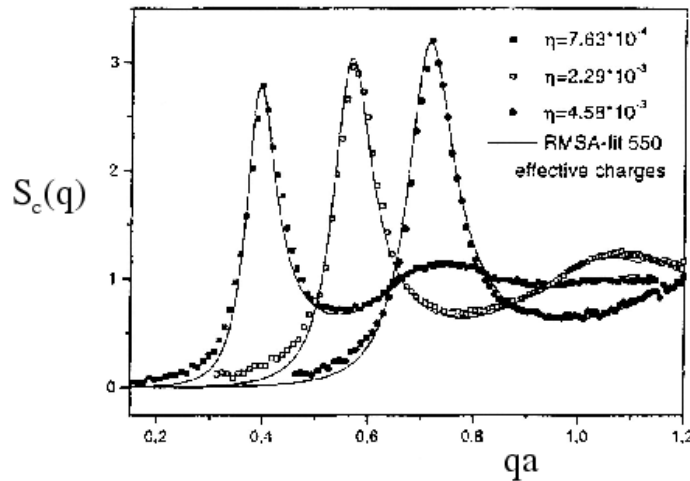
$$\boldsymbol{\omega}_{12}(\mathbf{r}) = \underbrace{\frac{3}{4} \left(\frac{a}{r} \right) \left[1 + \hat{\mathbf{r}} \hat{\mathbf{r}} \right]}_{\text{Oseen term}} + \underbrace{\frac{1}{2} \left(\frac{a}{r} \right)^3 \left[1 - 3 \hat{\mathbf{r}} \hat{\mathbf{r}} \right]}_{\text{dipole term}} + \underbrace{O(r^{-7})}_{\text{back reflections}}$$

Rotne-Prager part

$$\boldsymbol{\omega}_{11}(\mathbf{r}) = \underbrace{-\frac{15}{4} \left(\frac{a}{r} \right)^4 \hat{\mathbf{r}} \hat{\mathbf{r}}}_{\text{first self reflection}} + O(r^{-6})$$

Rotne-Prager (RP) part suffices for dilute charge-stabilized dispersions !

Hydrodynamic function

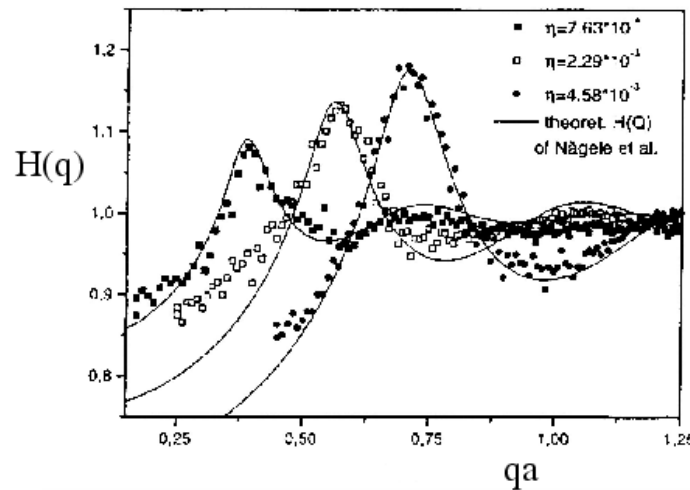


Dilute charge-stabilized dispersions

$$\phi \sim 10^{-4} - 10^{-3}$$

(input: RMSA – $g(r)$)

(G. Nägele, general ref. 4 on page 4)

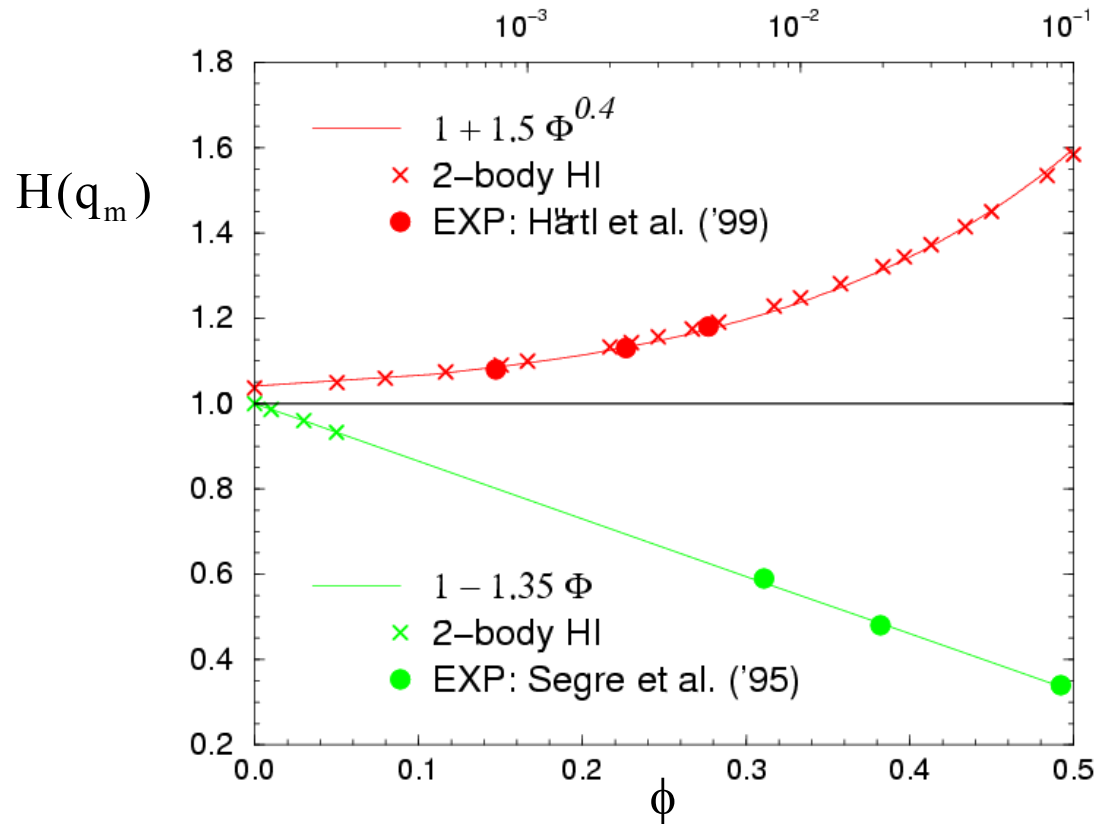


$$H(q_m) \approx 1 + 1.5\phi^{0.4}$$

$$H(0) \approx 1 - 1.8\phi^{1/3}$$

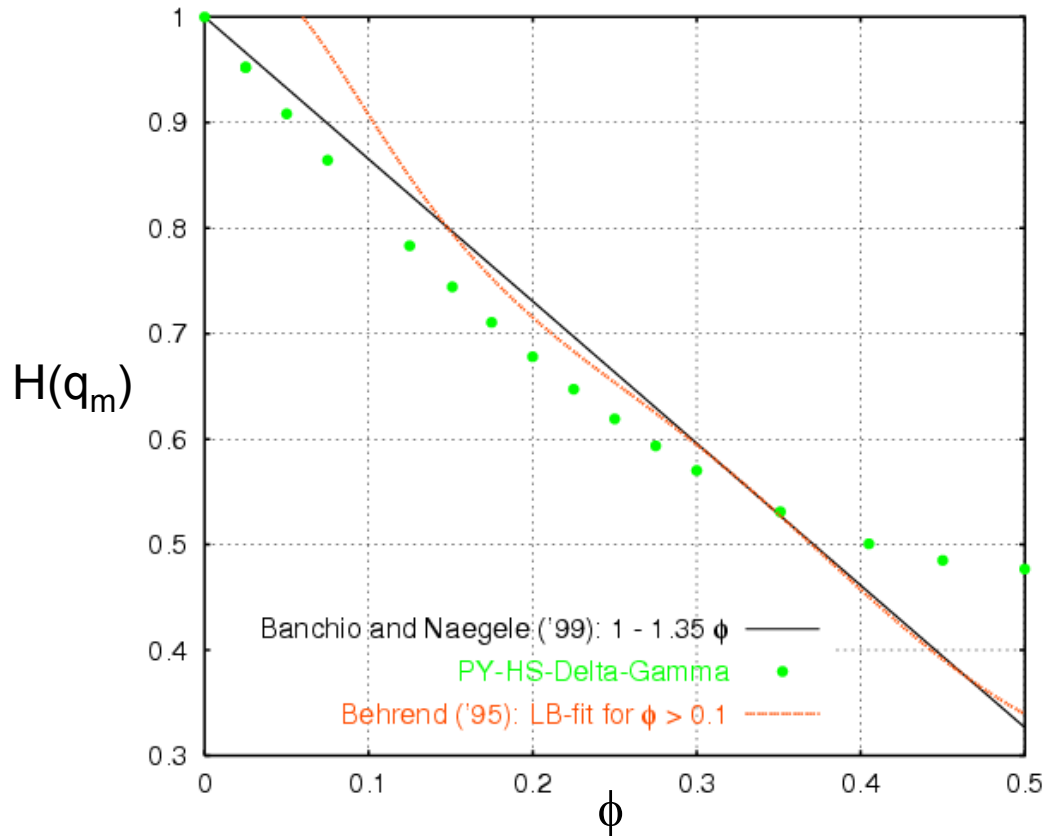
$$H_{RP}(y) = 1 - 15\phi \frac{j_1(y)}{y} + 18\phi \int_1^\infty dx x h(x) \left(j_0(xy) - \frac{j_1(xy)}{xy} + \frac{j_2(xy)}{6x^2} \right), \quad (y = q\sigma)$$

- Peak height $H(q_m)$ vs. concentration



$$H(q_m) \approx \begin{cases} 1 - 1.35\phi & (\text{HS: } \phi < 0.5) \\ 1 + p_0 \phi^{0.4} & (\text{CS: } \phi < 0.05 \text{ and } p_0 = 0.5 - 1.5) \end{cases}$$

- Peak height $H(q_m)$ for hard spheres



Behrend et al., PRE '95 :

Lattice-Boltzmann-fit for $\phi > 0.1$

$$\frac{D_0}{D_c(q_m)_{LB}} \approx 1 - 2\phi + 58\phi^2 - 220\phi^3 + 347\phi^4$$

combine with:

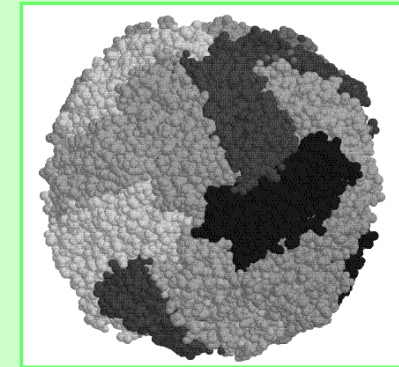
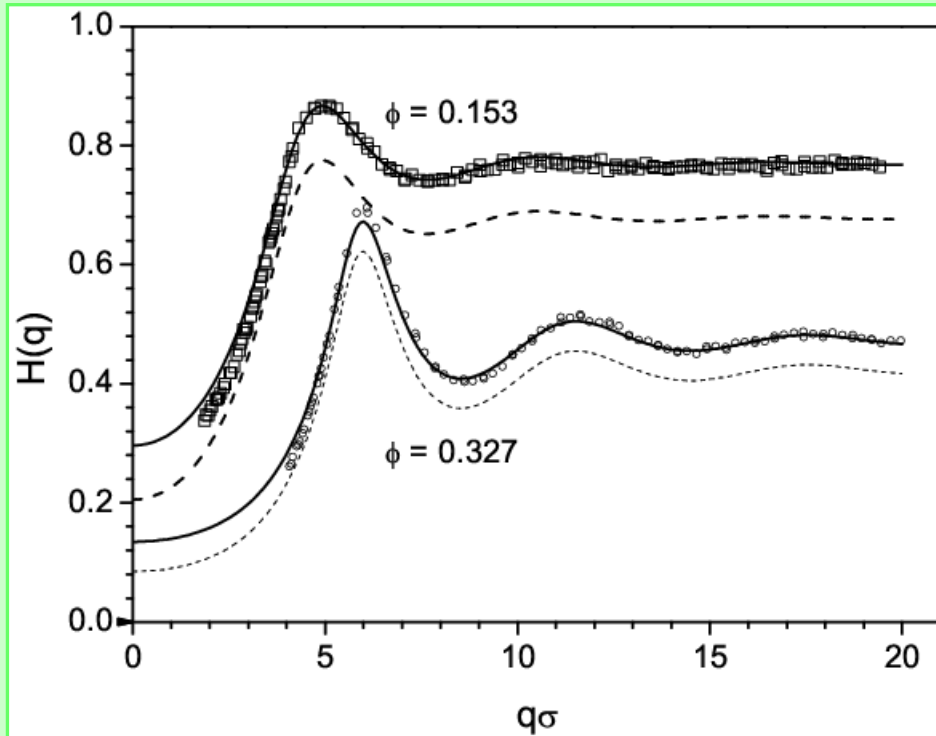
$$S(q_m) = 1 + 0.644 g_{CS}(\sigma^+; \phi)$$

$\Rightarrow$

$$|H(q_m)_{LB} - (1 - 1.35\phi)| < 4\%$$

- LB simulations of Ladd in PRE '95: $H(q_m)$ above $H_{\delta\gamma}(q_m)$ for $\phi > 0.4$

- $H(q)$ of concentrated charge-stabilized protein dispersions (Apoferritin)



SD simulation vs $\delta\gamma$ - calculations

symbols: SD
dashed : $\delta\gamma$
solid: hybrid - $\delta\gamma$

(Gapinski, Banchio, Nägele et al.,
submitted, 2005)

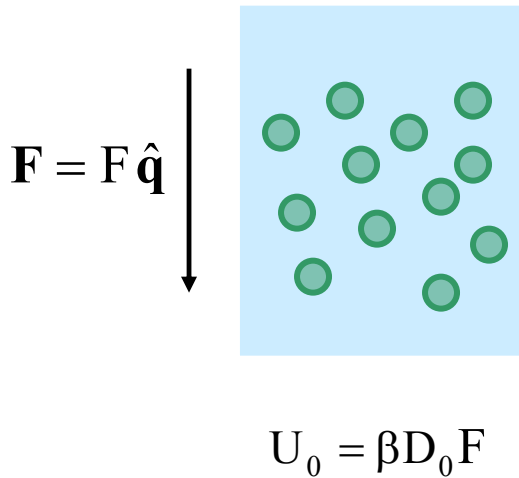
$$H(q) = \mathbf{D_s} / D_0 + H_d(q)$$



Input from SD in hybrid - $\delta\gamma$

Sedimentation

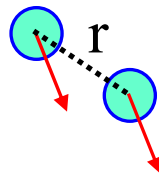
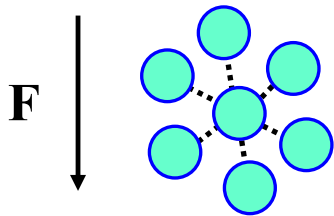
- Slow (initial) settling of colloidal Brownian spheres starting from homog. state



$$Pe = \frac{\text{diffusion time}}{\text{sedimentation time}} = \frac{\tau_I = \sigma^2 / D_0}{\tau_{\text{sed}} = \sigma / U_0} \ll 1$$

$$P_{\text{in}}(\mathbf{r}^N, t=0) \xrightarrow[t \gg \tau_I]{} \begin{cases} P_{\text{st}}(\mathbf{r}^N) = P_{\text{eq}}(\mathbf{r}^N) & \text{no or pairwise-additive HI} \\ P_{\text{st}}(\mathbf{r}^N) \neq P_{\text{eq}}(\mathbf{r}^N) & \text{3- and more-body HI} \end{cases}$$

equil. distribution for
zero ext. force $\mathbf{F} = 0$



$\mathbf{r}$ fixed for 2-body HI

- Find stationary & homog. Pdf solution of GSE under constant external force $\mathbf{F}$

$$0 = \frac{\partial}{\partial t} P_{st}(X) = \sum_{i,j=1}^N \nabla_i \cdot \mathbf{D}_{ij} \cdot \left[\nabla_j - \beta \mathbf{F}_j^p \right] P_{st} - \sum_{i,j=1}^N \nabla_i \cdot \mathbf{D}_{ij} \cdot [\beta \mathbf{F} P_{st}]$$

solution : $P_{eq}(X)$

non-eq. drift term

$$P_{eq}(X) \propto \exp\{-\beta U\} = \exp\left\{-\beta \sum_{i < j} u(r_{ij})\right\} \text{ is homogeneous}$$

without HI is : $\text{drift term} = \beta D_0 \mathbf{F} \cdot \sum_{i=1}^N \nabla_i P_{st} = 0$

$$P_{st}(\mathbf{r}_1 + \mathbf{x}, \dots, \mathbf{r}_N + \mathbf{x}) = P_{st}(\mathbf{r}_1, \dots, \mathbf{r}_N) \Rightarrow \sum_i \nabla_i P_{st} = 0$$

with pairwise additive HI is : $\text{drift term} = \beta \mathbf{F} \cdot \sum_{i,j=1}^N \nabla_i \cdot \mathbf{D}_{ij}^{(2)} P_{eq} = 0$

$$\mathbf{D}_{ij}^{(2)}(\mathbf{r}_1 + \mathbf{x}, \dots, \mathbf{r}_N + \mathbf{x}) = \mathbf{D}_{ij}^{(2)}(\mathbf{r}_1, \dots, \mathbf{r}_N)$$

- P_{eq} is homog. solution of GSE for pairwise additive HI and DI

- Assume pairwise additive HI :

$$\mathbf{D}_{ij}^{(2)}(\mathbf{r}^N) = D_0 \mathbf{1} \delta_{ij} + \Delta \mathbf{D}_{ij}^{(2)}(\mathbf{r}^N) = D_0 \mathbf{1} \delta_{ij} + D_0 \left[\delta_{ij} \sum_{l \neq j}^N \boldsymbol{\omega}_{11}(\mathbf{r}_{lj}) + (1 - \delta_{ij}) \boldsymbol{\omega}_{12}(\mathbf{r}_{lj}) \right]$$

$$\nabla_i \cdot \mathbf{D}_{ij}^{(2)} = \nabla_i \cdot \boldsymbol{\omega}_{12}(\mathbf{r}_i - \mathbf{r}_j) = -\nabla_j \cdot \boldsymbol{\omega}_{12}(\mathbf{r}_i - \mathbf{r}_j) = -\nabla_j \cdot \mathbf{D}_{ij}^{(2)} \quad (i \neq j), \quad \mathbf{D}_{ij}^{(2)} = \mathbf{D}_{ji}^{(2)}$$

$$\text{drift term} = \beta \mathbf{F} \cdot \sum_{i,j=1}^N \nabla_i \cdot \mathbf{D}_{ij}^{(2)} P_{\text{eq}} = \beta P_{\text{eq}} \mathbf{F} \cdot \left\{ \sum_{i,j=1}^N \nabla_i \cdot \mathbf{D}_{ij}^{(2)} + \beta \sum_{i,j=1}^N \mathbf{D}_{ij}^{(2)} \cdot \mathbf{F}_j^p \right\} = 0$$

- Reason for zero drift term :

$$\sum_{i,j=1}^N \nabla_i \cdot \mathbf{D}_{ij}^{(2)} = \frac{1}{2} \sum_{i,j=1}^N \underbrace{(\nabla_i \cdot \mathbf{D}_{ij}^{(2)} + \nabla_j \cdot \mathbf{D}_{ij}^{(2)})}_{=0} + \sum_{i=1}^N \nabla_i \cdot \mathbf{D}_{ii}^{(2)}$$

$$\sum_{i=1}^N \nabla_i \cdot \mathbf{D}_{ii}^{(2)} = \sum_{i,l=1}^N \nabla_i \cdot \boldsymbol{\omega}_{11}(\mathbf{r}_i - \mathbf{r}_l) = \frac{1}{2} \sum_{i,l=1}^N (\nabla_i \cdot \boldsymbol{\omega}_{11}(\mathbf{r}_i - \mathbf{r}_l) + \nabla_l \cdot \boldsymbol{\omega}_{11}(\mathbf{r}_i - \mathbf{r}_l)) = 0$$

$$\beta \sum_{i,j=1}^N \mathbf{D}_{ij}^{(2)} \cdot \mathbf{F}_j^p = 0 \quad \Leftrightarrow \text{zero macroscopic current since pair forces with actio = - reactio}$$

$$\mathbf{F}_j^p = -\sum_{l \neq j} \nabla_j u(r_{jl}) = \sum_{l \neq j} \mathbf{f}_{jl}, \quad (\mathbf{f}_{jl} = -\mathbf{f}_{lj})$$

- Calculation of mean sedimentation velocity U_{sed} at small Peclet numbers :

$$\frac{\partial}{\partial t} P_{\text{st}}(\mathbf{X}) = 0 = - \sum_{i=1}^N \nabla_i \cdot (\mathbf{v}_i(\mathbf{X}) P_{\text{st}}(\mathbf{X})) \quad P_{\text{st}} = P_{\text{st}}(\mathbf{X}; \mathbf{F})$$

$$U_{\text{sed}} = \left\langle \frac{1}{N} \sum_{i=1}^N \mathbf{v}_i(\mathbf{X}) \right\rangle_{\text{st}} = \left\langle \frac{1}{N} \sum_{i,l=1}^N \beta \mathbf{D}_{il} \cdot \left[\underbrace{\mathbf{F}_l^p - k_B T \nabla_l \ln P_{\text{st}}(\mathbf{X})}_{\substack{\text{long-time (memory) part of } U_{\text{sed}} \\ \text{vanishes for PA - HI where } P_{\text{st}} = P_{\text{eq}}}} + \mathbf{F} \right] \right\rangle_{\text{st}} \quad \mathbf{F}_l^p = -\nabla_l U(\mathbf{X})$$

- Since $Pe \ll 1$, find from GSE stationary Pdf to linear order in external force :

$$P_{\text{st}}(\mathbf{X}) = P_{\text{eq}}(\mathbf{X}) \left[1 - \beta \mathbf{F} \cdot \int_0^\infty du e^{\hat{O}_B^0 u} \sum_{j=1}^N \mathbf{v}_j^I \right] + O(\mathbf{F}^2)$$

$$\frac{U_{\text{sed}}}{U_0} = \underbrace{\left\langle \frac{1}{N D_0} \sum_{i,l=1}^N \hat{\mathbf{q}} \cdot \mathbf{D}_{il} \cdot \hat{\mathbf{q}} \right\rangle_{\text{eq}}}_{H(q=0) : \text{short-time part}} - \underbrace{\frac{1}{N D_0} \sum_{i,l=1}^N \int_0^\infty du \left\langle \hat{\mathbf{q}} \cdot \mathbf{v}_i^I e^{\hat{O}_B^0 u} \hat{\mathbf{q}} \cdot \mathbf{v}_l^I \right\rangle_{\text{eq}}}_{\substack{\text{memory-part (zero for PA-HI)} \\ \text{(Green-Kubo-type formula)}}}$$

$$\hat{O}_B^0 = \hat{O}_B(\mathbf{F} = 0)$$

$$U_{\text{sed}} = U_{\text{sed}} \hat{\mathbf{q}}$$

$$\mathbf{v}_i^I = \hat{O}_B^0 \mathbf{r}_i$$

$$\hat{O}_B^0 = \hat{O}_B(\mathbf{F} = 0)$$

$$U_{\text{sed}} = U_{\text{sed}} \hat{\mathbf{q}}$$

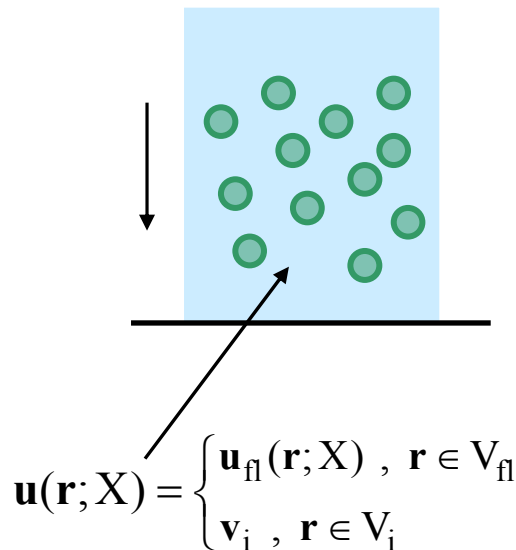
$$\mathbf{v}_i^I = \hat{O}_B^0 \mathbf{r}_i$$

Short-time transport property $\leq$ Long-time transport property

- Smoluchowski's paradoxon :

$$H(q=0) = 1 + \rho \underbrace{\int d\mathbf{r} g(\mathbf{r}) \hat{\mathbf{q}} \cdot \omega_{12}^{\text{RP}}(\mathbf{r}) \cdot \hat{\mathbf{q}}}_{\rightarrow \infty} + \text{regular part}$$

- Resolution : macroscop. solvent backflow due to container boundaries



- consider container bottom explicitly (Mazur & van Saarloos, '78)
- use zero volume flux condition for planes $\perp$ to $\mathbf{F}$ (Batchelor, '72)

$$\underbrace{\int_{V_c} d\mathbf{r} \langle \mathbf{u}(\mathbf{r}; X) \rangle_{\text{st}}}_{V_c \langle \mathbf{u} \rangle_{\text{sa}}} = \mathbf{0} = \int dS_{\perp} \langle \mathbf{u}(\mathbf{r}; X) \rangle_{\text{st}} \quad \text{rest frame of container}$$

$$-\nabla \langle p \rangle_{\text{sa}} = -\rho \mathbf{F} \quad \text{drives backflow}$$

- use that : $U_{\text{sed}}^{\text{S}} - \langle \mathbf{u}(\mathbf{r}; X) \rangle = U_0 \lim_{q \rightarrow 0} \lim_{\infty} H(q) \neq U_0 H(q=0)$

relative to ensemble averaged volume flow velocity, then
container-shape & position independent (c.f. intrinsic convection) ¹²⁶

Assume spatially periodic weak external force is acting on each sphere :

$$\mathbf{F}_j^{\text{ext}} = \hat{\mathbf{q}} F(q) \exp[-i\mathbf{q} \cdot \mathbf{r}_j]$$

weak external force on sphere j

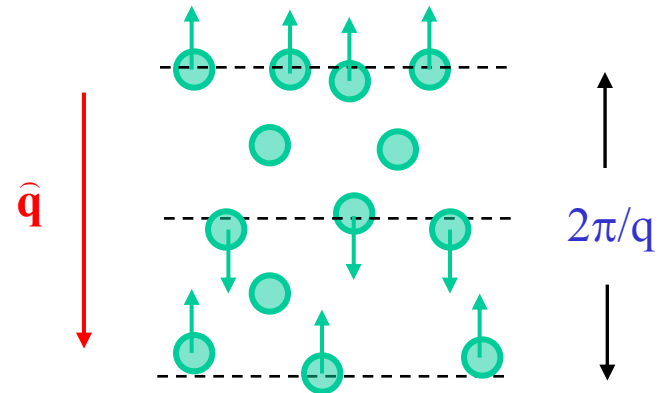
$$\langle V(q) \rangle = \left\langle \frac{1}{N} \sum_{j=1}^N \hat{\mathbf{q}} \cdot \mathbf{v}_j \exp[i\mathbf{q} \cdot \mathbf{r}_j] \right\rangle$$

mean (short-time) response

$$\frac{\langle V(q) \rangle}{U_0(q)} = H(q)$$

$$\lim_{q \rightarrow 0} \langle V(q) \rangle = U_{\text{sed}}^s$$

$$U_0(q) = b_0 F(q) = \beta D_0 F(q)$$



- no macroscopic backflow for non-macroscopic q^{-1} (no regularization necessary)

- $U_{\text{sed}}^L = U_{\text{sed}}^S - \Delta U_{\text{sed}}^L$: long-time part usually small (needs regularization, too)

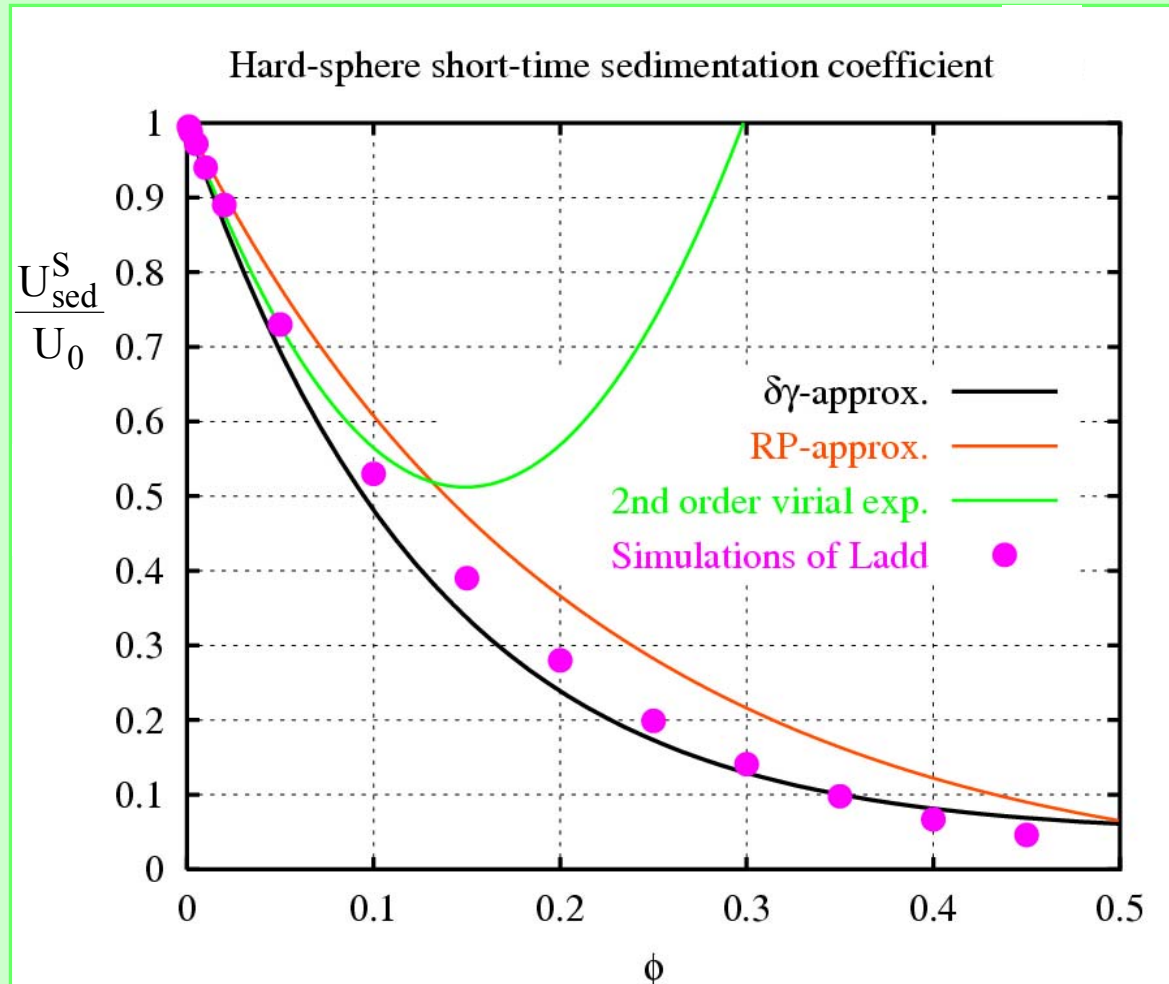
hard spheres (HS): $|\Delta U_s^L| / U_s^S < 6 \%$ (at $\phi = 0.45$)

charged spheres (CS): $\left\{ \begin{array}{l} \text{comparably small (no lubrication)} \\ \text{truncated 2-body HI sufficient for } \phi < 5 - 15 \% \end{array} \right.$

- (Short-time) sedimentation on Rotne - Prager level (zero volume velocity frame) :

$$\frac{U_{\text{sed}}^S}{U_0} = 1 - \phi \left[5 + 12 \underbrace{\int_1^\infty dx \, x (1 - g(x; \phi))}_{\text{known analytically for hard spheres in PY}} + \frac{15}{8} \int_1^\infty dx \, \frac{g(x; \phi)}{x^2} \right] \quad x = r/2a$$

$$\left(\frac{U_{\text{sed}}^S}{U_0} \right)_{\text{HS}} = \begin{cases} (1 - \phi)^3 / (1 + 2\phi) \approx 1 - 5\phi + 5\phi^2 & \text{in RP-PY} \\ 1 - 6.546\phi + 21.918\phi^2 + ? & \text{exact (Cichocki et al., '02)} \end{cases}$$



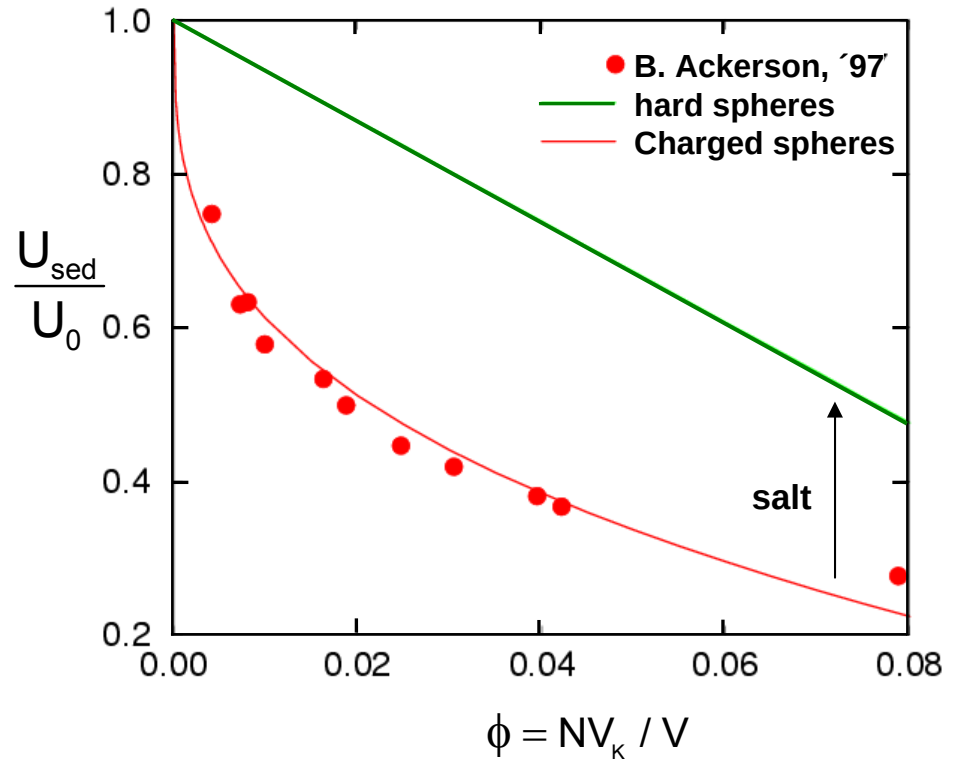
- near-field HI less important for sedimentation

- charged spheres :
(Nägele & Watzlawek, PRE '97)

$$U_{\text{sed}} / U_0 \approx 1 - 1.8\phi^{1/3}$$

- neutral hard spheres :
(Batchelor '72, Cichocki et al. '02)

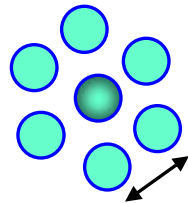
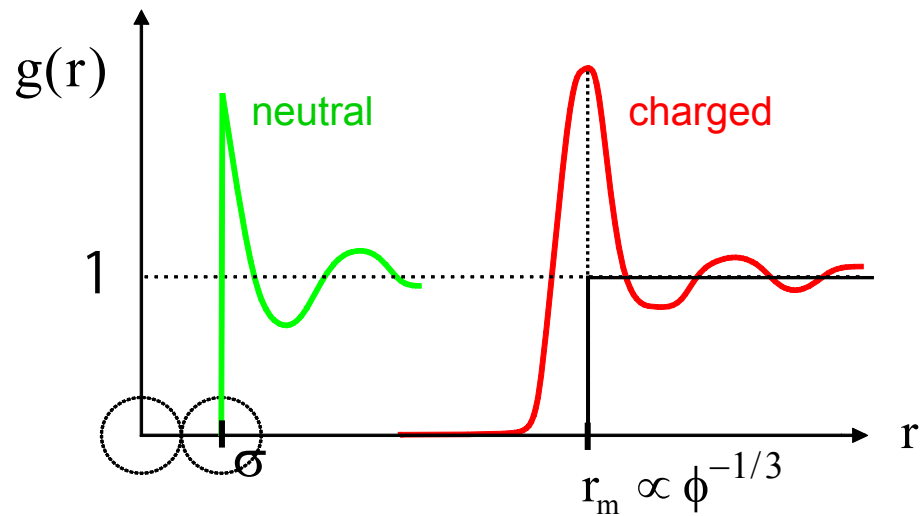
$$U_{\text{sed}} / U_0 \approx 1 - 6.55\phi + 21.92\phi^2$$



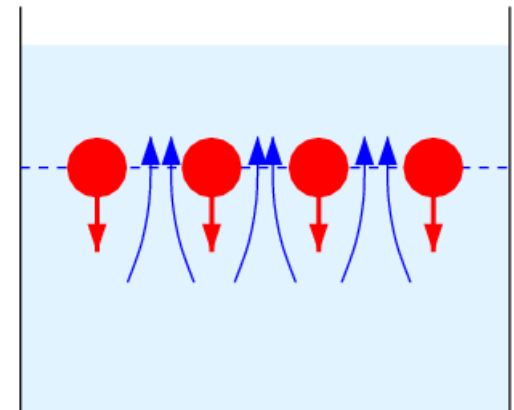
- charged particles sediment more slowly (sweet-water river delta)

- Charged colloids : non-linear density-dependence of transport coeff.

Radial distribution function



Solvent backflow



- Rough model of effective hard spheres :

$$g(r) \approx \Theta(r - \sigma_{\text{eff}}) \quad \sigma_{\text{eff}} = r_m \propto \phi^{-1/3}$$

$$\frac{U_{\text{sed}}}{U_0} \approx 1 + \phi \left[-6 \left(\frac{\sigma_{\text{eff}}}{\sigma} \right)^2 + \dots \right] \approx 1 - 6\phi^{1/3}$$



Oseen point-force approx.

Smoluchowski equation with incident fluid flow

$$\frac{\partial}{\partial t} P(\mathbf{X}, t) + \sum_{i=1}^N \nabla_i \cdot (\mathbf{v}_i(\mathbf{X}) P(\mathbf{X}, t)) = 0$$

- Force balance in presence of incident flow $\mathbf{u}_0$ compatible with homog. Stokes eqs.
- Assume hydrodynamically torque-free spheres

$$\mathbf{v}_i - \mathbf{v}_{ic}(\mathbf{X}; [\mathbf{u}_0]) = -\beta \sum_{l=1}^N \mathbf{D}_{il}^{tt}(\mathbf{X}) \cdot [\mathbf{F}_l^H = -\mathbf{F}_l^p - \mathbf{F}_l^{\text{ext}} - \mathbf{F}_l^B]$$

↑ ↑ indep. of $\mathbf{u}_0$

velocity of force- and torque-free sphere i advected by surrounding fluid (linear functional of $\mathbf{u}_0$)

$$\mathbf{v}_{ic} = \mathbf{u}_0(\mathbf{r}_i) + \int d\mathbf{r}' \mathbf{C}_i^{(k)}(\mathbf{r}'; \mathbf{X}) \cdot \mathbf{u}_0(\mathbf{r}') = \mathbf{u}_0(\mathbf{r}_i) + \mathbf{C}_i(\mathbf{X}) : \mathbf{e}_0$$

convection kernel

linear flow

3rd rank shear mobility tensor: $O(r^{-3})$

$$\frac{\partial}{\partial t} P(\mathbf{X}, t) = \underbrace{\sum_{i,j=1}^N \nabla_i \cdot \mathbf{D}_{ij} \cdot [\nabla_j - \beta \mathbf{F}_j^p] P}_{\text{drift term (e.g. gravity)}} - \underbrace{\sum_{i,j=1}^N \nabla_i \cdot \mathbf{D}_{ij} \cdot [\beta \mathbf{F}_j^{\text{ext}} P]}_{\text{drift term (e.g. gravity)}} - \underbrace{\sum_{i=1}^N \nabla_i \cdot [\mathbf{v}_{ic} P]}_{\text{convective term}}$$

- Convective term vanishes in constant flow field $\mathbf{v}_B$ for homogeneous system
- Mere system translation with constant velocity does not affect Pdf („Galilei“-invariance)

$$\sum_{i=1}^N \nabla_i \cdot [\mathbf{v}_B P] = \mathbf{v}_B \cdot \sum_{i=1}^N \nabla_i \cdot P \stackrel{?}{=} 0$$

translationally invariant system

- Application: uniform backflow does not change form of stationary homogeneous Pdf

$$\frac{\partial}{\partial t} P(X, t) = (\hat{O} + \hat{O}_{\text{adv}}) P(X, t)$$

$$\hat{O}_{\text{adv}} = -\nabla \cdot \mathbf{v}_c(X)$$

$$\hat{O}_{\text{adv}}^\dagger = \nabla \cdot \mathbf{v}_c(X)$$

- Flow-perturbed (advective) part of Smoluchowski-op. not self-adjoint w/r to $\langle | \rangle$,
contrary to the unperturbed part

Collective and gradient diffusion

$$\frac{\partial}{\partial t} S(\mathbf{q}, t) = - \underbrace{q^2 D_0 \frac{H(\mathbf{q})}{S(\mathbf{q})}}_{\tau_B \ll t \ll \tau_I} S(\mathbf{q}, t) + \underbrace{\int_0^t du M_c(\mathbf{q}, t-u) \frac{S(\mathbf{q}, u)}{S(\mathbf{q})}}_{t \gg \tau_I \text{ cage relaxation}}$$

$$M_c(t) = \left\langle f_{\mathbf{q}}^c \mid e^{\hat{Q}_c \hat{O}_B^0 \hat{Q}_c t} f_{\mathbf{q}}^c \right\rangle$$

$$S(\mathbf{q}, t) \approx S(\mathbf{q}) \exp[-q^2 D_C^S(\mathbf{q}) t] \quad (\tau_B \ll t \ll \tau_I)$$

$$D_C^S(\mathbf{q}) := D_0 \frac{H(\mathbf{q})}{S(\mathbf{q})}$$

$$D_C^S = \lim_{q \rightarrow 0} \frac{H(\mathbf{q})}{S(\mathbf{q})}$$

short-time collective
diffusion coefficient

$$\exp\{-q^2 D_C^L\} = \lim_{t \rightarrow \infty} \lim_{q \rightarrow 0} \frac{S(\mathbf{q}, t)}{S(\mathbf{q})}$$

long-time collective or
gradient diffusion coeff.

$$(q^2 t = O(1))$$

hydrodynamic
limit

$$f_{\mathbf{q}}^c = i\mathbf{q} \cdot \frac{1}{\sqrt{N}} \sum_{i=1}^N \underbrace{\mathbf{v}_i^I}_{\substack{\text{zero mean drift velocity} \\ \text{for pairwise-additive DI \& HI} \\ \text{(no external force)}}} + O(q^2)$$



$$\lim_{q \rightarrow 0} \frac{1}{q^2} M_C(\mathbf{q}, t) = 0$$

$$D_C^S = D_L^S$$

pairwise-additive DI & HI

- Green-Kubo relation from memory eq. & definition of gradient diffusion coefficient :

$$D_c^L = D_c^S - \lim_{q \rightarrow \infty} \frac{1}{S(q)} \int_0^\infty dt \left\langle j_q^c \mid e^{\hat{Q}_c \hat{O}_B^0 \hat{Q}_c t} j_q^c \right\rangle$$

$$j_q^c = \frac{1}{iq} O_0^B c_q$$

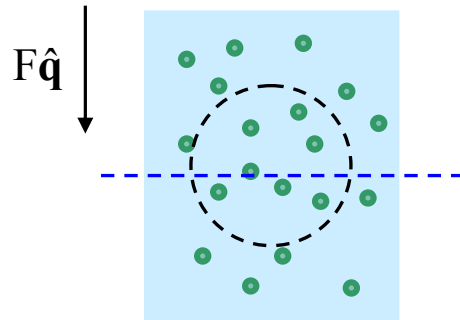
Fourier-comp. of microscop.
density fluctuations

- Comparison with Green-Kubo relation for U_{sed} shows that :

$$\frac{D_c^L}{D_c^S} = \frac{U_{\text{sed}}^L}{U_{\text{sed}}^S}$$

$$D_c^L = \frac{D_0}{S(0)} \frac{U_{\text{sed}}^L}{U_0}$$

- Macroscopic phenomenological “derivation” from zero total flux balance in steady-state :



The diagram shows a light blue rectangular container filled with green dots representing particles. A dashed horizontal line is drawn across the middle of the container. A vertical arrow labeled $F\hat{q}$ points downwards from the top left corner. A dashed circle is drawn in the center of the container, containing several green dots.

$$0 = \mathbf{j}_{\text{sed}} + \mathbf{j}_{\text{diff}} = \rho_0 U_{\text{sed}}^L \hat{\mathbf{q}} - D_C^L \nabla \rho$$

small gradients, osmotic equil.

$$\nabla \rho = \left(\frac{\partial \rho_0}{\partial p} \right)_{T, \mu_s}$$

pressure gradient due to container bottom

$$\nabla p = \beta S(0) \rho_0 F \hat{\mathbf{q}}$$

Gradient diffusion

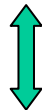
- Gradient diffusion: $q \ll q_m$

$$S(q, t) \approx S(q) \exp[-q^2 D_c t]$$

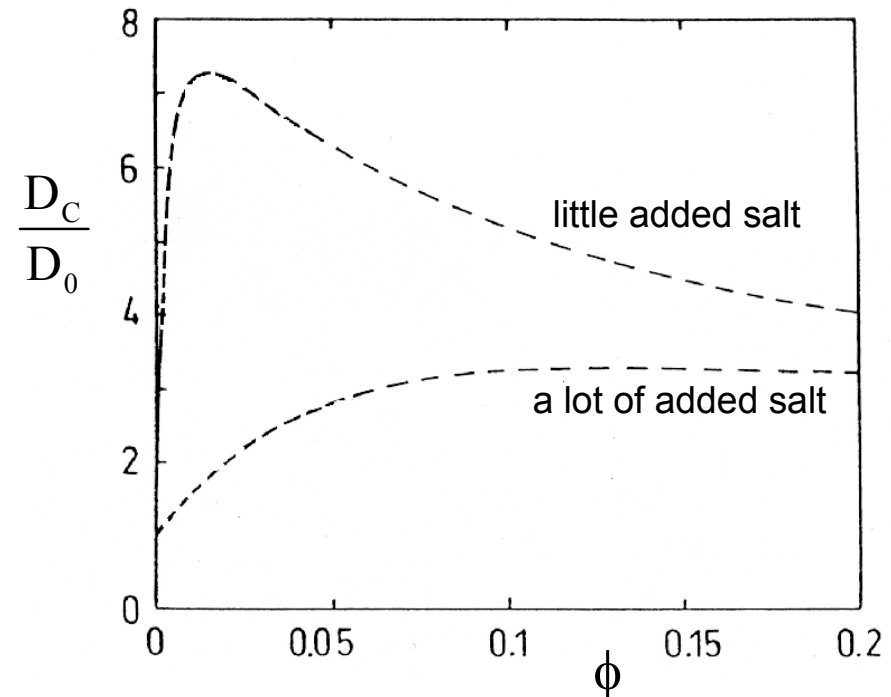
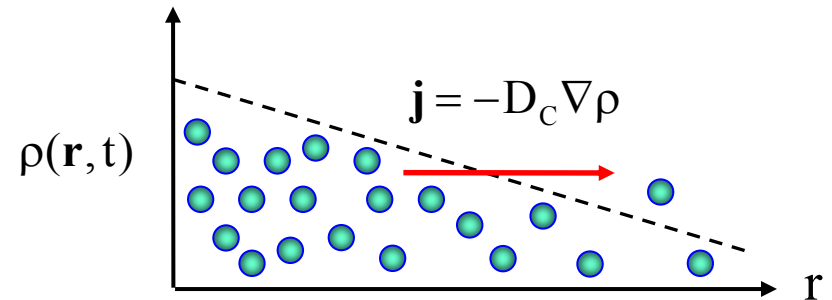
$$\frac{D_c}{D_0} = \lim_{q \rightarrow 0} \frac{H(q)}{S(q)} = \frac{U_{\text{sed}} / U_0}{k_B T (\partial \bar{p} / \partial p)_T}$$

osmotic pressure

Hydrodynamic interaction : U_{sed} / U_0



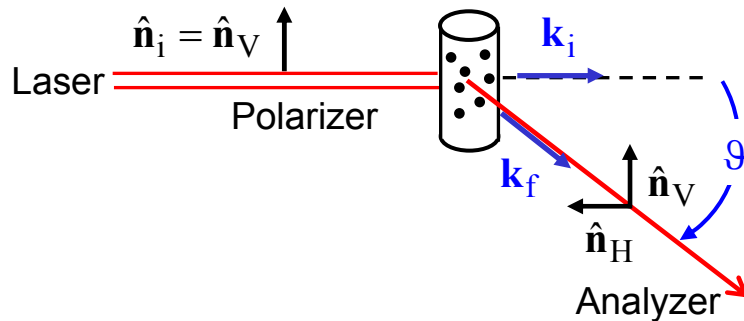
Osmotic compressibility



(G.N., Phys. Reports '95)

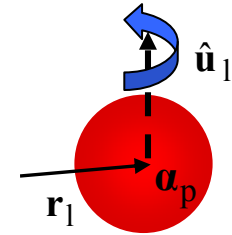
Rotational self-diffusion

Homogeneous spheres with single optical axis pointing along $\hat{\mathbf{u}}_1$



$$\alpha = (\Delta\alpha_{\parallel} + 2\Delta\alpha_{\perp})/3$$

$$\beta = \alpha_{\parallel} - \alpha_{\perp} \quad \text{particle anisotropy (solvent-indep.)}$$



$$\mathbf{E}_S(\mathbf{q}) \propto \frac{e^{i\mathbf{k}_i \cdot \mathbf{R}}}{\lambda^2 R} \mathbf{E}_0 \sum_{l=1}^N e^{i\mathbf{q} \cdot \mathbf{r}_l} \hat{\mathbf{n}}_f \cdot (\mathbf{1} - \hat{\mathbf{k}}_f \hat{\mathbf{k}}_f) \cdot \mathbf{B}_l(\mathbf{q}) \cdot \hat{\mathbf{n}}_i$$

$$\mathbf{B}_l(\mathbf{q}) \propto \left\{ \left(\alpha_{\parallel}^l - \alpha_s \right) \hat{\mathbf{u}}_l \hat{\mathbf{u}}_l + \left(\alpha_{\perp}^l - \alpha_s \right) \left(\mathbf{1} - \hat{\mathbf{u}}_l \hat{\mathbf{u}}_l \right) \right\}$$

$$\propto \left\{ \alpha \mathbf{1} + \beta \left(\hat{\mathbf{u}}_l \hat{\mathbf{u}}_l - \frac{1}{3} \mathbf{1} \right) \right\}$$

From depolarized DLS in VH-geometry one determines electric field ACF :

$$g_E^{\text{VH}}(\mathbf{q}, t) \propto \beta^2 G(\mathbf{q}, t) G_r(t)$$

rotat.-transl. decoupling approx. for $t \sim \tau_1^r = 1/D_0^r$

$$G_r(t) = \langle P_2(\hat{\mathbf{u}}_1(t) \cdot \hat{\mathbf{u}}_1(0)) \rangle$$

rotational self-correlation function

$$P_2(x) = (3x^2 - 1)/2$$

- Hypothetical case : spheres interacting only by isotropic DI (no HI)

$$g_E^{VH}(q, t) \propto \beta^2 \left[e^{-q^2 W(t)} (1 + \text{non-gaussian corr.}) \right] e^{-6 D_0^r t}$$

$$D_0^r = \frac{k_B T}{\zeta_0^r} = \frac{k_B T}{8\pi\eta_0 a^3}$$

independent spheres rotation

$$\left\langle [\hat{\mathbf{u}}(t) - \hat{\mathbf{u}}(0)]^2 \right\rangle_0 = 2 \left[1 - e^{-2t/\tau_r} \right] = \begin{cases} 4 D_0^r t, & \tau_B^r \ll t \ll \tau_I^r \\ 2, & t \gg \tau_I^r \end{cases}$$

$$\tau_B^r = \frac{(2/5)Ma^2}{\zeta_0^r} = \frac{3}{10} \tau_B$$

$$\tau_I^r = 1/D_0^r = (4/3)\tau_I$$

- Totally non-interacting spheres (very low concentration) :

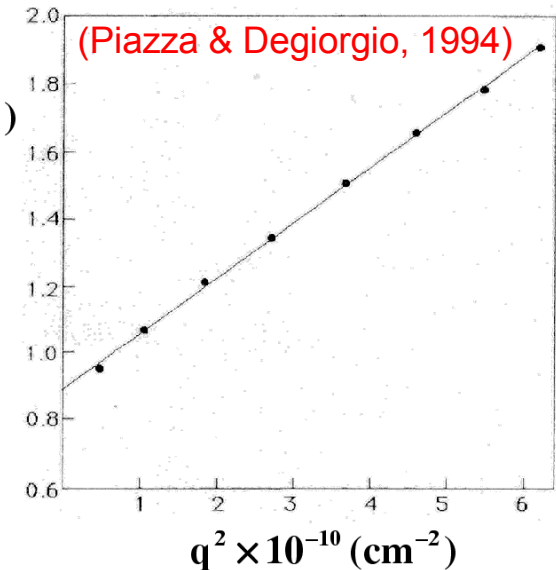
$$\Gamma_{VH} \times 10^{-3} (\text{s}^{-1})$$

$$g_E^{VH}(q, t) \propto \beta^2 e^{-(q^2 D_0 + 6 D_0^r)t}$$

- Initial decay rate : $\Gamma_{VH}(q) = - \lim_{t \rightarrow 0} \frac{d}{dt} \ln g_E^{VH}(q, t)$

$$= q^2 D_0 + 6 D_0^r$$

→ hydrodynamic sphere radius a



- Spheres with DI and HI : short-time rotational self-diffusion :

$$G_r(t) = e^{-6\mathbf{D}_s^r t}, \quad \tau_B^r \ll t \ll \tau_I^r \quad \mathbf{D}_s^r = -\frac{1}{6} \lim_{t \rightarrow 0} \frac{\partial \ln G_r(t)}{\partial t} \leq D_0^r$$

- From Smoluchowski equation for spheres including rotational degrees of freedom :

$$\frac{\partial}{\partial t} P(\mathbf{r}^N, \mathbf{u}^N | t) = \left[\hat{O}^{tt}(\mathbf{r}^N, \mathbf{u}^N) + \hat{O}^{tr}(\mathbf{r}^N, \mathbf{u}^N) + \hat{O}^{rt}(\mathbf{r}^N, \mathbf{u}^N) + \hat{O}^{rr}(\mathbf{r}^N, \mathbf{u}^N) \right] P$$

$$\mathbf{D}_s^r = \left\langle \hat{\mathbf{q}} \cdot \mathbf{D}_{11}^{rr}(\mathbf{r}^N) \cdot \hat{\mathbf{q}} \right\rangle_{\text{eq}} \quad \begin{pmatrix} \mathbf{v} \\ \boldsymbol{\omega} \end{pmatrix} = \beta \begin{pmatrix} \mathbf{D}^{tt}(X) & \mathbf{D}^{tr}(X) \\ \mathbf{D}^{rt}(X) & \mathbf{D}^{rr}(X) \end{pmatrix} \cdot \begin{pmatrix} \mathbf{F} \\ \mathbf{T} \end{pmatrix}$$

$$\boldsymbol{\omega}_1 = \beta \mathbf{D}_{11}^{rr}(X) \cdot \mathbf{T}_1, \quad (\mathbf{F}_j = 0 = \mathbf{T}_j \text{ for } j \neq 1)$$

$$\mathbf{T}_i^H = -8\pi\eta_0 a^3 \left[\boldsymbol{\omega}_i - \frac{1}{2} \nabla_i \times (\mathbf{u}_{N-1}(\mathbf{r}_i; X) + \mathbf{u}_0(\mathbf{r}_i)) \right] \quad \text{generalized rotational Faxén law (stick BCs)}$$

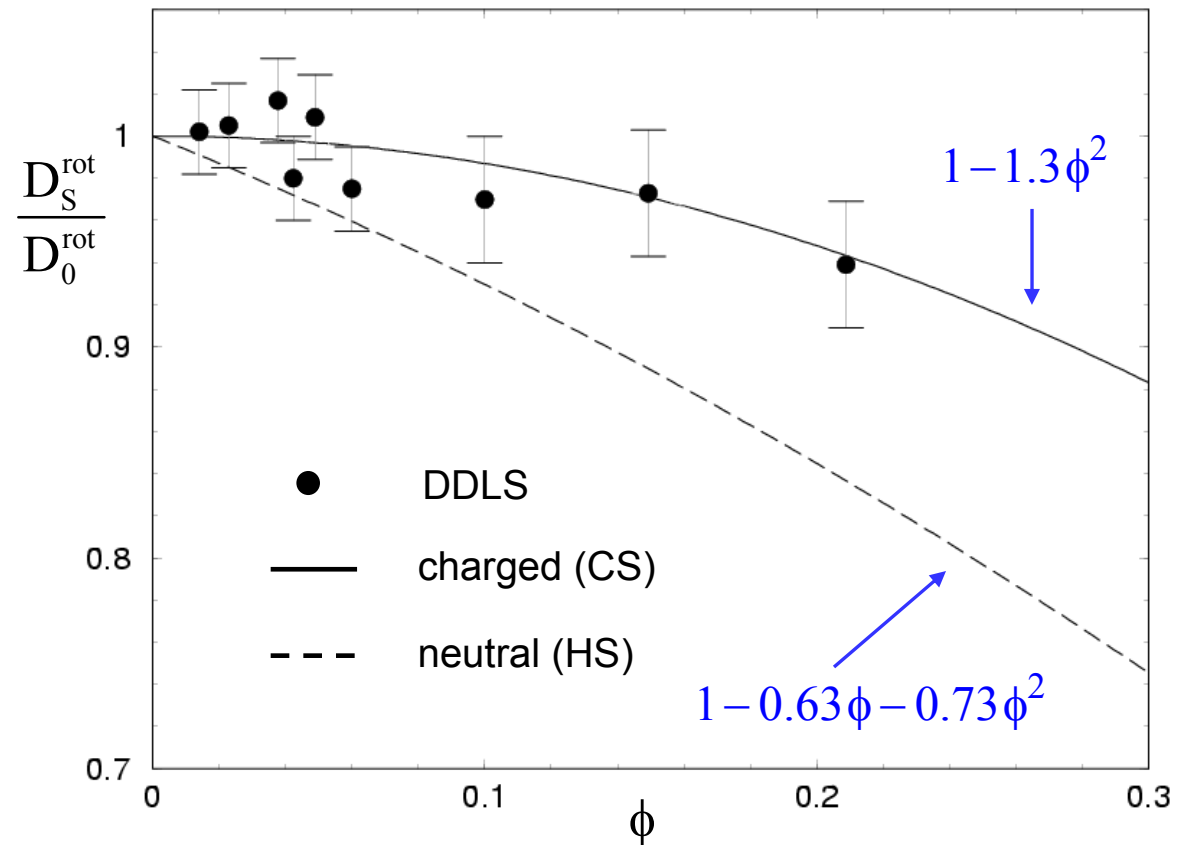
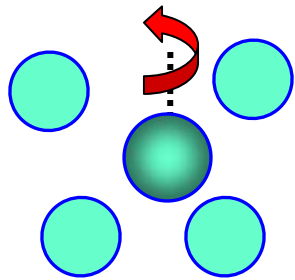
$$\mathbf{D}_{11}^{rr}(\mathbf{r}^N) = D_0^r \mathbf{1} + \underbrace{\Delta \mathbf{D}_{11}^{rr(2)}(\mathbf{r}^N)}_{\text{2-body HI}} + \underbrace{\Delta \mathbf{D}_{11}^{rr(3)}(\mathbf{r}^N)}_{\text{3-body HI}} + \dots$$

$$\Delta \mathbf{D}_{11}^{\text{rr}(2)}(\mathbf{r}^{\text{N}}) = \mathbf{D}_0^{\text{r}} \sum_{l \neq j}^{\text{N}} \boldsymbol{\omega}_{11}^{\text{rr}}(\mathbf{r}_{lj}) \qquad \Delta \mathbf{D}_{11}^{\text{rr}(3)}(\mathbf{r}^{\text{N}}) = \mathcal{O}(r^{-9})$$

Long-distance multipole expansion of 2-body HI :

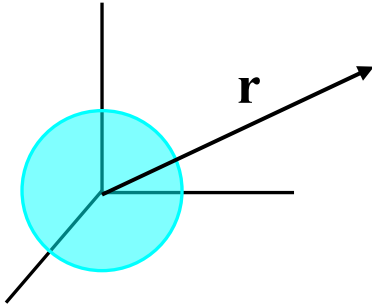
$$\boldsymbol{\omega}_{11}^{\text{rr}}(\mathbf{r}) = \underbrace{-\frac{15}{4} \left(\frac{a}{r} \right)^6}_{\text{first self-reflection}} \left[\mathbf{1} - \hat{\mathbf{r}} \hat{\mathbf{r}} \right] + \mathcal{O}(r^{-8})$$

Charged spheres versus hard spheres



- DDLS: Bitzer, Palberg & Leiderer (Konstanz, '97)
- CS with 3-body HI: Nägele, Watzlawek & Zhang, Physica A '97 & JCP '02
- HS with 3-body HI: Cichocki et al., JCP '99

- Flow field $\mathbf{u}_0(\mathbf{r})$ of single sphere in origin with transl. velocity $\mathbf{v}_0$ and rotat. velocity $\boldsymbol{\omega}_0$
- Stick BC on sphere surface and quiescent unbound fluid



$$\mathbf{u}(\mathbf{r}) \Big|_{r \geq a} = \underbrace{\left[\frac{3}{4} \left(\frac{a}{r} \right) (\mathbf{1} + \hat{\mathbf{r}} \hat{\mathbf{r}}) + \frac{1}{4} \left(\frac{a}{r} \right)^3 (\mathbf{1} - 3\hat{\mathbf{r}} \hat{\mathbf{r}}) \right]}_{\zeta_0 \left(\mathbf{1} + \frac{a^2}{6} \nabla^2 \right) \mathbf{T}_0(\mathbf{r})} \cdot \mathbf{v}_0 + \left(\frac{a}{r} \right)^3 \boldsymbol{\omega}_0 \times \mathbf{r}$$

$$\mathbf{u}(\mathbf{r}) \Big|_{r=a} = \mathbf{v}_0 + \boldsymbol{\omega}_0 \times (a \hat{\mathbf{r}})$$

8. Long-time dynamics

- **Generalized hydrodynamics**
- **Mode coupling approximation of memory functions**
- **Application: non-exponential decay of dynamic structure factor**

Generalized hydrodynamics

- Phenomenological starting point :

$$\frac{\partial}{\partial t} \bar{\rho}(\mathbf{r}, t) + \nabla \cdot \bar{\mathbf{j}}(\mathbf{r}, t) = 0 \quad \bar{\rho}(\mathbf{r}, t) = \frac{1}{\Delta V} \int d\mathbf{x} \rho(\mathbf{x}, t)$$

$$\bar{\mathbf{j}}(\mathbf{r}, t) = - \int_0^t dt' \int d\mathbf{r}' \mathbf{D}_c(|\mathbf{r} - \mathbf{r}'|, t - t') \cdot \nabla' \bar{\rho}(\mathbf{r}', t')$$

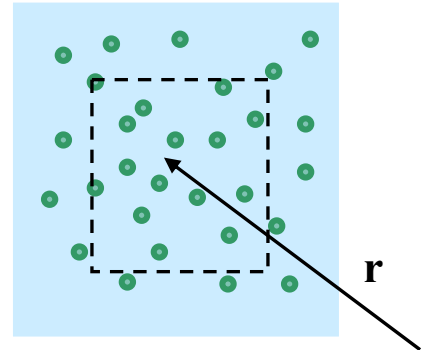
$$S(\mathbf{q}, t) = \frac{V}{N} \int d(\mathbf{r}' - \mathbf{r}) e^{i\mathbf{q} \cdot (\mathbf{r}' - \mathbf{r})} \langle \bar{\rho}(\mathbf{r}', 0) \bar{\rho}(\mathbf{r}, t) \rangle$$

→

$$\tilde{S}(\mathbf{q}, z) = \int_0^\infty dt e^{-zt} S(\mathbf{q}, t) = \frac{S(\mathbf{q})}{z + q^2 \tilde{D}_c(\mathbf{q}, z)}$$

$$\tilde{D}_c(\mathbf{q}, z) = \int_0^t dt e^{-zt} \int d\mathbf{r} e^{i\mathbf{q} \cdot \mathbf{r}} \hat{\mathbf{q}} \cdot \mathbf{D}_c(\mathbf{r}, t) \cdot \hat{\mathbf{q}} \geq 0$$

spectrum of relaxation frequencies z



$$\mathbf{D}_c^L = \tilde{D}_c(q \rightarrow 0, z \rightarrow 0) \longleftrightarrow S(q \ll q_m, t \gg \tau_I) \propto \exp\{-q^2 \mathbf{D}_c^L t\} \quad \text{hydrodyn. limit}$$

$$\mathbf{D}_c^S(q) = \tilde{D}_c(q, z \rightarrow \infty) \longleftrightarrow S(q, t \ll \tau_I) \propto \exp\{-q^2 \mathbf{D}_c^S(q) t\} \quad \text{short-time limit}$$

- Split $\tilde{D}_c^L(q, z)$ in instantaneous & relaxational part : $\tilde{D}_c(q, z) = D_0 \frac{H(q)}{S(q)} - \frac{\tilde{M}(q, z)}{q^2 S(q)} \geq 0$

$$\frac{\partial}{\partial t} S(q, t) = - \underbrace{q^2 D_0 \frac{H(q)}{S(q)}}_{=: 1/\tau_s(q)} S(q, t) + \int_0^t du \mathbf{M}_c(q, t-u) \frac{S(q, u)}{S(q)}$$

approximation of M_c might violate positivity for strong coupling

- Define generalized friction kernel function $\tilde{\zeta}_c(q, z)$ through :

$$\tilde{\zeta}_c(q, z) = \frac{k_B T / S(q)}{\tilde{D}_c(q, z)} \longrightarrow \zeta_0 = \frac{k_B T}{D_0} \quad (\rho \rightarrow 0)$$

- Again, split in instantaneous and relaxational part : $\tilde{\zeta}_c(q, z) = \frac{\zeta_0}{H(q)} + \Delta \tilde{\zeta}_c(q, z)$

- Define so-called irreducible memory function by : $\tilde{m}_c^{\text{irr}}(q, z) = \frac{H(q)}{\zeta_0} \Delta \tilde{\zeta}_c(q, z)$

$$\tilde{S}(q, z) = \frac{S(q)}{z + \frac{\tau_s(q)^{-1}}{1 + \tilde{m}_c^{\text{irr}}(q, z)}}$$

renormalizes short-time lifetime of density fluctuations

$$\frac{\partial}{\partial t} S(q, t) = - \frac{1}{\tau_s(q)} S(q, t) - \int_0^t du \mathbf{m}_c^{\text{irr}}(q, t-u) \frac{\partial S(q, u)}{\partial u}$$

- best suited for memory approximations
- can preserve positivity of $\tilde{D}_c(q, z)$

Mode coupling approximation of memory functions

- Microscopic expression for irreducible memory function : Nägele & Baur, Physica A (1997)

$$m_c^{\text{irr}}(q, t) = \frac{1}{q^2 D_0 H(q)} \underbrace{\left\langle f_q^c \left| e^{\hat{\Omega}_c^{\text{irr}} t} f_q^c \right\rangle \right.}_{=: M_c^{\text{irr}}(q, t)}$$

$$\hat{\Omega}_c^{\text{irr}} = \hat{Q}_c \left[\hat{O}_B + \frac{1}{q^2 D_0 H(q)} |f_q^c\rangle \langle f_q^c| \right] \hat{Q}_c$$

irreducible Smoluchowski op.
for collective diffusion

- for comparison :

$$M_c(q, t) = \left\langle f_q^c \left| e^{\hat{Q}_c \hat{O}_B^0 \hat{Q}_c t} f_q^c \right\rangle$$

$$M_c^{\text{un}}(q, t) = \left\langle f_q^c \left| e^{\hat{O}_B^0 t} f_q^c \right\rangle \quad \leftarrow \text{unreduced force-force ACF}$$

- Relations among various force ACFs :

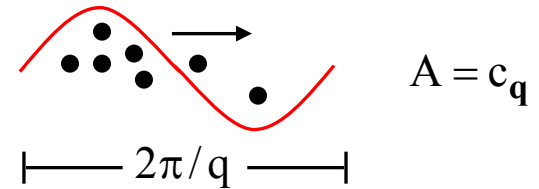
$$\tilde{M}_c(q, z) = \frac{\tilde{m}_c^{\text{irr}}(q, z)}{1 + \tilde{m}_c^{\text{irr}}(q, z)} = \tilde{M}_c^{\text{un}}(q, z) \left[1 + \frac{\tilde{M}_c^{\text{un}}(q, z)}{z S(q) + q^2 D_0 H(q)} \right]^{-1}$$

- Provided ACFs are expandable in smallness parameter ε and are of $O(\varepsilon)$:

$$M(q, t) = M_c^{\text{irr}}(q, t) = M_c^{\text{un}}(q, t) + O(\varepsilon^2) \quad \text{Example: } \varepsilon = u(r)^2, \rho$$

$$\frac{\partial}{\partial t} c_{\mathbf{q}} \equiv \hat{O}_B c_{\mathbf{q}} = i \mathbf{q} \cdot \mathbf{j}_{\mathbf{q}}^c \rightarrow 0, \quad q \rightarrow 0$$

slow, at least for q small



- What about "slowness" of density products AA , AAA , ... ?
- Basic idea : - project $f_{\mathbf{q}}$ into sub-subspace of slowest of fast variables spanned by binary products of density fluctuations
 - expected to dominate long-time decay of $M_c^{\text{irr}}(q, t)$ at least for dense systems with strong caging

- Introduce projector on bilinear density variables :

$$P_{\mathbf{q}}^{(2)} \equiv \sum_{\mathbf{k}} \frac{|c_{\mathbf{q}-\mathbf{k}} c_{\mathbf{k}} \rangle \langle c_{\mathbf{k}} c_{\mathbf{q}-\mathbf{k}}|}{2 S(\mathbf{k}) S(|\mathbf{q} - \mathbf{k}|)}$$

- 1. Approximation : $e^{\hat{\Omega}_c^{\text{irr}} t} \approx P_{\mathbf{q}}^{(2)} e^{\hat{\Omega}_c^{\text{irr}} t} P_{\mathbf{q}}^{(2)}$

$$m_c^{\text{irr}}(q, t) \propto \frac{1}{4q^2} \sum_{\mathbf{k}, \mathbf{k}'} \frac{\langle f_{\mathbf{q}}^c | c_{\mathbf{q}-\mathbf{k}} c_{\mathbf{k}} \rangle \langle c_{\mathbf{k}'} c_{\mathbf{q}-\mathbf{k}'} | f_{\mathbf{q}}^c \rangle}{S(k) S(k') S(|\mathbf{q}-\mathbf{k}|) S(|\mathbf{q}-\mathbf{k}'|)} \underbrace{\langle c_{\mathbf{k}} c_{\mathbf{q}-\mathbf{k}} | e^{\hat{\Omega}_c^{\text{irr}} t} c_{\mathbf{q}-\mathbf{k}'} c_{\mathbf{k}'} \rangle}_{\approx S(k, t) S(|\mathbf{q}-\mathbf{k}|, t) [\delta_{\mathbf{k}', \mathbf{k}} + \delta_{\mathbf{k}', \mathbf{q}-\mathbf{k}}]}$$

- 2. Approximation : $\rightarrow$ use Gaussian factorization of 4-point corr. function

$\rightarrow$ replace $\exp\{\hat{\Omega}_c^{\text{irr}} t\}$ by $\exp\{\hat{O}_B t\}$

- MCT result for $m_c^{\text{irr}}(q, t)$ with HI neglected (Götze, Fuchs et al., Szamel & Löwen) :

$$m_c^{\text{irr}}(q, t) = \frac{\rho D_0}{2(2\pi)^3} \int d\mathbf{k} [V_c(\mathbf{q}, \mathbf{k})]^2 S(k, t) S(|\mathbf{q}-\mathbf{k}|, t) \geq 0$$

$$V_c(\mathbf{q}, \mathbf{k}) = \hat{\mathbf{q}} \cdot \mathbf{k} c(k) + \hat{\mathbf{q}} \cdot (\mathbf{q} - \mathbf{k}) c(|\mathbf{q}-\mathbf{k}|) + q \rho c^{(3)}(\mathbf{k}, \mathbf{q}-\mathbf{k})$$

$\rightarrow$ usually neglected
(convolution approx.)

$\rightarrow$ self-consistent non-linear integro-differential eq. for $S(q, t)$

$\rightarrow$ single static input required is : $S(q) = 1/(1 - \rho c(q))$

$$\delta\rho_{\mathbf{q}} = \sum_{l=1}^N e^{i\mathbf{q}\cdot\mathbf{r}_l} - N\delta_{\mathbf{q},0} = \sqrt{N}c_{\mathbf{q}}$$

$$S^{(3)}(\mathbf{k}, \mathbf{k}') \equiv \frac{1}{N} \langle \delta\rho_{\mathbf{k}} \delta\rho_{\mathbf{k}'} \delta\rho_{-\mathbf{k}-\mathbf{k}'} \rangle = \sqrt{N} \langle \delta c_{\mathbf{k}} \delta c_{\mathbf{k}'} \delta c_{-\mathbf{k}-\mathbf{k}'} \rangle$$

$$S^{(3)}(\mathbf{k}, \mathbf{k}') \equiv S(\mathbf{k})S(\mathbf{k}')S(|\mathbf{k} - \mathbf{k}'|) \left[1 + \rho^2 c^{(3)}(\mathbf{k}, \mathbf{k}') \right] \approx S(\mathbf{k})S(\mathbf{k}')S(|\mathbf{k} - \mathbf{k}'|)$$

- Static convolution approximation (CA) :

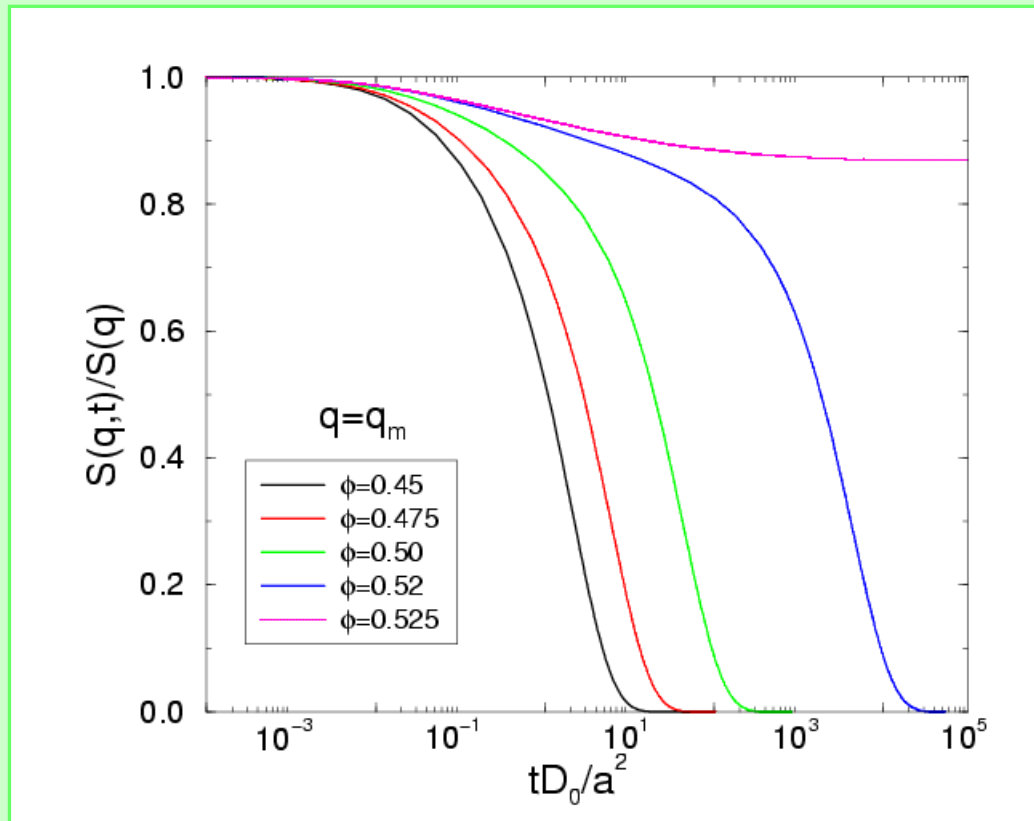
⊖ does not vanish when centers of two particles coincide

⊕ becomes exact to linear order in ρ and to linear order in $u(r)$ (WCA)

- MCT applied to irreducible memory function :
 - ⊕ gives exact limit of weakly interacting point particles
 - ⊕ preserves strict monotonicity of (irreducible) memory function
 - ⊕ becomes exact for point particles to linear order in $u(r)$ (WCA)
 - ⊕ correct functional short- and long-time asymptotics for HS w/o HI, including q -dependence
 - ⊕ consistent idealized glass transition scenario
 - ⊖ not exact at small times or densities
 - ⊖ non-systematic approximation (no smallness parameter)

⊕ consistent idealized glass transition scenario

$$\frac{S(q, t \rightarrow \infty)}{S(q)} \rightarrow f_c(q) > 0 \quad (\phi > \phi_g)$$



Hard spheres :

$$\phi_g^{\text{exp}} \approx 0.57$$

$$\phi_g^{\text{MCT}} \approx 0.525$$

$$\hat{O}_B(\mathbf{r}^N) = \underbrace{D_0 \sum_{i=1}^N [\nabla_i + \beta \mathbf{F}_i^p] \cdot \nabla_i}_{\hat{O}_B^p(\mathbf{r}^N)} + \underbrace{D_0 \sum_{i,j}^N \mathbf{T}_{ij}^{RP}(\mathbf{r}_{ij}) : [\beta \mathbf{F}_i^p \nabla_j + \nabla_i \nabla_j]}_{\hat{O}_B^{\text{hyd}}(\mathbf{r}^N)}$$

$$\mathbf{f}_{\mathbf{q}}^c = \mathbf{f}_{\mathbf{q}}^{c,p} + \mathbf{f}_{\mathbf{q}}^{c,\text{hyd}}$$

$$\hat{\Omega}_c^{\text{irr}} = \hat{Q}_c \left[\hat{O}_B + \frac{1}{q^2 D_0} \mathbf{H}(\mathbf{q}) \left| \mathbf{f}_{\mathbf{q}}^c \right\rangle \left\langle \mathbf{f}_{\mathbf{q}}^c \right| \right] \hat{Q}_c$$

- use same 4-point factorization approximation
- same static convolution approximation (needed for collective diffusion only)
- extended to mixtures and linear viscoelasticity (Nägele et al., 1997 - 2000)

- Example: MCT with far-field HI for self-dynamic scattering function $G(q,t)$:

$$\frac{\partial}{\partial t} G(q, t) = - q^2 D_s G(q, t) - \int_0^t du m_s^{\text{irr}}(q, t-u) \frac{\partial G(q, u)}{\partial u}$$

$$m_c^{\text{irr}}(q, t) = \frac{1}{q^2 D_s} \left\langle f_{\mathbf{q}}^s \left| e^{\hat{\Omega}_s^{\text{irr}} t} f_{\mathbf{q}}^s \right. \right\rangle$$

$$\hat{\Omega}_s^{\text{irr}} = \hat{Q}_s \left[\hat{O}_B + \frac{1}{q^2 D_s} |f_{\mathbf{q}}^s\rangle \langle f_{\mathbf{q}}^s| \right] \hat{Q}_s$$

irreducible Smoluchowski op.
for self-diffusion

$$\hat{Q}_s = \mathbf{1} - |a_{\mathbf{q}}\rangle \langle a_{\mathbf{q}}|$$

- Apply MCT approximation with RP-HI :

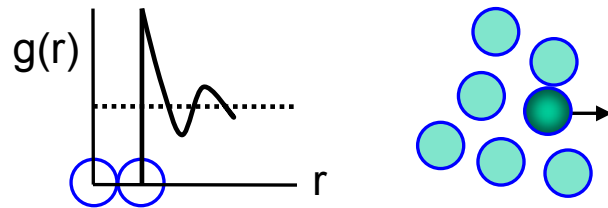
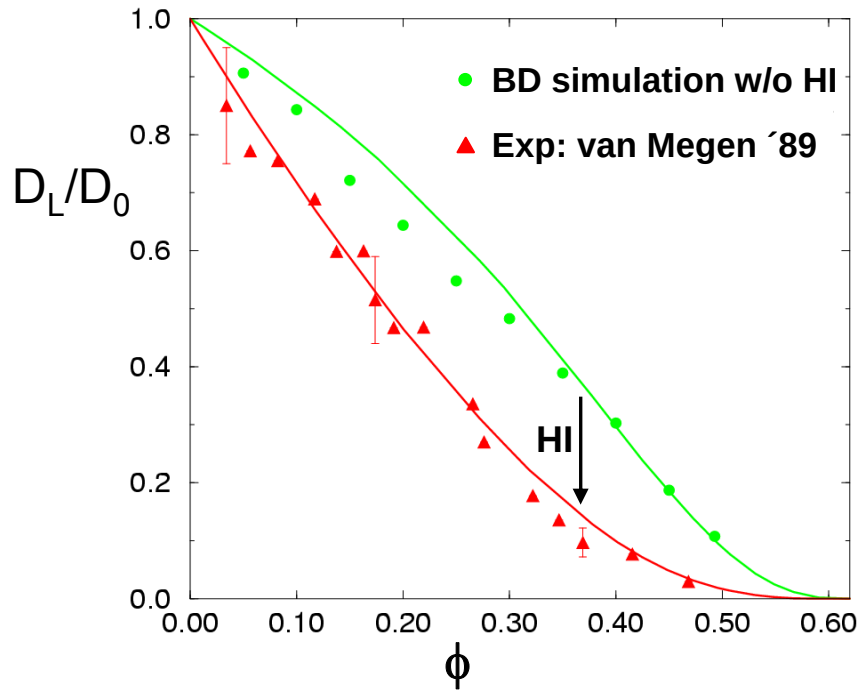
$$m_s^{\text{irr}}(q, t) = \frac{D_0}{2(2\pi)^3 \rho} \int d\mathbf{k} [V_s(\mathbf{k})]^2 S(\mathbf{k}, t) G(|\mathbf{q} - \mathbf{k}|, t) \geq 0$$

$$V_s(\mathbf{k}) = \left[1 - \frac{H(\mathbf{k})}{S(\mathbf{k})} \right]$$

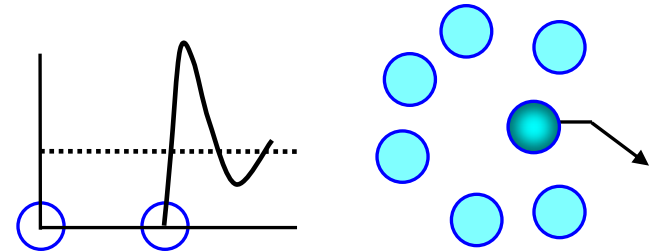
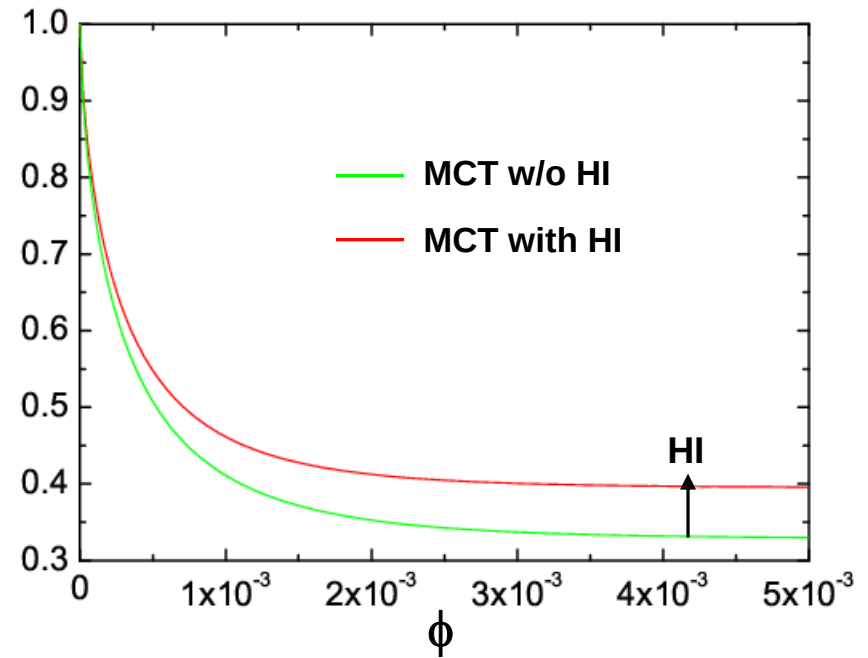
Input is now $S(q)$ and $H(q)$

MCT results for long-time self-diffusion

- hard spheres



- charged spheres



(G.N. & Banchio et al., Europhys. Lett. '97 & JCP '00)

VAF: general behavior

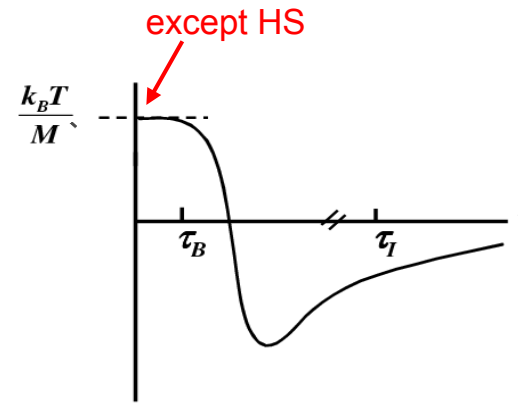
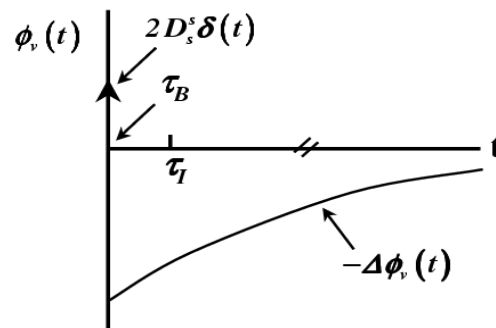
- From memory eq. for $G(q, t) = \exp[-q^2 W(t)] + O(q^4)$ follows :

$$W(t) = D_S t - \int_0^t du (t-u) \left\langle \hat{\mathbf{q}} \cdot \mathbf{v}_1^I \mid e^{\hat{\mathbf{O}}_B u} \hat{\mathbf{q}} \cdot \mathbf{v}_1^I \right\rangle \rightarrow D_L t \quad (t \gg \tau_I)$$

- Comparison with generally valid Ornstein-Fürth formula (requires only stationarity) :

$$W(t) = \int_0^t du (t-u) \phi_v(u) \longrightarrow$$

$$\begin{aligned} \phi_v(t) &= 2D_S \delta(t) - \Delta\phi_v(t) \\ D_L &= D_S - \int_0^\infty dt \Delta\phi_v(t) < D_S \end{aligned}$$



$$\phi_v(t \gg \tau_m) \approx -A \left(\frac{t}{\tau_m} \right)^{-(d+2)/2}$$

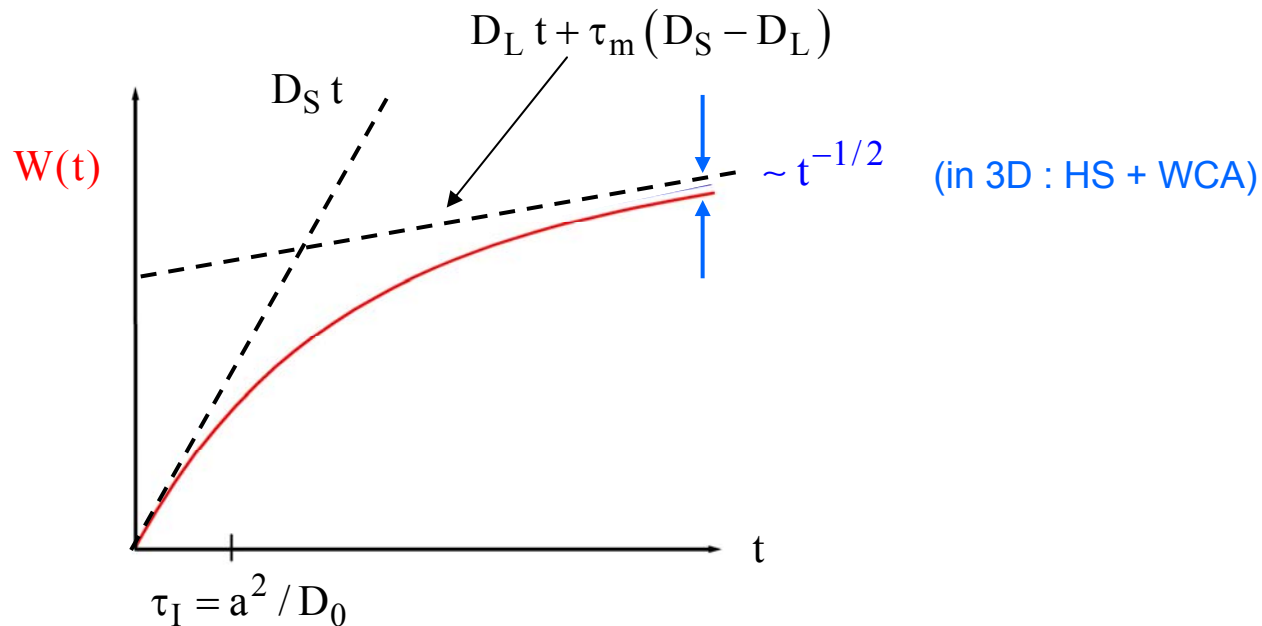
negative configurational
long-time tail

MSD: general behavior

$$W(t) = D_L t + \tau_m (D_S - D_L) - \int_t^\infty du (u - t) \Delta\phi_V(u)$$

τ_m : mean relaxation time of corresponding VAF (regular part)

$$\tau_m = \int_0^\infty dt t \Delta\phi_V(t) \bigg/ \int_0^\infty dt \Delta\phi_V(t)$$



Application: non-exponential decay of dynamic structure factor

- Global measure : non-exponentiality factor

$$\Delta(q) \equiv 1 - \frac{\tau_s(q)}{\bar{\tau}(q)}$$

$$\bar{\tau}(q) = \int_0^{\infty} dt \frac{S(q,t)}{S(q)}$$

$$\tau_s(q) = \left(q^2 D_0 \frac{H(q)}{S(q)} \right)^{-1}$$

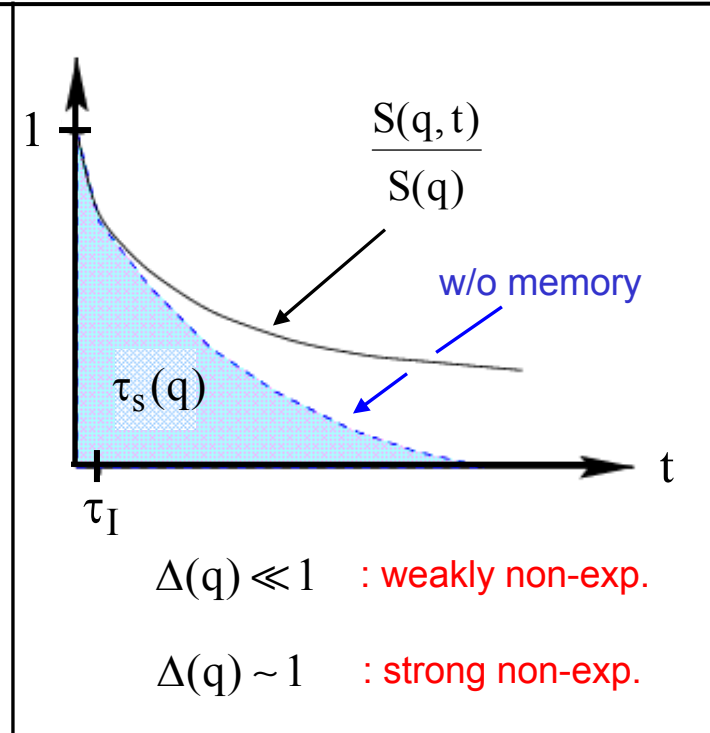
- from memory eqs. for $S(q,t)$ follow :

$$\Delta(q) = \frac{\tilde{m}_c^{\text{irr}}(q, z=0)}{1 + \tilde{m}_c^{\text{irr}}(q, z=0)} = \frac{\tilde{M}_c(q, z)}{q^2 D_0 H(q)} \longrightarrow 0 \leq \Delta(q) \leq 1$$

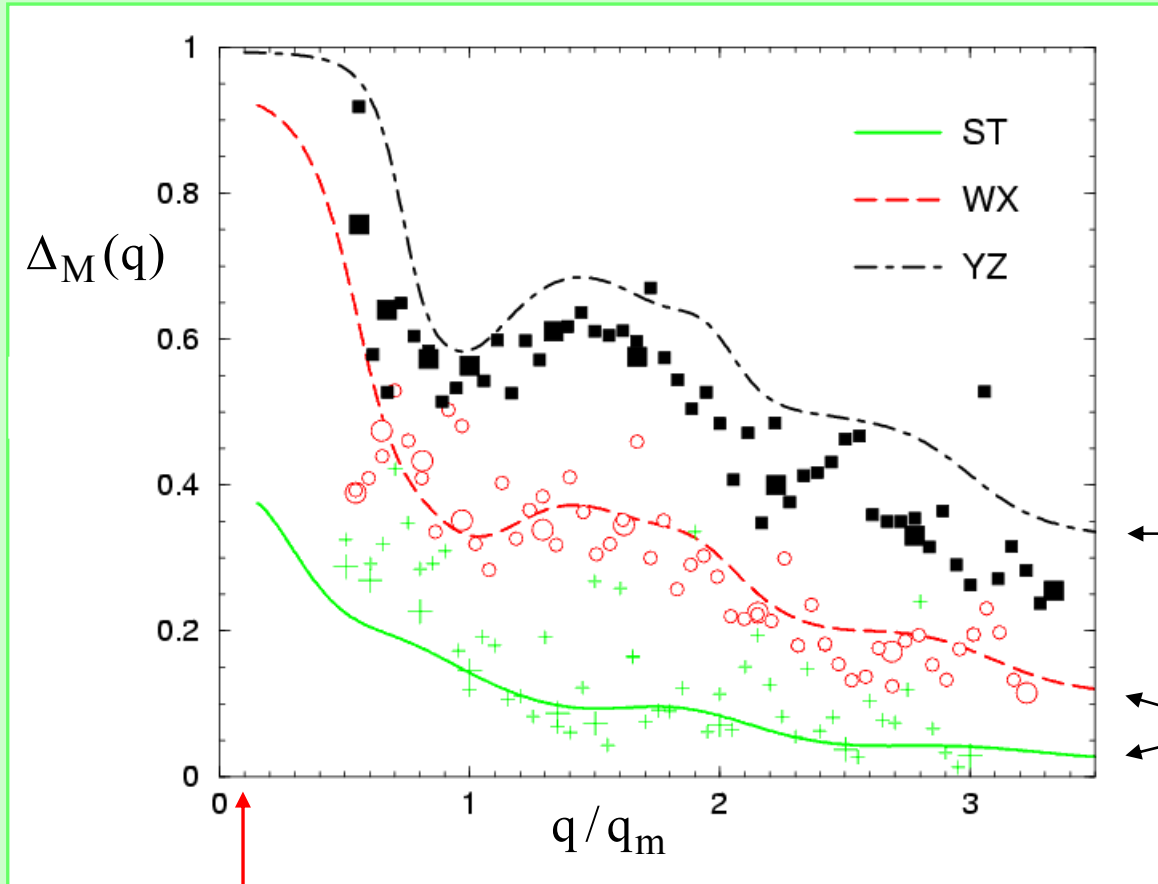
$$\lim_{q \rightarrow 0} \Delta(q) = \frac{D_c^S - D_c^L}{D_c^S}$$

- zero for no or PA-HI

- smaller than 0.06 for dense hard-sphere systems



- Measured non-exponentiality factor for charge-stabilized dispersions



$$\phi \sim 10^{-4} - 10^{-3}$$

$$s = \sqrt{\langle \sigma^2 \rangle - \bar{\sigma}^2} / \bar{\sigma} = 0.05$$

← zero added salt

← little added salt

$$\Delta(q \gg q_m) > 1 - D_L/D_S$$

Puzzle : - reason for strong „non-exponentiality“ near $q = 0$?
 - can't be due to many-body HI !

Exp.: Müller & Schätzel, Kiel (1993)

Theory: Banchio, Nägele & Bergenholtz, J. Chem. Phys. (2000)

- Resolution : tiny amount of size-polydispersity is sufficient

DLS-measurable dynamic structure factor for polydisperse system :

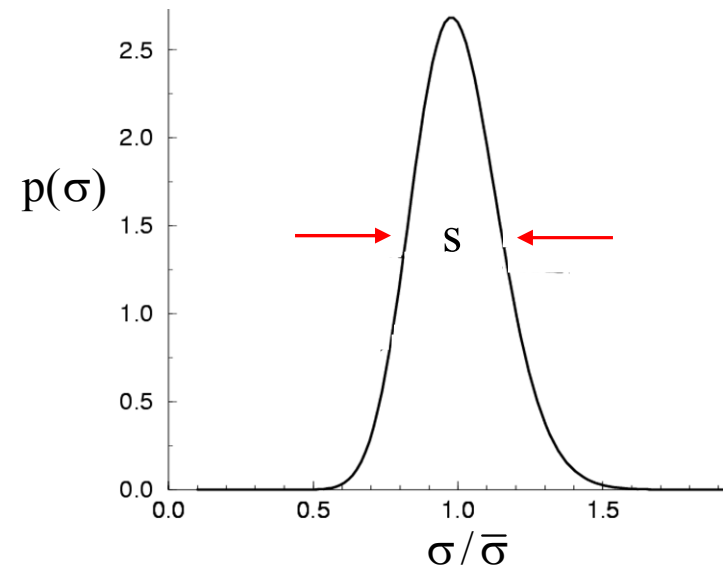
$$S_M(q, t) \propto \sum_{\alpha, \beta=1}^m (x_\alpha x_\beta)^{1/2} b_\alpha(q) b_\beta(q) S_{\alpha\beta}(q, t)$$

Small polydispersity $s \ll 1 \Rightarrow$ decoupling approx.

$$S_M(q, t) \propto X(q) \mathbf{G}_{id}(q, t) + [1 - X(q)] \mathbf{S}_{id}(q, t)$$

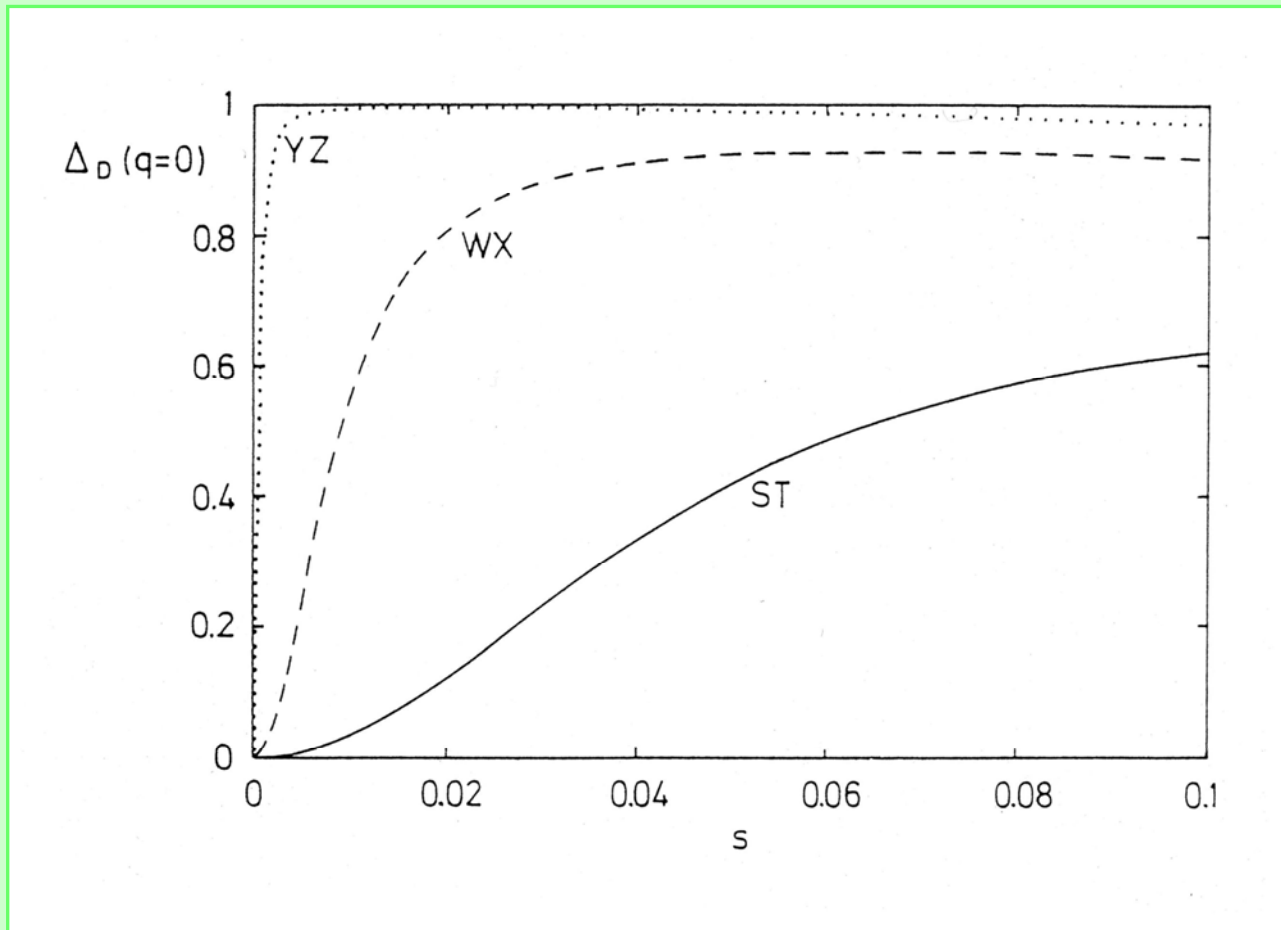
$$X(q) = 1 - \frac{\langle b(q) \rangle_p^2}{\langle b(q)^2 \rangle_p} \approx 9s^2 \quad (q\sigma < 1.5)$$

$$\Delta_M(q \rightarrow 0) = 1 - \frac{\tau_s^M(q)}{\bar{\tau}^M(q)} > 0 \quad \text{since :}$$



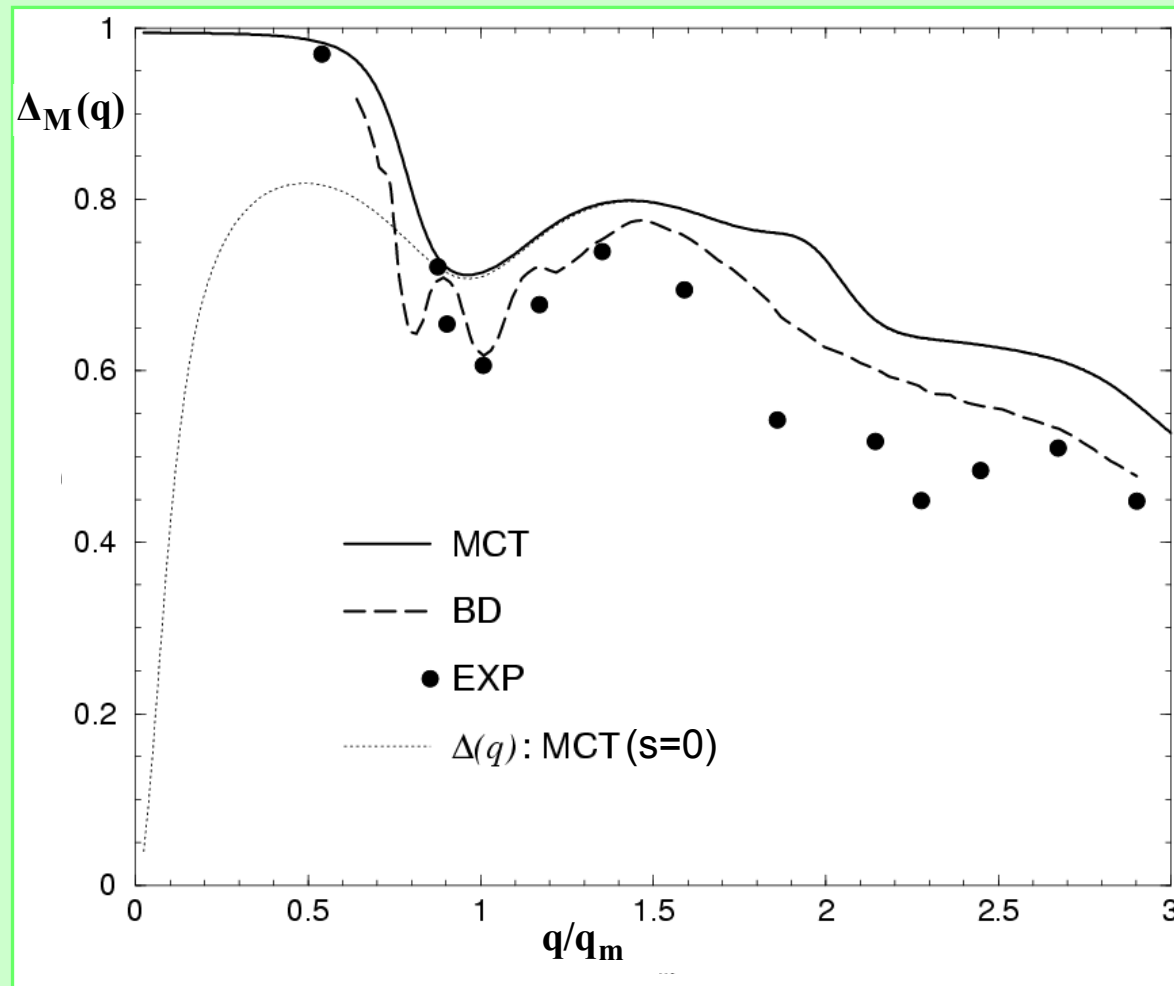
$$S_M(q \ll q_m, t) \propto (1 - 9s^2) \underbrace{S(0)}_{\ll 1} \underbrace{\exp\left\{-q^2 D_0 \frac{H(0)}{S(0)} t\right\}}_{\text{decays fast}} + 9s^2 \underbrace{\exp\left\{-q^2 W(t)\right\}}_{\text{decays slowly}}$$

- Influence of polydispersity s on $\Delta_M(q=0)$



(Baur & Nägele, Physica A (1997))

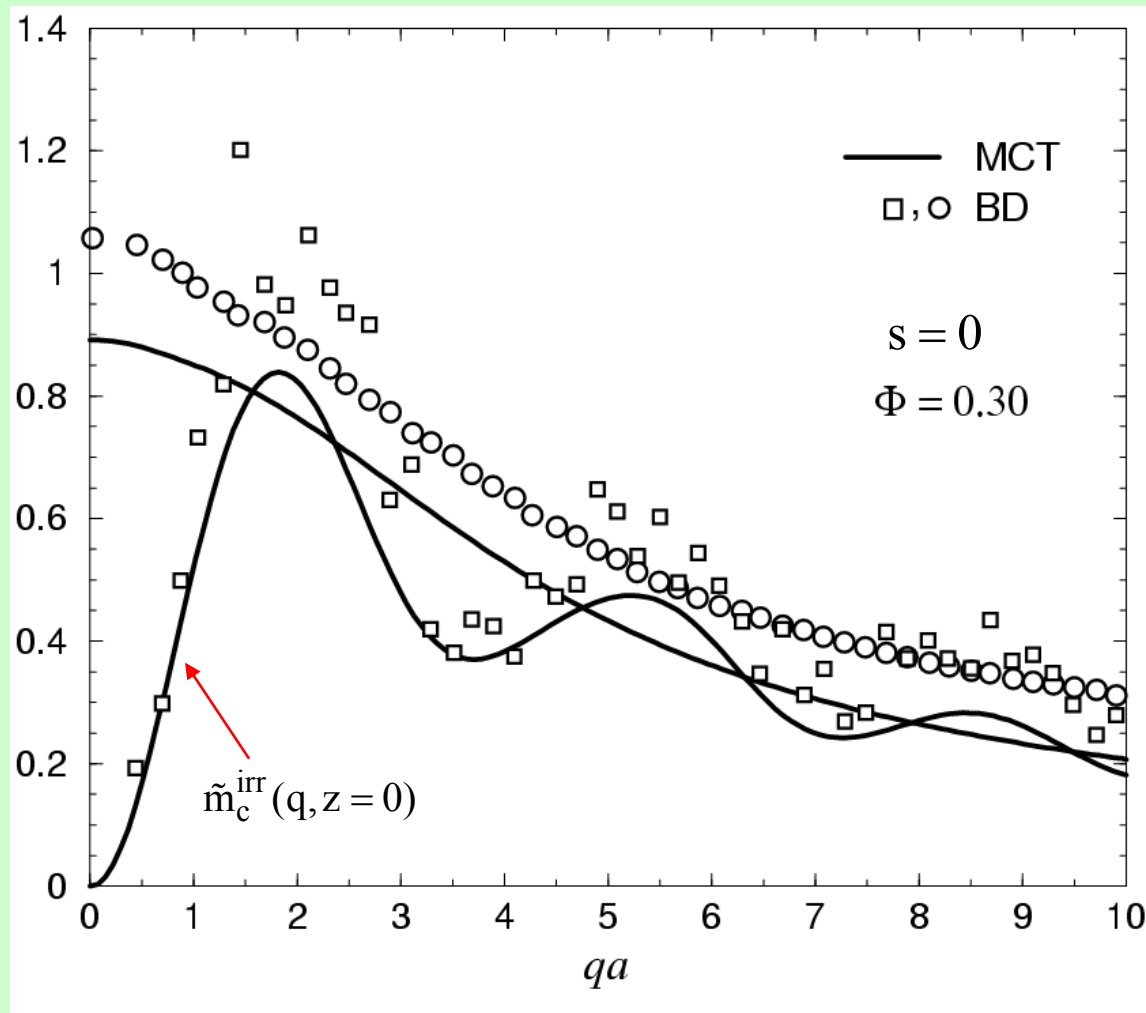
- Measurable non-exponentiality factor for charge-stabilized dispersion with $\sigma = 0.06$



Theory: Banchio, Nägele & Bergenholtz, J. Chem. Phys. (2000)

Exp. + BD: Härtl et al., J. Chem. Phys. (1992)

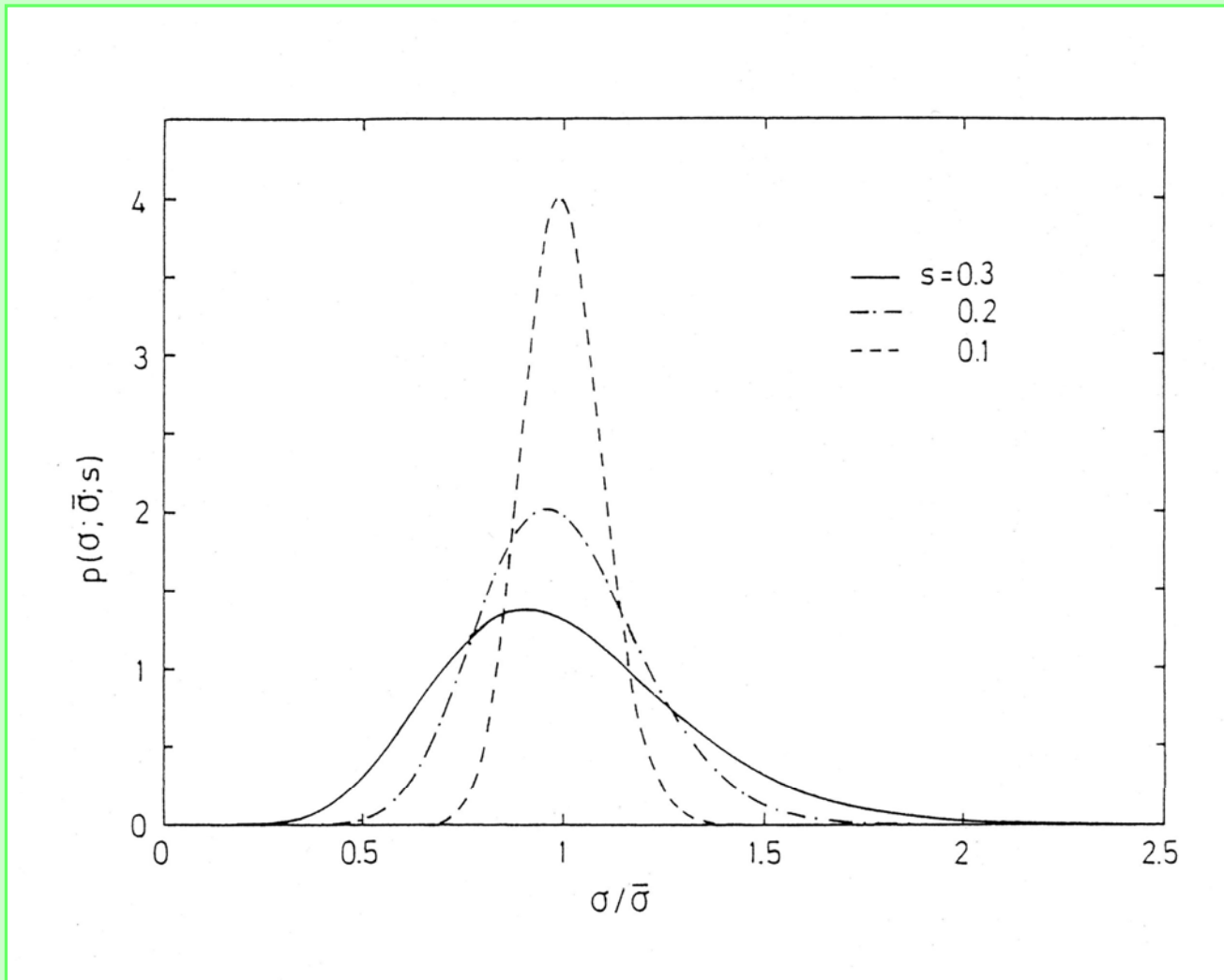
- Time-integrated collective and self-dynamic irreducible memory functions



Theory: Banchio, Nägele & Bergenholtz, J. Chem. Phys. (2000)

Simulation: Cichocki & Hinsen, Ber. Bunsenges. Phys. Chem. (1990)

- Schultz distribution of particle sizes



9. Concluding remarks

- Colloidal dispersions: grand variety of dynamic properties
- Transport properties are determined by a delicate interplay of hydrodynamic and direct particle interactions
- Theoretical methods extendable to colloidal composites and polymer solutions
- There is an intensive & fruitful exchange between theory + experiment :
quantitative theoretical predictions for colloidal model dispersions