

Vectorization

Why you shouldn't care.

June 7th, 2016 | Ivo Kabadshow, Andreas Beckmann | Jureca Workshop 2016, JSC

Welcome To The Lectures On Hardware Design

- Processor microarchitecture
- Micro-Ops bandwidth/latency
- Memory hierarchy
- Memory bandwidth/latency
- Critical path analysis
- Intrinsic/Assembly

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Instead we only look at this more conceptually.

Why You Should Not Care A Lot

You have to know a lot about your code

- data layout, algorithmic complexity, critical path, performance bottlenecks

You need to change a lot

- algorithm, data layout, loop structure, access pattern

You probably make it worse

- non-portable binary, confused compiler, unreadable and bloated source code

What is your ...

Or: Is vectorization the right tool for me?

... performance bottleneck?

- FLOPS, memory (bandwidth/latency)
- Data dependencies
- Communication (MPI), I/O (Disk)

... programming language?

- Fortran – Are you allowed/capable to write ASM,C/C++ code?
- Python – Are you allowed/capable to write ASM,C/C++ code?
- C/C++ – Already close to the metal, go ahead ...

Level of Parallelism

Parallelization Stack

MPI
Threading
Cache Tiling
Unrolling
Vectorization

User

User, Compiler extensions (OMP)

Compiler, User

Compiler, Hardware

Compiler

Vectorization

- Fine-grained parallelism needs regular algorithmic structure

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Vectorization

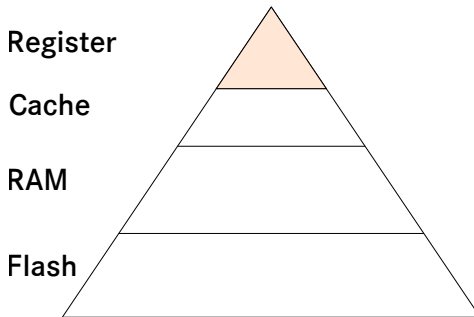
- Fine-grained parallelism needs regular algorithmic structure

Best practices: Find Critical Kernel Algorithm

- Use highly tuned existing libraries, like: Intel MKL, Atlas, BLAS, Eigen, FFTW, Spiral, ...

Memory Hierarchy

Data Movement Is Very Expensive

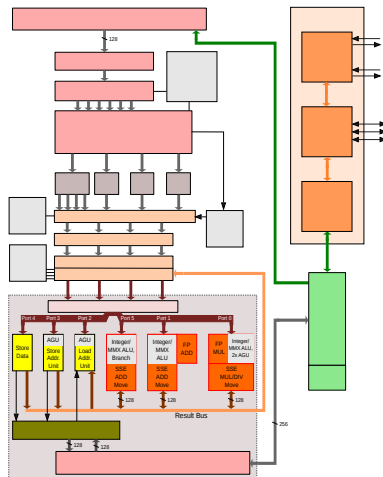


Memory Hierarchy

- Towards top: more expensive (\$), smaller, faster
- Reuse data in registers, cache as much as possible

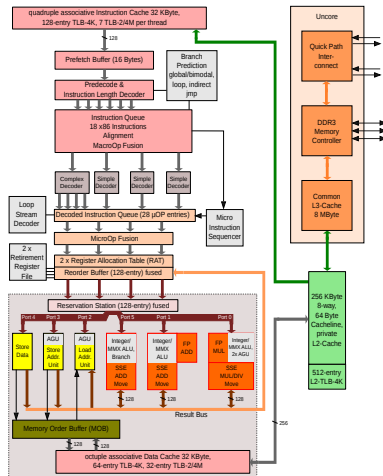
Microarchitecture

Memory, Caches, Register, Ports



Microarchitecture

Memory, Caches, Register, Ports



Single Instruction - Multiple Data (SIMD)

SIMD Operations in AVX

Float/Int:  =  $\odot$ 

Double/Long:  =  $\odot$ 

Some Available Operations $\odot$

$+$ $-$ $\times$ $\div$ $\sqrt{\cdot}$ $|\cdot|$ $\min(\cdot)$ $\max(\cdot)$ $\text{sgn}(\cdot)$

Careful!

- Consecutive (and aligned) memory for SIMD load/store needed
- Not all operations are available in SIMD (trigonometric, exp, log)
- Some operations may be available as estimates ($1/\cdot$, $\sqrt{\cdot}$)
- Not all operations have the same ALU bandwidth or latency

Using Intrinsics to Utilize SIMD

C/C++ Intrinsics, Use up to 16 registers

$1/\sqrt{a}$ estimate with 22 bits for 8 floats

```
inline __m256 rsqrt_estimate_22bits(__m256 a)
{
    __m256 ymm0;
    __m256 ymm2;
    __m256 ymm3 = {3.f, 3.f, 3.f, 3.f, 3.f, 3.f, 3.f, 3.f};
    __m256 ymm4 = {0.5f, 0.5f, 0.5f, 0.5f, 0.5f, 0.5f, 0.5f, 0.5f};
    __m256 ymm5;
    ymm5 = a;
    ymm0 = _mm256_rsqrt_ps(ymm5);
    ymm2 = ymm0 * ymm0;
    ymm2 = ymm2 * ymm5;
    ymm2 = ymm3 - ymm2;
    ymm0 = ymm0 * ymm2;
    ymm0 = ymm0 * ymm4;
    return ymm0;
}
```

Single Instruction - Multiple Data (SIMD)

Fused Multiply-Add (FMA) – Three Operands (FMA3)

- No SIMD (float or double)

$$\blacksquare = \blacksquare \times \blacksquare + \blacksquare$$

- SIMD (Double)

$$\blacksquare \blacksquare \blacksquare \blacksquare = \blacksquare \blacksquare \blacksquare \blacksquare \times \blacksquare \blacksquare \blacksquare \blacksquare + \blacksquare \blacksquare \blacksquare \blacksquare$$

- SIMD (Float)

$$\blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare = \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \times \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare + \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare \blacksquare$$

Details

- One operand may come from memory
- One operand needs to be reused for output ($\blacksquare =$)

Perfect ASM for OoOE on Intel CPUs

Compiler-generated from SIMD-aware code

AVX without FMA

```
loop:
vsubps 0x0(%r13,%rax,4),%ymm12,%ymm7
vsubps (%r14,%rax,4),%ymm13,%ymm6
vsubps (%r15,%rax,4),%ymm14,%ymm5
vmulps %ymm7,%ymm7,%ymm8
vmulps %ymm6,%ymm6,%ymm0
vaddps %ymm0,%ymm8,%ymm0
vmulps %ymm5,%ymm5,%ymm8
vaddps %ymm8,%ymm0,%ymm0
vsqrtps %ymm0,%ymm0
vdivps %ymm0,%ymm9,%ymm0
vmulps (%rdx,%rax,4),%ymm0,%ymm8
add $0x8,%rax
cmp %rax,%rbx
vmulps %ymm0,%ymm0,%ymm0
vmulps %ymm0,%ymm8,%ymm0
vaddps %ymm8,%ymm1,%ymm1
vmulps %ymm0,%ymm7,%ymm7
vmulps %ymm0,%ymm6,%ymm6
vmulps %ymm0,%ymm5,%ymm0
vaddps %ymm7,%ymm3,%ymm3
vaddps %ymm6,%ymm2,%ymm2
vaddps %ymm0,%ymm4,%ymm4
ja loop
```

AVX2 with FMA

```
loop:
vsubpd (%rcx,%rdx,8),%ymm13,%ymm7
vsubpd (%rdi,%rdx,8),%ymm14,%ymm6
vsubpd (%r8,%rdx,8),%ymm15,%ymm5
vmulpd %ymm6,%ymm6,%ymm4
vfmadd231pd %ymm7,%ymm7,%ymm4
vfmadd231pd %ymm5,%ymm5,%ymm4
vsqrtpd %ymm4,%ymm4
vdivpd %ymm4,%ymm12,%ymm4
vmulpd (%r9,%rdx,8),%ymm4,%ymm8
add $0x4,%rdx
vmulpd %ymm4,%ymm4,%ymm4
cmp %rax,%rdx
vmulpd %ymm4,%ymm8,%ymm4
vaddpd %ymm8,%ymm3,%ymm3
vfmadd231pd %ymm4,%ymm7,%ymm0
vfmadd231pd %ymm4,%ymm6,%ymm1
vfmadd231pd %ymm4,%ymm5,%ymm2
jb loop
```

Demystifying Peak-Performance

Jureca Specifications

- 1872 compute nodes
- Two Intel Xeon E5-2680 v3 Haswell CPUs per node
- 2 x 12 cores, 2.5 GHz, SMT
- AVX 2.0 ISA extension
- 1.8 PFLOPs for all the CPUs combined

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- What is the performance of your code on Jureca?

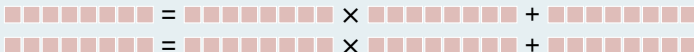
Dissecting Peak-Performance

Processor Architecture: Intel Haswell, Broadwell & Skylake

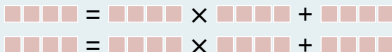
FLOP/Cycle

Single Element (4/8 Bytes) 

- Float: 32 (256 bit SIMD size: 8 elements $\times$ 4 Bytes)



- Double: 16 (256 bit SIMD size: 4 elements $\times$ 8 Bytes)



- Throughput: 2 per cycle (super-scalar), 2 FMA ports available
- Latency: 5 cycles, pipelining needed for peak performance

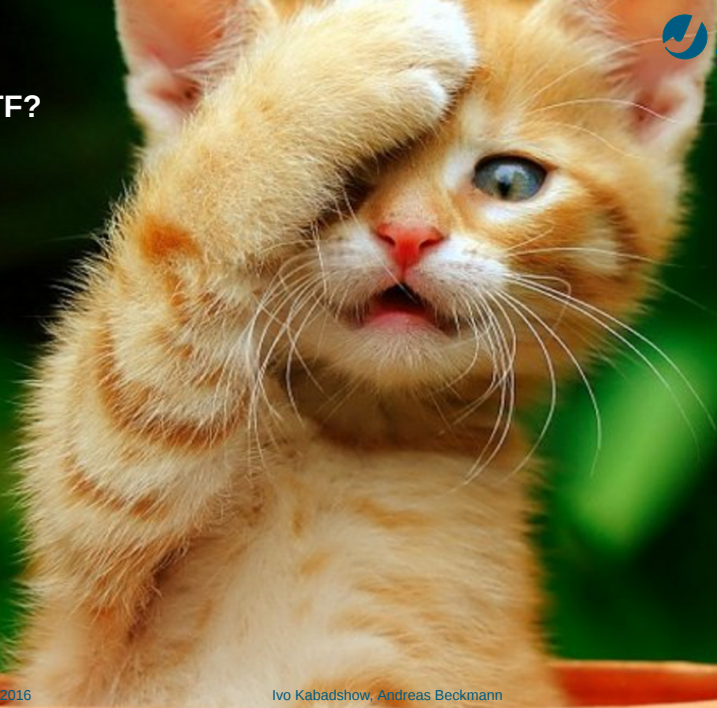
Dissecting Peak-Performance

Peak Performance

- $32 \text{ FLOP/cycle} \times 2.5\text{GHz} \times 12 \text{ cores} \times 2 \text{ sockets} \times 1872 \text{ nodes}$
- = 3.5942×10^{15} (float)
- = 1.7971×10^{15} (double) with 16 FLOP/cycle

- Pipelined instructions
- Only 1 store and 2 loads per cycle possible
- Data resides in L1 cache, no cache misses
- No data dependencies
- No I/O, no MPI bottleneck

WTF?



WTF?

Realistic FLOPs	Divider
-----------------	---------

- | | |
|-------------------------|-----|
| ■ Double Precision | : 2 |
| ■ No FMA used | : 2 |
| ■ One FP port per cycle | : 2 |
| ■ No SIMD | : 4 |

- | | |
|---|--|
| ■ $1/32 \approx 3\%$ peak is very good! | |
|---|--|

Data Layout vs. SIMDization

Your data structures need to adapt

- Array of Structs (AoS)
 - xyzxyzxyzxyz, ...
- Struct of Arrays (SoA)
 - xxxx ...
 - yyyy ...
 - zzzz ...
- Array of Struct of Arrays (AoSoA)
 - xxyyzzxxyyzz ...

SIMDization

- In which direction does the operation go?
- Do you access your data aligned (32 Byte)?

Pitfalls I

If you still decide to do it yourself

- Data alignment is paramount
- Reordering/shuffling of data might increase runtime
- Algorithm needs to be adapted to hardware architecture
- Algorithm will be most likely not portable
- Expert knowledge of microarchitecture required
- Expert knowledge of instruction set architecture (ISA) required

Pitfalls II

- Use of SIMD may reduce clockspeed
- Some SIMD instructions are not fully vectorized ($\sqrt{\cdot}$)
- Increased register usage may be a bottleneck
- Increased performance after redesign may come from CPU out-of-order unit
- Data dependencies on critical path may stall computation
- Don't optimize for a specific SIMD size
- SIMD size will increase in future (e.g. Xeon Phi)

Going to utilize a GPU soon?

- Listen carefully to the GPU talk
- Start porting to the GPU first
- Algorithm has to change anyway
- Prepare loop unrolling, find common/independent sub-expressions
- Optimized GPU code (SIMT) can be ported back to CPU (SIMD)

Lessons learned

- Solution depends on your problem/bottleneck
- If you are paid for science, don't go off-course too much
- Change data layout to allow the use of libraries
- Ask you boss to employ a computer scientist



I am using SIMDized libraries
and do not care anymore!

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