

From biology to your coffee machine ? How neuromorphic computing may affect our future life

*HBP Colloquium
FZ Jülich, October 2018*

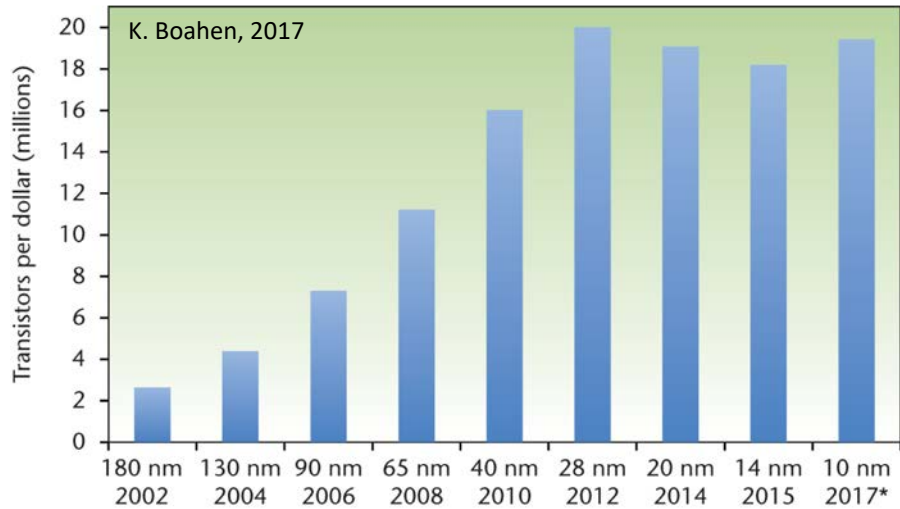
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No more progress from smaller transistors

New **ARCHITECTURES** suddenly interesting !

First : Make use of CMOS devices

Then : Pave the way for non-CMOS

Brain-inspired, brain-derived or neuromorphic computing

Definition Transferring aspects of **structure** and **function** from biological substrates to electronic circuits

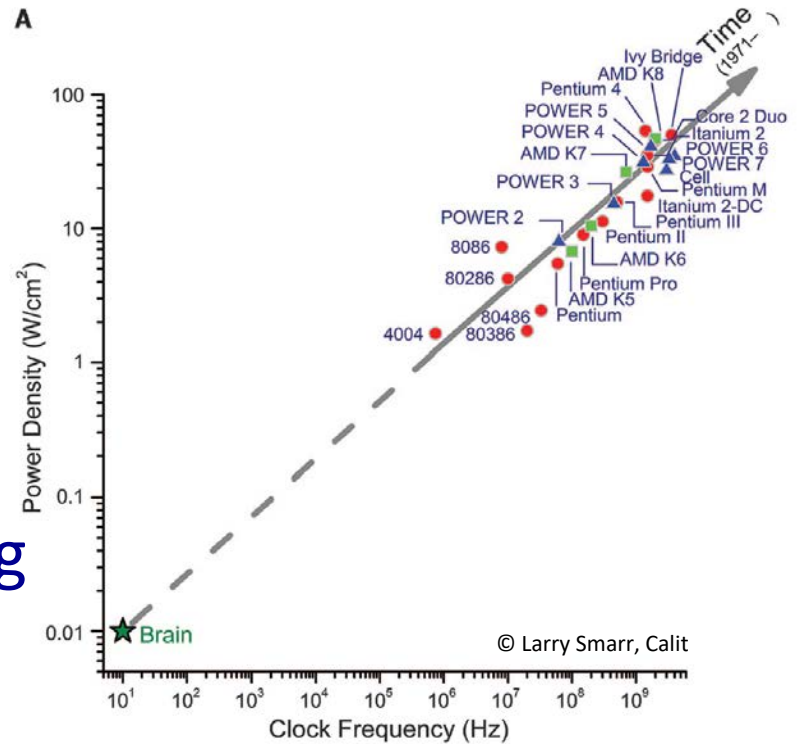
Structure : Cells – Networks – Connections

Function : Local Processing – Communication – Learning



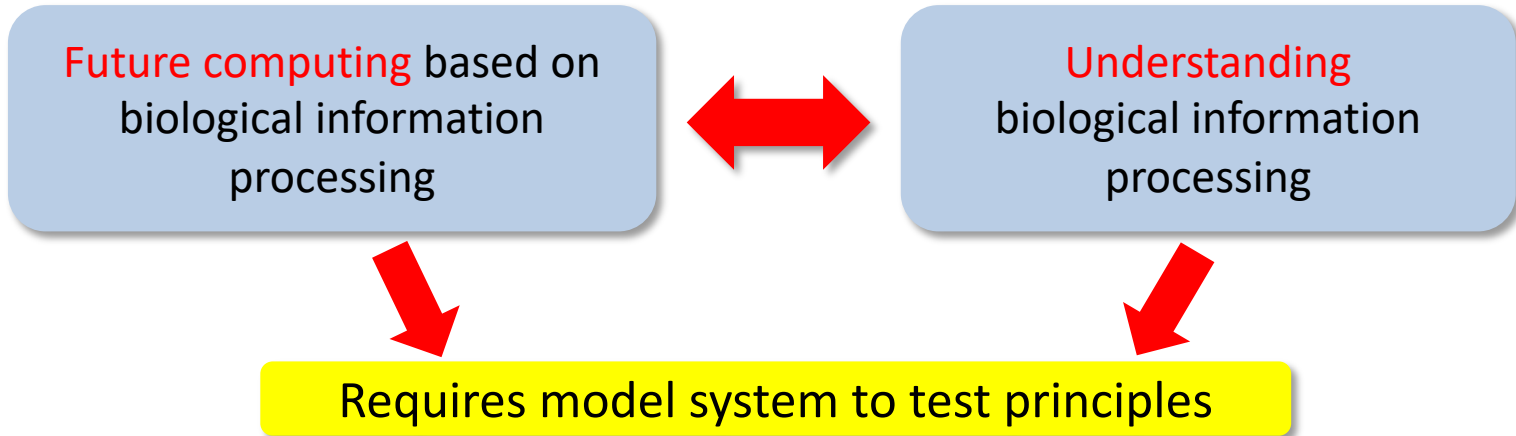
Assets of brain inspired computing

- Energy efficiency
- Compactness
- Fault tolerance
- Speed
- Configuration and learning replace programming
- Scalability



Conventional
computing is moving
away from the brain

Neuromorphic : why and how ?

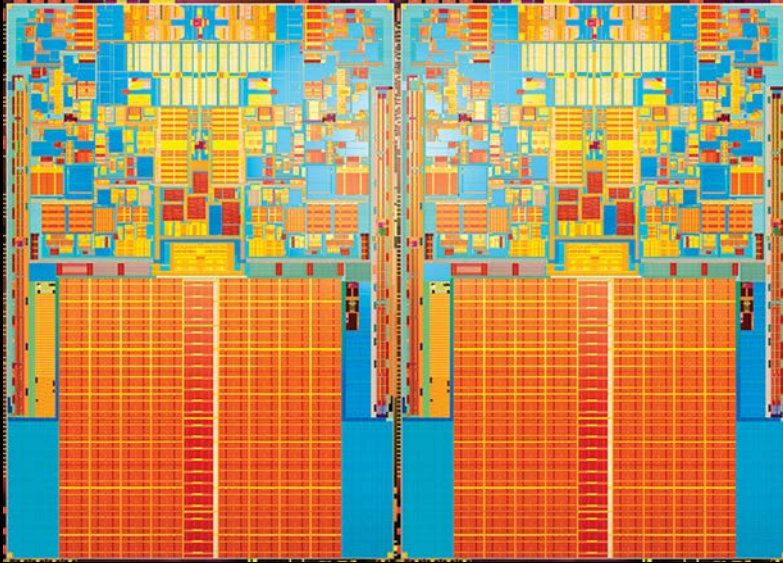


Two **fundamentally different** modeling approaches

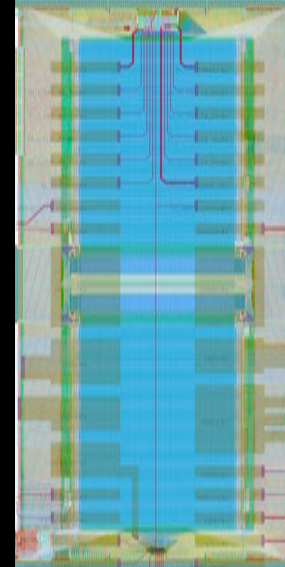
- **SYMBOLIC MODEL (Turing)**
represents model parameters as **symbols (binary numbers)**
represents function as **instructions (algorithms)**
- **PHYSICAL MODEL (non Turing)**
represents model parameters as **physical quantities (like the brain)**
represents function as **circuit dynamics (physical laws)**

Combined into
hybrid system

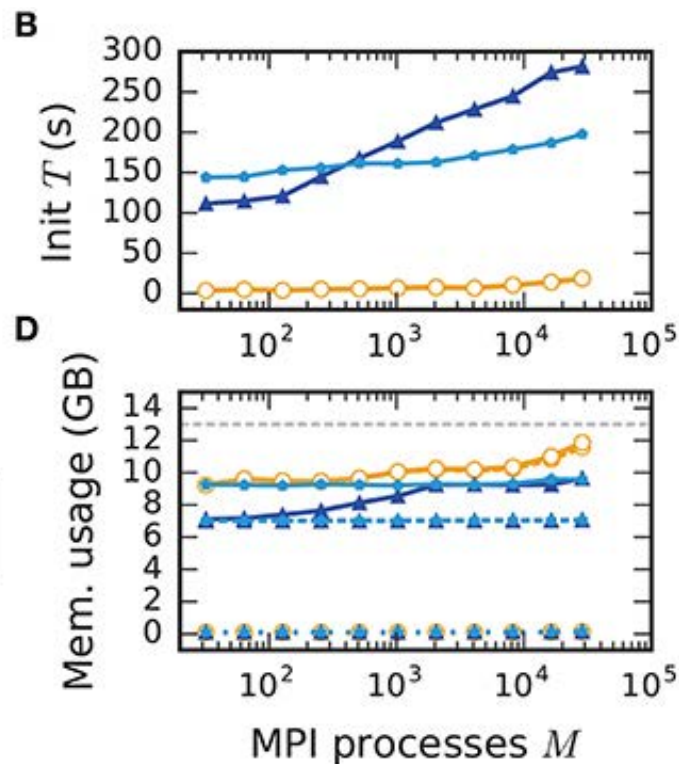
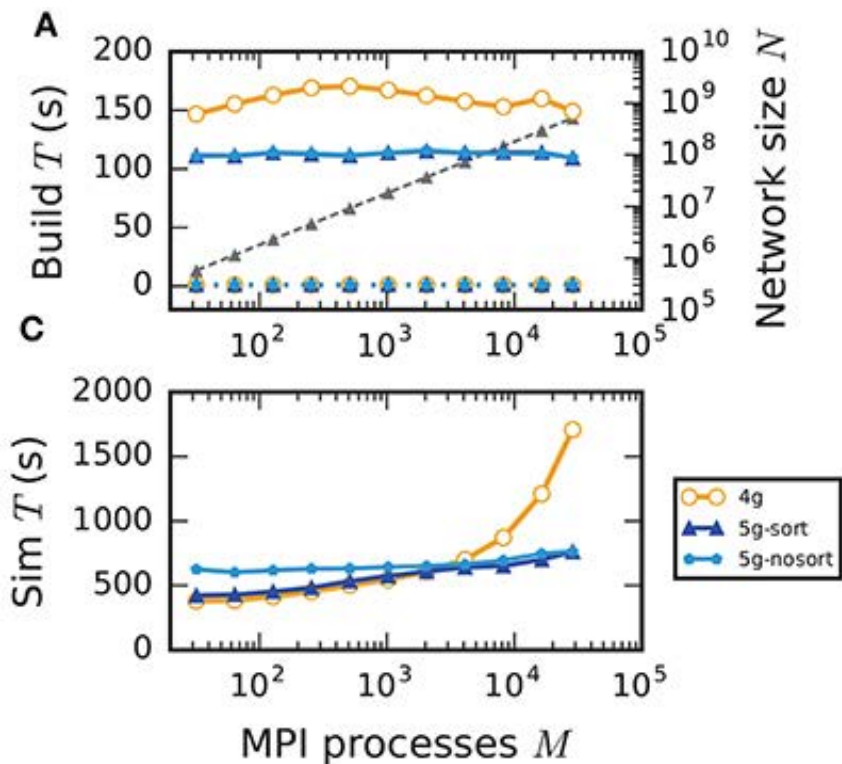
Same transistors - where's the neuron ?



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The BrainScaleS Project

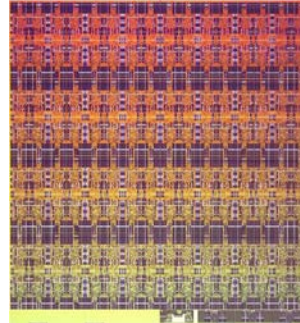


The simulation approach

Weak scaling (*sizeup*) on modern petascale many-processor machines



Neuromorphic implementations : Towards biological realism



Biological realism

Ease of use by traditional programming tools

Many-core (ARM) architecture
Optimized spike
communication network
Programmable local learning
x0.01 real-time to real-time

Full-custom-digital neural circuits
No local learning (TrueNorth)
Programmable local learning (Loihi)
Exploit economy of scale
x0.01 real-time to x100 real-time

Analog neural cores
Digital spike communication
Biological local learning
Programmable local learning
x10.000 real-time

The HBP Neuromorphic Computing Strategy

2nd generation emerged from co-design process in HBP

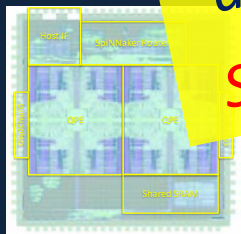
1st generation SpiNNaker-1 Machine



Many-core system
1 Million ARM cores
Real-time simulator

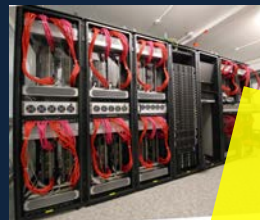
Many-core
architecture
SIMULATION

Towards the 2nd generation SpiNNaker-2



144 Cortex M4F per chip
36 GIPS/Watt per chip
x10 performance with constant power

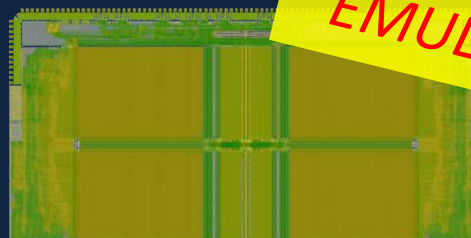
1st generation BrainScaleS-1 Machine



Physical model system
4M neurons, 1B plastic synapses
Accelerated emulator

Physical
model
EMULATION

Towards the 2nd generation BrainScaleS-2



On-chip plasticity processors
Flexible hybrid plasticity
Active dendrites

These are neuromorphic processors
Common software ecosystem, remote access, open user facility
designed and built from the transistor up!
Close cooperation with (theoretical) neuroscience, application domain

Assets of brain inspired computing ?

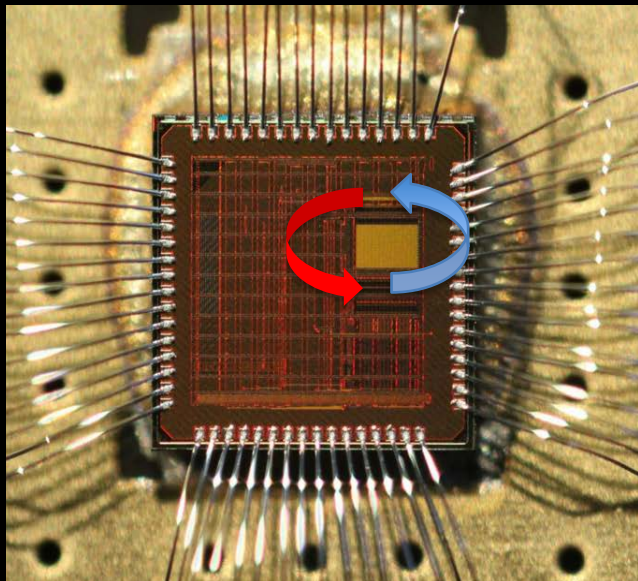
- Energy efficiency
- Compactness
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2nd generation – HBP made

- Hybrid plasticity with on-chip processor (PPU): on-chip loops, time-scales from ms to years
 - Input : timing correlations, rates, membrane potentials, external signals
 - Change : synaptic weights, neuromodulation, network structure
- Structured neurons
 - Multicompartment neurons
 - Active, non-linear dendrites, backpropagating APs
 - NMDA, Ca plateau potentials

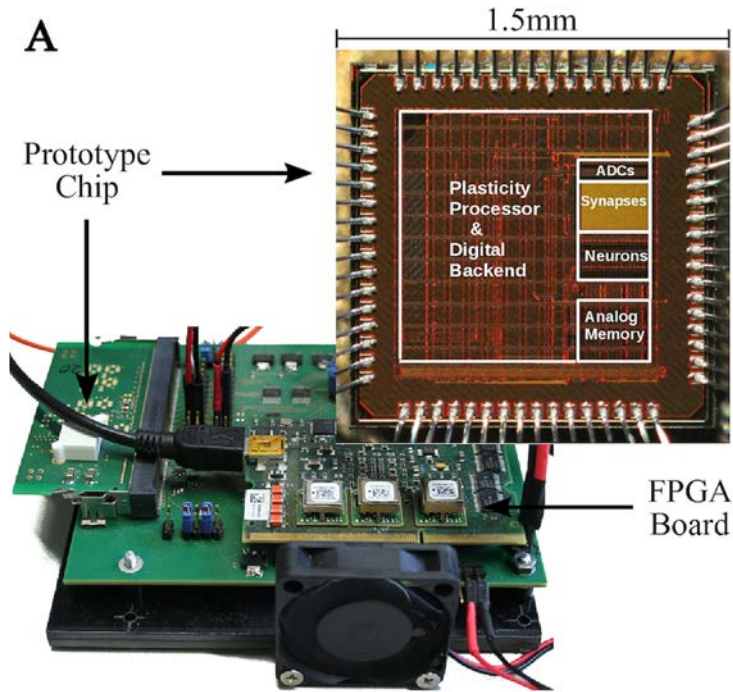
BrainScaleS-2

65 nm prototype chip in the lab

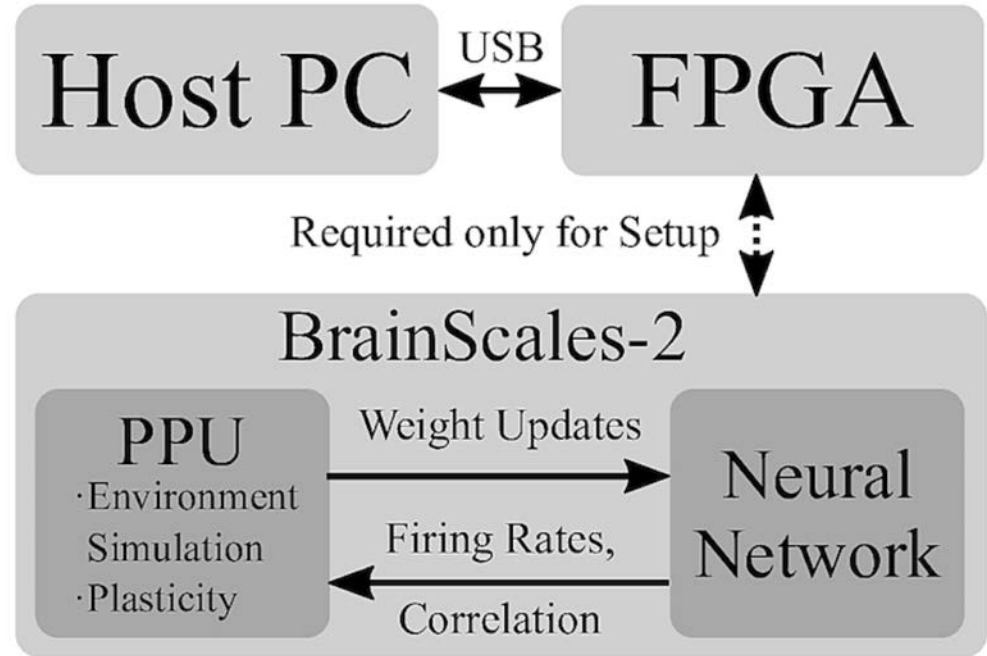


- Public evaluation system by end-2018
- Full-size prototypes by mid-2020
- Full size system by 2023
- Funding pending

In-the-the-loop experiments on silicon – External computers only for set-up

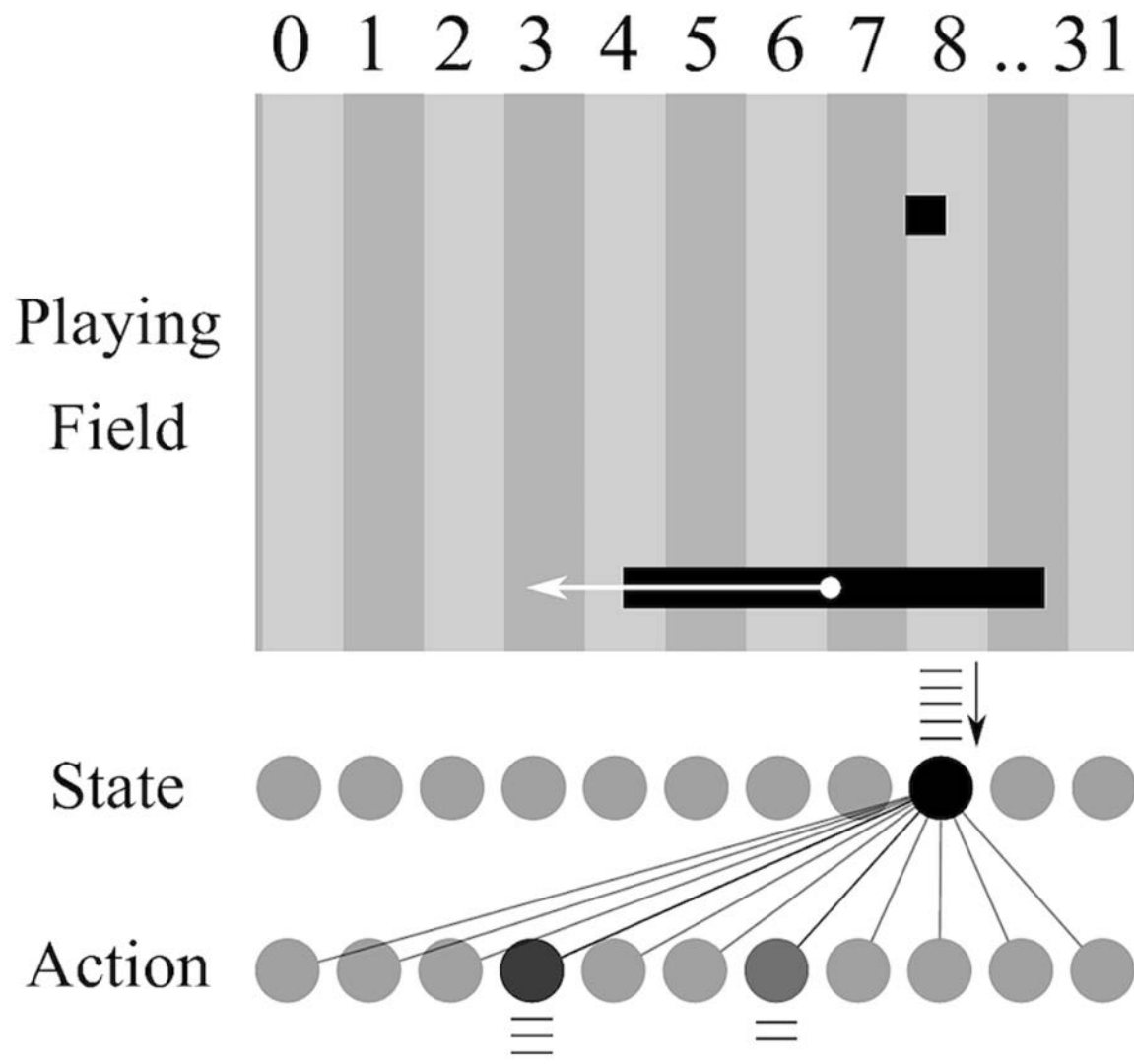


Compactness



Aamir, S. A. et al. (2018). An Accelerated LIF Neuronal Network Array for a Large Scale Mixed-Signal Neuromorphic Architecture. IEEE Transactions on Circuits and Systems I: Regular Papers , 1 14

Wunderlich et al., 2018, to be submitted to Frontiers of Neuromorphic Engineering



PONG : Closed action-perception loop

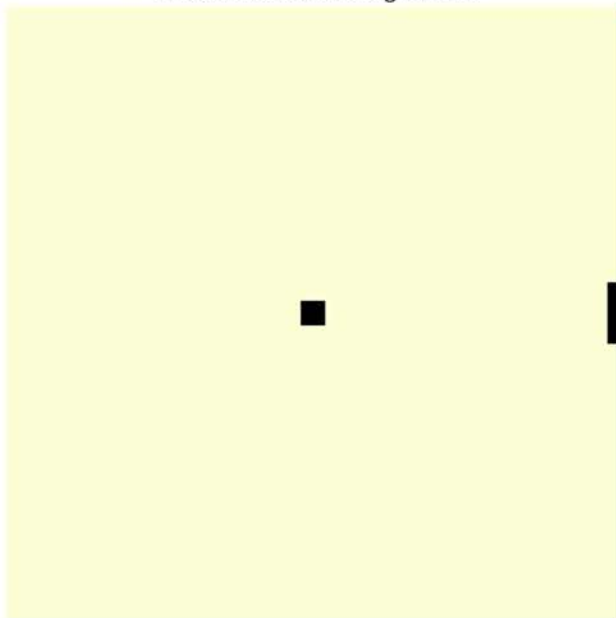
- Reinforcement learning by **reward-modulated** spike-timing-dependent plasticity
- R-STDP : three-factor learning rule that **modulates the effect of unsupervised STDP** using a reward signal
- Inspired by the activity of **dopamine** in the brain found to encode expected reward (e.g. Hollerman and Schultz, 1998)

$$\Delta w_{ij} = \beta \cdot (R - b) \cdot e_{ij}$$

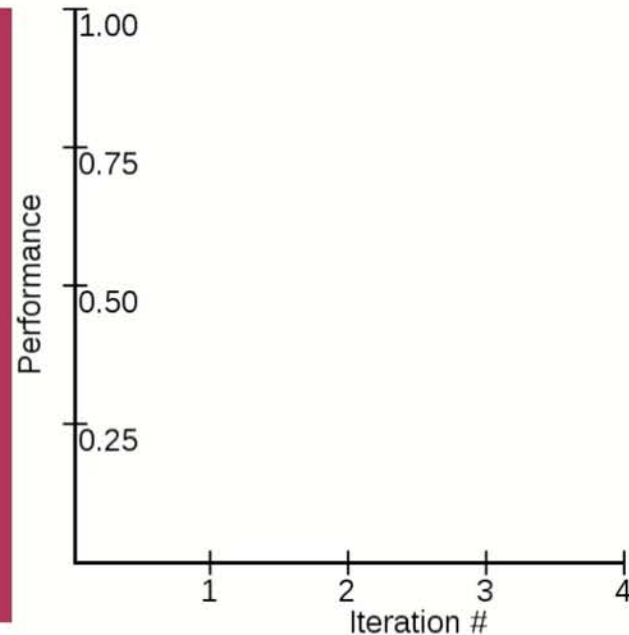
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Local Learning Demo on BrainScaleS 2

Environment & Firing Rates



Weight Matrix



Start

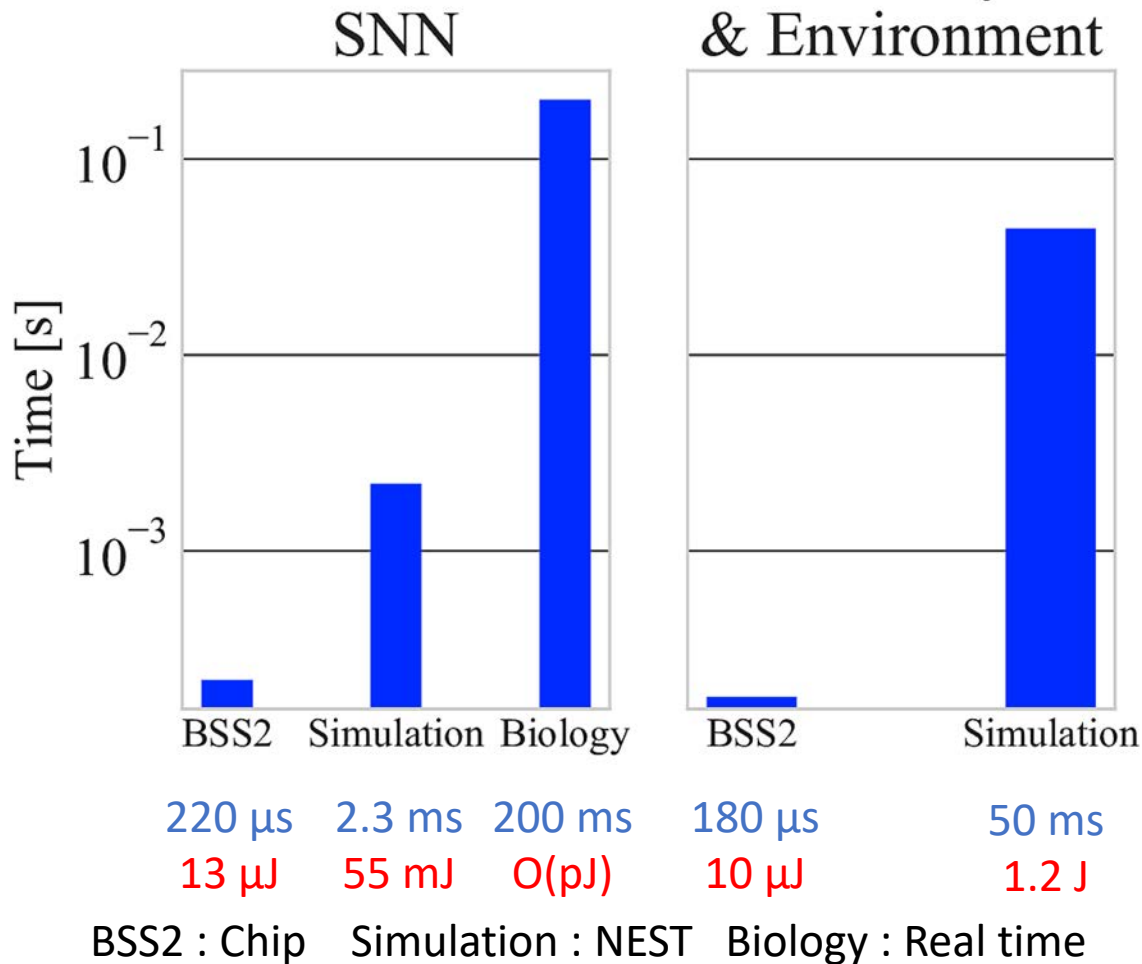
Reset

Slow-down factor: ☐ 2x ☐ 10x ☒ 100x

Elapsed Hardware Time: 0s

Plasticity & Environment

Speed and energy



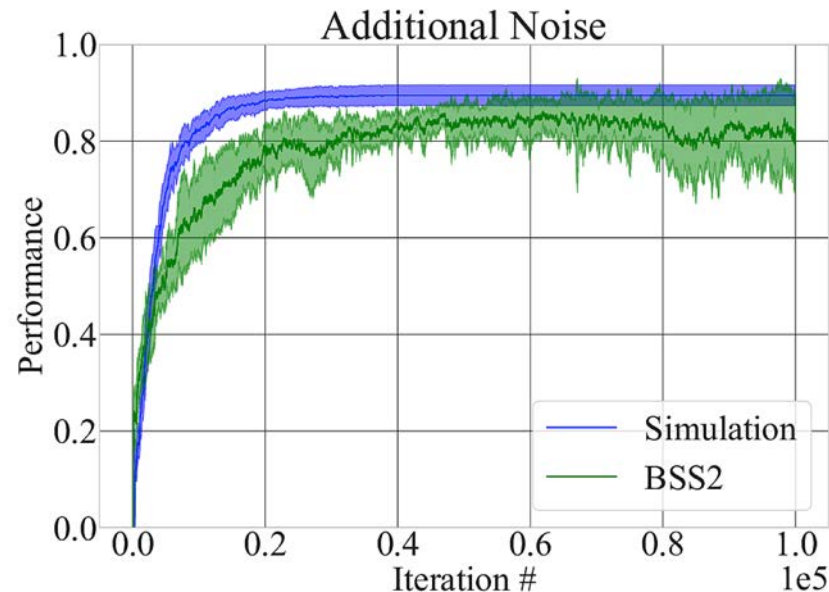
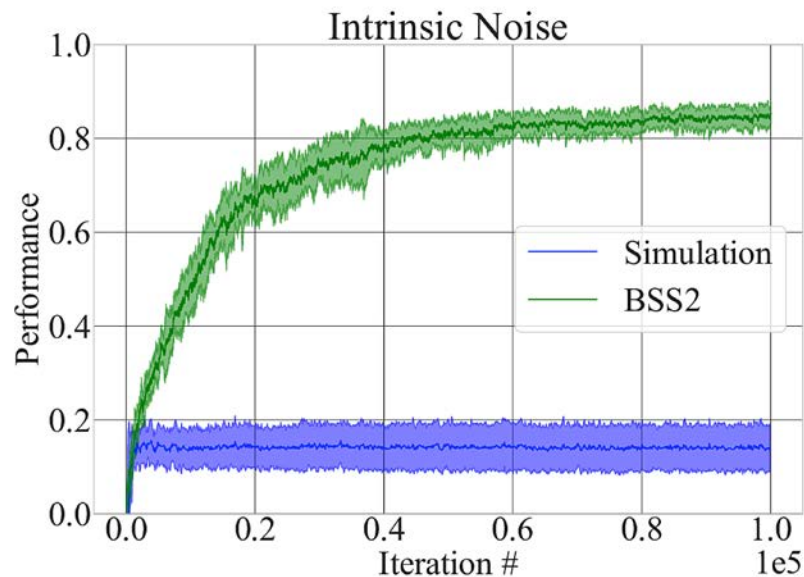
Times and energies for
single experiment
iterations

Energy measured
directly through
processor current

Simulation running on
one single core of an
Intel i7-4771 CPU

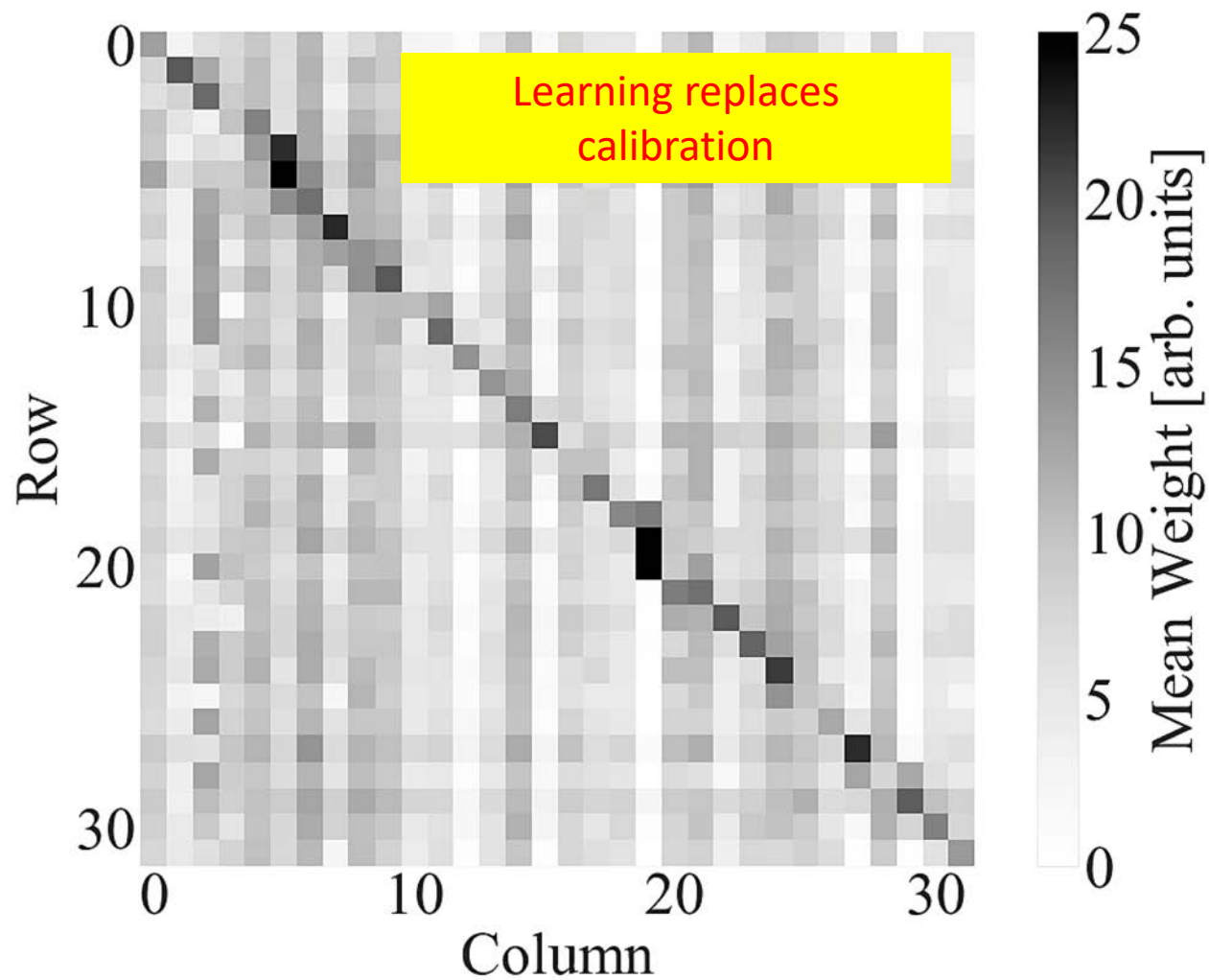
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Neuromorphic Engineering

Learning success in software (NEST) with and without artificial noise and hardware with intrinsic noise



Exploiting noise

Wunderlich et al., 2018, to be
submitted to Frontiers of
Neuromorphic Engineering



Weight matrix on chip
after 10^5 iterations

Variability after
learning represents
self-calibration

Learning replaces
calibration



BrainScaleS-2

Next generation neuromorphic computing

Hybrid architecture analog-custom digital-processor nased

Scalability



Two on-chip plasticity processors

Synaptic plasticity

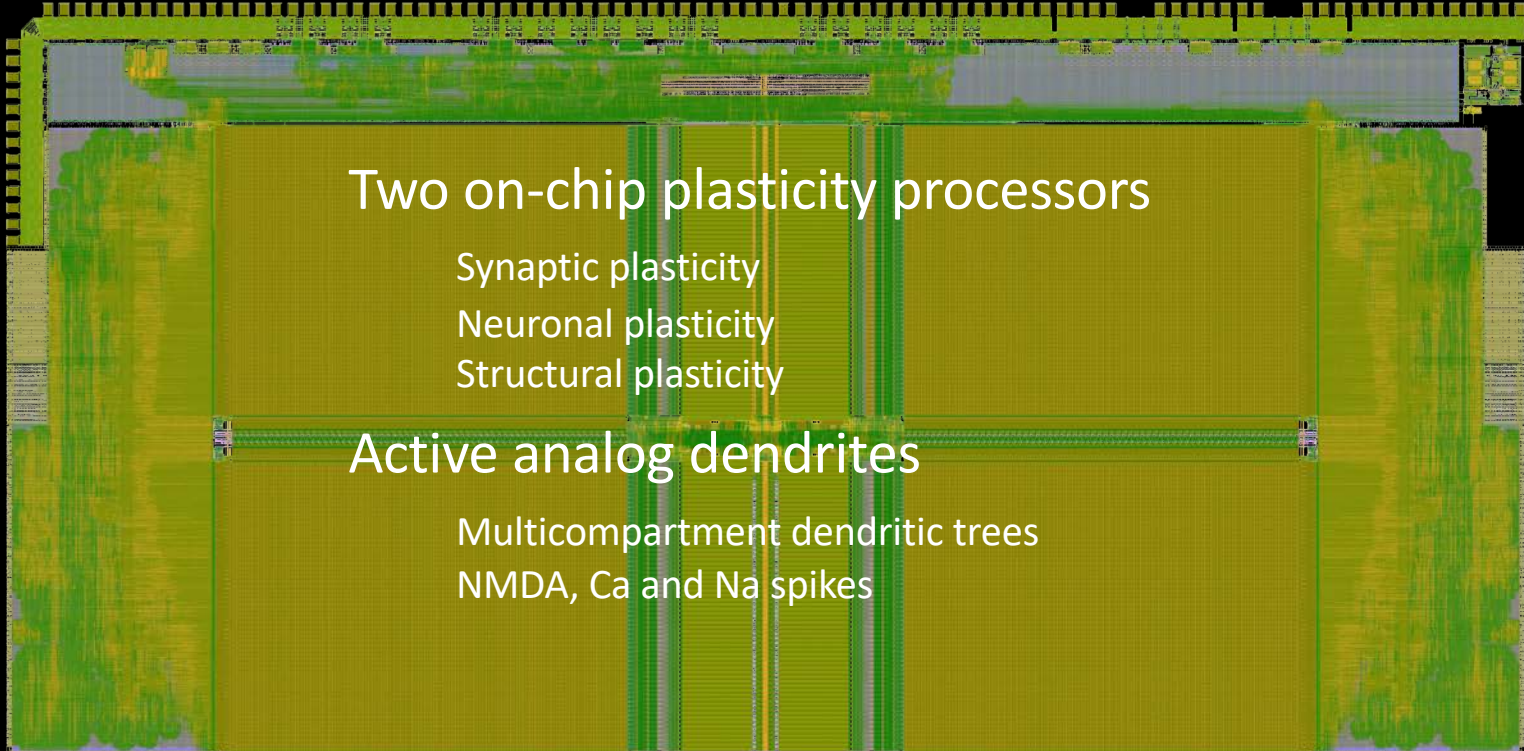
Neuronal plasticity

Structural plasticity

Active analog dendrites

Multicompartment dendritic trees

NMDA, Ca and Na spikes



Coffee machines ?

More general : Distributed sensing / IoT

IoT Challenges

- Energy consumption
- Size
- Data transfer
- Local preprocessing
- Adaptation

NMC technology

- Energy efficiency
- Compactness
- Local intelligence (learning)
- Adaptability

All enabled by biological principles

Concrete examples

- Personal medical devices (EEG, ECG, drug delivery, nerve stimulation, brain implants, sensory substitution)
- Intelligent adaptive control (engines, manufacturing plants)

Project evaluation under way with BASF, Huawei, Airbus, Daimler

Why do we need big HBP systems, then ?

- Rapid prototyping (like LTL, continuous learning, one-shot learning, dendritic computation)
- Neural FPGA concept